

1 **A benchtop Single-Sided magnet with NMR well-logging tool specifications – Examples** 2 **of application**

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13 14 **Abstract**

15 This article was written in honor of Prof. Bernhard Blümich, who has heavily impacted many
16 areas of Magnetic Resonance and, in particular, low-field and portable NMR with numerous
17 advances, concepts, innovations, and applications of this impressive technology. Many years
18 ago, we decided to research and develop single-sided magnets for the area of petroleum
19 science and engineering to study oil reservoir rocks in the laboratory under well-logging
20 conditions. The global urge to exploit oil reserves requires the analysis of reservoirs, intending
21 to characterize the yields before starting the production. Thus, well-logging tools have been
22 developed to estimate the quality of oil and reservoir productivity. NMR logging is included in
23 these analytical tools, and numerous operations using this kind of device were performed since
24 the early 1950s. To contribute to this vital research area, we show the development of a new
25 benchtop single-sided NMR system, with well-logging tool characteristics, a cylindrical sweet
26 spot with 4 cm of diameter and length, with magnetic field of 47 mT centered at 11 cm from the
27 magnet's surface and a linear gradient of 35.7 G/cm along z. This system was used in self-
28 diffusion, T₁-T₂, and D-T₂ measurements of standard liquids and rock cores, demonstrating its
29 functionality.

30 **Keywords:** Single-sided magnet, NMR well-logging, deep sweet spot, NMR porous media.

31 **Introduction**

32 Fossil-based fuels and petrochemicals are still essential for the global economy. Due to the
33 high demand for fossil fuels, the number of operations dedicated to finding and exploiting
34 petroleum reserves onshore and offshore has grown intensely in recent years. That creates the
35 need for exploring reservoirs in challenging environments such as deep water, or
36 unconventional resources like shale oil and gas, to serve global demand.¹ Therefore, existing
37 physical methods are being improved, and new ones developed to find new oil reservoirs and
38 enhance their production. One of the most important and traditional physical methods employed
39 for the analysis of oil embedded rock formations is Nuclear Magnetic Resonance (NMR), which
40 is used in laboratory research and well-logging operations.^{2,3}

41 Throughout the years, NMR tools have been used to assist the estimations of reservoirs
42 porosity, permeability and fluid typing. Nowadays, an effort is being made to increase the
43 accuracy of NMR Logging While Drilling (LWD) acquisition,⁴ where the rotation of the tool
44 following the drill bit imposes the necessity of understanding the acquisition under a somewhat
45 erratic motion. Our research groups are fully dedicated to developing new NMR methods and
46 instrumentation for both scenarios. In the case of NMR spectrometers employing traditional
47 magnets, several contributions were already given⁵⁻¹⁶. Currently, substantial efforts have been
48 dedicated to developing single-sided magnets, as well as NMR methods and studies under
49 simulated reservoir conditions.

50 NMR well-logging was one of the first industrial NMR applications, starting in the 1950s. Since
51 then, it has continually evolved, reaching a prominent position among the most used techniques
52 for profiling oil reservoirs, making it an indispensable tool for the petroleum industry.¹⁷ New
53 magnets used for NMR well-logging are continuously designed to generate a relatively strong
54 magnetic field inside the rock formations, having a specific profile within a so-called “sweet
55 spot” volume. That is why this class of magnets was called “single-sided” or “inside-out”.¹⁸
56 Complementarily, appropriate radio-frequency (rf) surface coils are also designed for use with
57 the single-sided magnets to excite and detect nuclear spins at the sweet-spot. Using these
58 distinctive magnets and rf coils, it is possible, for example, to study liquids confined in an oil
59 reservoir rock and estimate the permeability.³ However, such single-sided NMR sensors are
60 not limited only to the oil industry, and several other applications have already been
61 proposed.¹⁹⁻²²

62 The term inside-out NMR was coined early in the well logging prospection literature,²³ and
63 different designs of well logging tools have been since proposed.¹⁷ Well logging tools from
64 different oil companies have different designs, e.g., NUMAR/Halliburton's well logging NMR
65 tool MRIL (Magnetic Resonance Imaging Logging-Prime) and Schlumberger's tool PNMT
66 (Pulse Nuclear Magnetism Tool).^{24,25} The former measures cylindrical shells to the borehole,
67 with ¹H frequencies between 580 kHz to 760 kHz, depending on the depth, with a magnetic
68 field gradient of 25 G/cm, while the latter measures a localized volume in the rock formation,
69 with a ¹H frequency of about 2 MHz.^{25,26} Additional considerations, such as the temperature of
70 operation, usually much higher than room temperature, are taken into account for the choice of
71 the magnetic materials.

72 A large variety of small transportable single-sided systems have been developed.²⁷⁻³⁰ These
73 systems can have magnetic fields parallel,²⁷ or perpendicular²⁸⁻³⁰ to the magnet surface, and
74 produce either homogeneous magnetic fields, or magnetic field gradients inside the sweet spot.

75 Generating purely linear gradients over large regions of space is interesting both for imaging
76 and diffusion measurements, but it proves to be impossible at low magnetic fields because of
77 the presence of concomitant gradient components. However, theoretical analysis using
78 spherical harmonics demonstrates that it is possible to make homogeneous magnetic fields on
79 the XY plane located at a certain distance from the magnet while having a homogeneous
80 gradient on the Z-axis. This methodology has already been successfully applied to design a
81 single-sided system capable of generating a sweet spot with a 0.3 T magnetic field and a 340
82 G/cm magnetic field gradient, at 2 cm from the surface of the magnet.^{28,31} This system was
83 used to measure self-diffusion in thin samples and to perform multimodal experiments with a
84 Small Angle Neutron Scattering (SANS).³²⁻³⁴ Using the same principles, a new single-sided
85 system was designed and built, presenting magnetic field specifications appropriate for well-
86 logging applications, including a sizeable sweet spot located at a considerable distance from
87 the magnet surface.

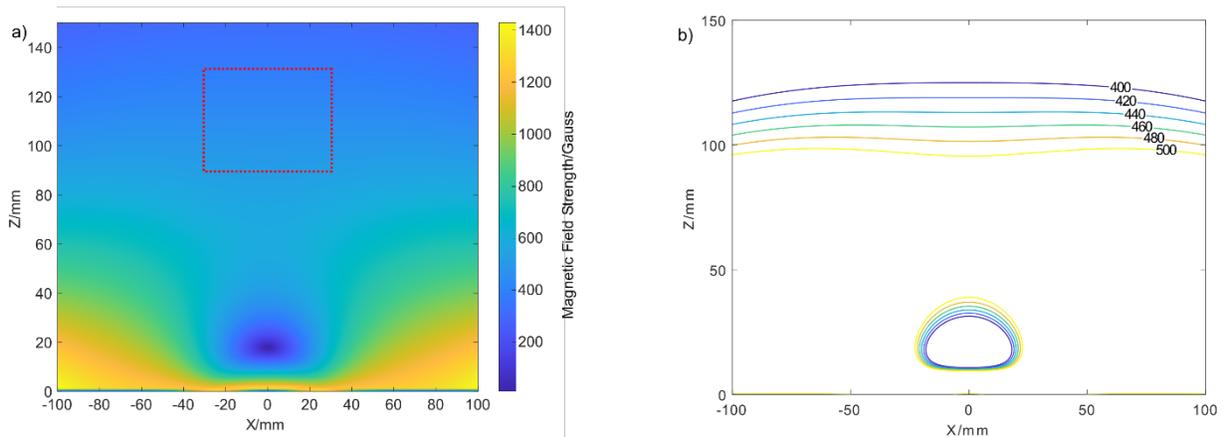
88 This paper presents the developments of this novel single-sided NMR system having well-
89 logging tool specifications and the first NMR experiments performed with water-embedded
90 porous media, including distribution of transverse relaxation times (T_2) and diffusion coefficients
91 (D), as well as two-dimensional correlation maps $D \times T_2$ and $T_1 \times T_2$.

92

93 Experimental

94 **Magnet Development**

95 The target specifications for the built single-sided magnet were 470 G in magnetic field strength
96 and 30 G/cm constant gradient over a 36 mm diameter spherical volume located at a significant
97 distance (>10 cm) from its surface. The magnetic field direction has been specified to be
98 perpendicular to the magnet's surface in order to generate the sweet spot at a greater distance
99 from its surface. As suggested in many literature references^{30,31,35,36}, a cylindrical geometry was
100 chosen, generating a cylindrically shaped sweet-spot, see Figure 1, and the Spherical
101 Harmonic Decomposition theoretical framework was employed for the calculations^{28,31}. The
102 dimensions of the magnet (thickness, inner and outer diameter) were optimized using analytical
103 formulas to achieve the required specifications. Because of the flat shape of the magnet, these
104 numerical results were further optimized using a 3D finite element software (Radia) where the
105 effects of demagnetization were properly accounted for (using the susceptibility properties of
106 the material) and the dimensions were slightly corrected before fabrication. Since the magnet's
107 operation would take place in the laboratory at room temperatures, NdFeB magnetic material
108 (grade N48SH) was purchased (The RE Magnet Studio Ltd.), instead of SmCo, which is
109 typically used in well logging NMR sensors.



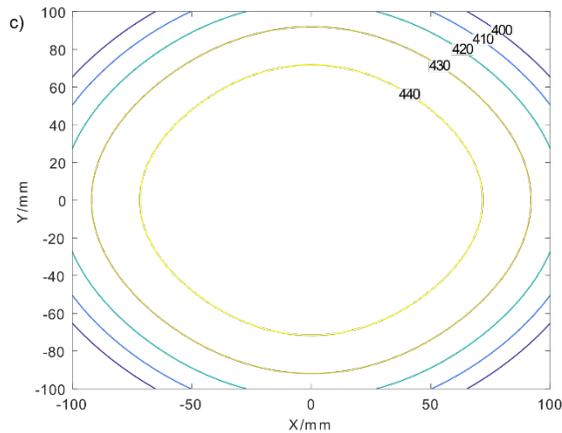


Figure 1 – Magnetic field design characteristics. In a) the simulated magnetic field map in the XZ plane is shown. The red dashed line rectangle corresponds to a cross section of the cylindrical sweet spot volume. Figure b) contour lines in the same region are highlighting the intensity of the magnetic field between 400 and 500 Gauss. c) Surface plot of the magnetic field strength in the XY plane calculated at the sweet spot location 11 cm from the surface of the magnet.

110

111 The pieces were glued inside a disk-shaped aluminum frame, as shown in Figure 2(a). The
 112 magnet's height and diameter were 45 mm and 374 mm, respectively. Because of its large size
 113 (~40 kg in weight), mounting magnetized pieces would represent a hazard and would not
 114 guarantee uniformity of magnetization. For this reason, the entire assembly was magnetized
 115 after mounting and gluing it in a non-magnetized state. The magnetization took place at the
 116 LNCMI facility (Grenoble / France). After magnetization, its magnetic field was roughly mapped
 117 using a SENIS 3MH3-20T 3-axis Hall probe. The resolution of this probe (10G) does not allow
 118 very precise magnetic field measurements but it allows a quick assessment of the magnetic
 119 field profile of the magnet. The measured magnetic field orientation was perpendicular to its
 120 surface, and its magnitude along the Z-axis is plotted in Figure 2b. The field on-axis shows a
 121 flat maximum (having some homogeneity) at 70 mm from the surface and then decays mainly
 122 linearly along the Z-axis. The constant gradient sweet spot's location lies 11 cm from its surface,
 123 where the nominal field magnitude is (470 ± 10) G and the measured gradient (33 ± 5) G/cm.
 124 At this vertical position, mapping the magnitude of the field in the XY-plane, as shown in Figure
 125 2c, demonstrates the excellent field uniformity over at least 50 mm in diameter.

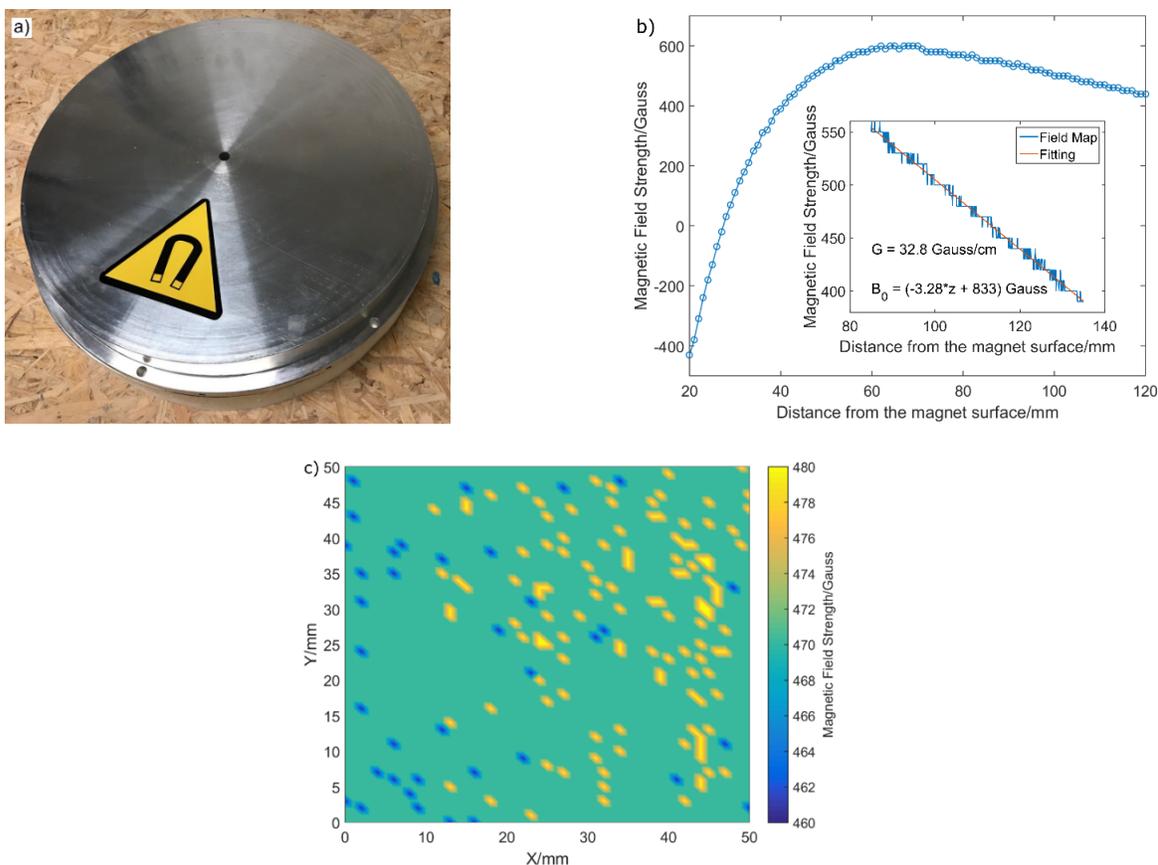


Figure 2 – Single-sided benchtop well-logging magnet. (a) Photograph of the permanent magnet assembly (total dimensions: 40 cm diameter, 5.5 cm height, 40 kg weight). (b) Magnetic field profile along the z-axis (perpendicular to the surface of the magnet), measured using a Hall probe. The magnetic field intensity at the sweet spot (11 cm) is (470 ± 10) G and magnetic field gradient (33 ± 5) G/cm. (c) Magnetic field profile in the XY-plane (parallel to the surface of the magnet), measured using a Hall probe at the location of the sweet spot.

126 **Probes**

127 Two NMR probes were designed and constructed for the measurements using the single-sided
 128 magnet, both operating at 2 MHz (^1H Larmor frequency), the respective coils are shown in the
 129 Figure 3. The first one has a solenoid coil with 26 turns, a diameter of 48 mm, and a length of
 130 53 mm, which can accommodate cylindrical samples with a maximum diameter of 44 mm. Its
 131 purpose is testing the sensitivity over a specific region by using a homogeneous B_1 field. The
 132 second one has an eight-shaped planar surface coil, to attain a sensitive region outside the
 133 probe, which will not limit the shape of the sample to be studied. The planar eight-shape coil
 134 expands over an area 180 mm long and 80 mm wide.

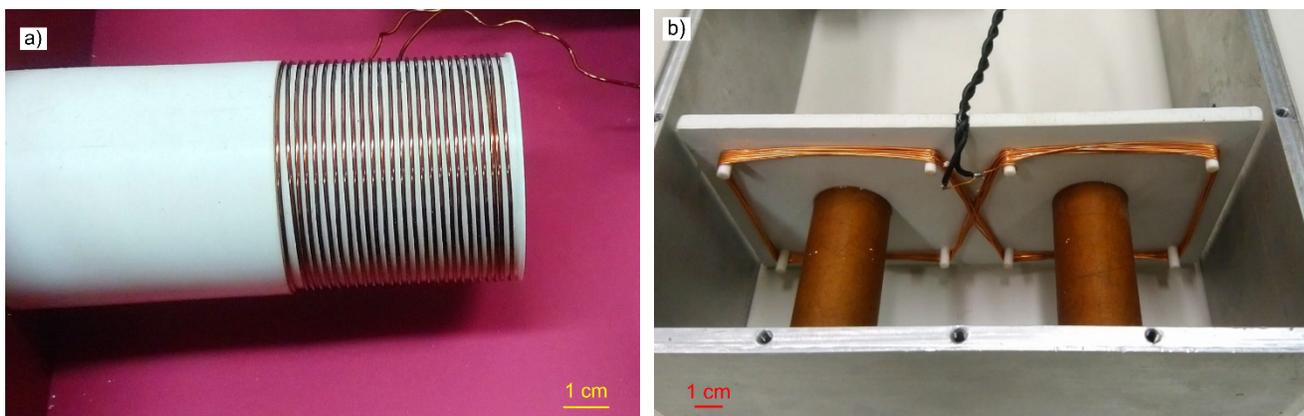


Figure 3 – Coils used for the measurements. a) Solenoid coil with 26 turns, 53 mm of length and 48 mm of diameter and b) eight-shape coil mounted under a PVC support, with 9 turns and dimensions 180 mm in length and depth of 80 mm. The sample is placed at the region above the support to be measured.

135 Both probes have the same rf circuit topologies, a simple conventional dual capacitor in
 136 association with the sample coil.³⁷ A parallel capacitor with the sample coil adjusts the
 137 resonance frequency, and a series capacitor adjusts the 50-ohm matching. Both solenoidal and
 138 surface coils were designed to have low quality factors Q of 12 and 22, respectively, to reduce
 139 the ringing time and enable shorter rf hard-pulses, which is desirable because of the intense
 140 magnetic field gradient. The simulated and measured sensitivity of the solenoidal probe are
 141 4.7 G/Amp and 4.6 G/Amp, respectively. Table 1 summarizes the sensitivity of the eight-shaped
 142 planar coil for different distances from its surface.

143 Table 1 – Simulated and measured sensitivities of the eight-shaped planar coil for different distances from its
 144 surface.

Distance (mm)	Simulated Sensitivity (G/Amp)	Measured Sensitivity (G/Amp)
5	7.6	--
10	3.6	3.5
20	1.6	1.6
30	0.8	0.9

145 The probe coils were made by winding enameled copper wire around rigid PVC mechanical
 146 supports. Variable non-magnetic Polyflon capacitors (5-125 pF, 6 kV) were used for tuning and
 147 an association of fixed value porcelain ATC capacitors (model 100E) for matching. The Q
 148 damping was provided with the association of a non-inductive, non-magnetic, power Vishay
 149 resistor. Both probes were assembled inside aluminum boxes with 4 mm thick walls to provide
 150 electromagnetic shielding and mechanical stability.

151 **Samples**

152 For the evaluation of the single-sided system, different samples were used. Self-diffusion
 153 experiments were performed with bulk water, methanol, ethanol, and acetone. T₁-T₂

154 experiments were performed with Berea and Indiana rock cores 38 mm in diameter and length,
155 and also with bulk water and mineral oil samples placed in the same sample holder but
156 separated in different tubes. D-T₂ experiments were also performed with the two rock cores.

157 ***NMR Experiments***

158 A Tecmag NMR console (LapNMR) in association with a Tomco rf power amplifier (BT00500-
159 AlphaS) were used to perform the single-sided NMR experiments. The widths for the 90°
160 excitation pulses were 7 μs and 9 μs, for the solenoid and eight-shape coil probes, respectively.
161 Furthermore, the 180° pulse length was set to twice those values. The temperatures of the
162 magnet, probes and samples were kept constant at (25.0 ± 0.1)°C during the experiments.

163 For the solenoid coil, with a diameter of 48 mm, despite providing good B₁ field homogeneity,
164 there is a B₀ variation of 144 G along its diameter and, consequently, a Larmor frequency
165 distribution of about 600 kHz along the z-axis, due to the magnetic field gradient of ~33 G/cm.
166 The 90° and 180° rf pulses are however selective due to their durations of 7 μs and 14 μs,
167 resulting in excitation bandwidths of approximately 140 kHz and 70 kHz, respectively. A
168 bandwidth of 70 kHz corresponds to an excited slice of ~5 mm.

169 Similarly, for the eight-shaped coil, the B₀ gradient determines that only part of the sample will
170 be excited. However, in addition to the B₀ gradient, the B₁ magnetic field produced by this coil
171 has a non-uniform profile. That modifies further the shape of the excited region of the sample.
172 The losses in the S/N ratio due to the employed RF pulses' selectivity were compensated by
173 the number of averages of the experiments.

174 Self-diffusion, T₁-T₂, and D-T₂ were performed with the standard CPMG acquisition, with echo
175 time $2t_e = 200 \mu\text{s}$ (see Figure 4). Two dimensional T₁-T₂ relaxation time correlations³⁷ were
176 measured using the inversion recovery experiment, for the encoding of T₁ with 16 recovery
177 times t_1 logarithmically spaced from 100 μs to 10 s (Figure 4a). Additionally, 8000 echoes were
178 measured in the T₂ decay for the Indiana and the water/oil samples and 4000 echoes for the
179 Berea sample. The self-diffusion and D-T₂ experiments were performed according to the pulse
180 sequence presented in Figure 4b.^{38,39} Furthermore, for self-diffusion experiments performed
181 with the bulk liquids, the sum of the 100 first echoes was used to improve the signal to noise
182 ratio, since the T₁ relaxation times are on the order of seconds. For self-diffusion experiments
183 with rocks, the full decay was measured comprising 8000 echoes and 4000 echoes,
184 respectively, for the Indiana and Berea samples. The diffusion encoding times t_d ranged from

185 564 μs to 6 ms in 10 equidistant steps in t_d^3 domain. The number of averages are summarized
 186 in the
 187 Table 2.

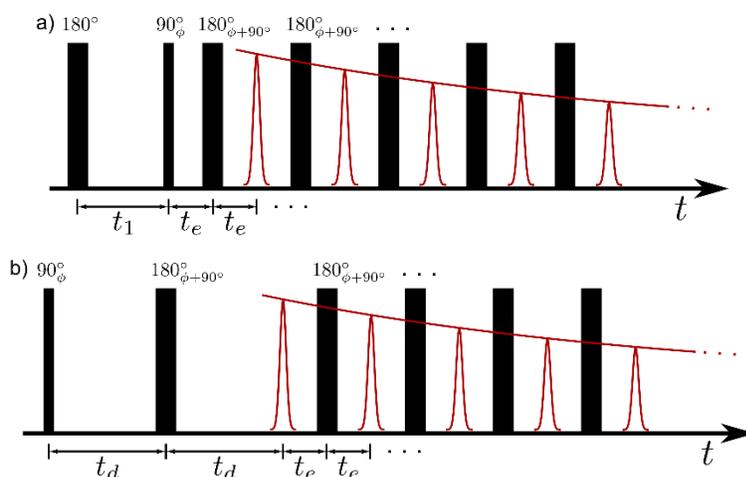


Figure 4 – (a) The T_1 - T_2 correlation experiment is performed by combining the IR and CPMG experiments. The T_1 modulated signal intensity (because of the different recovery time t_1 between the 180° and the 90° pulses) is measured with the CPMG sequence, consisting of a train of echoes separated by two times t_e .³⁷ (b) Similarly, the D- T_2 correlation experiment measures the T_2 relaxation while encoding the diffusion time's (t_d) effect on the signal intensity.^{38,39}

Table 2 – Number of averages of the performed experiments.

Sample	Self-Diffusion	D- T_2	T_1 - T_2
Berea	NA	128	128
Indiana	NA	128	128
H ₂ O + Oil	NA	NA	128
H ₂ O	16	NA	NA
Acetone	16	NA	NA
Methanol	32	NA	NA
Ethanol	16	NA	NA

NA = not applicable.

188 **Data processing**

189 In general, two-dimensional NMR sequences based on the relaxation process are formulated
190 with the aim of being represented by two independent *kernels*. Thus, the measured
191 magnetization $M(y_1, y_2)$ can be written as:³⁷⁻³⁹

$$M(y_1, y_2) = \iint dx_1 dx_2 f(x_1, x_2) k_1(x_1, y_1) k_2(x_2, y_2) + \epsilon(y_1, y_2) \quad (1)$$

192 where $f(x_1, x_2)$ is the distribution function of interest, and k_1 and k_2 are the kernels related to
193 the kind of experiment. Based on the sequences shown in Figure 4, the kernels are given by:

$$k_1^{T_1 T_2}(T_1, t_1) = 1 - 2 \exp\left(-\frac{t_1}{T_1}\right), \quad (2)$$

194

$$k_1^{DT_2}(D, 2t_d) = \exp\left(-\frac{2}{3}\gamma^2 G^2 D t_d^3\right) \exp\left(-\frac{2t_d}{T_2}\right), \quad (3)$$

195

$$k_2(T_2, Nt_e) = \exp\left(-\frac{Nt_e}{T_2}\right), \quad (4)$$

196 where k_2 is the same for all sequences, based on the standard CPMG with N echoes, γ is the
197 gyromagnetic factor, G is the gradient and D the self-diffusion coefficient. T_1 - T_2 kernel ($k_1^{T_1 T_2}$)
198 and formulation are the same used by Song *et al.*,³⁷ for the fast 2D Laplace Inversion transform
199 (2D – ILT) algorithm.³⁷ Thus, based on this algorithm, an Octave script was developed to
200 process T_1 - T_2 experiment data.

201 On the other hand, the kernel for the diffusion-editing proposed by Hürlimann *et al.*³⁸ rewrites
202 the kernel $k_1^{DT_2}$. The approach was made so that the fast 2D Laplace Inversion transform should
203 be applied. In this case, the algorithm was implemented, considering the $k_1^{DT_2}$ without
204 approximation, making data processing slower, which, for the purpose of this work, has no
205 implications.

206 The self-diffusion coefficients for the bulk-liquids were determined by the fitting with
207 exponential model according to equation (5):³²

$$I(2t_d) = I_0 \exp\left(-\frac{2t_d}{T_2^*} - \frac{2}{3}\gamma^2 G^2 t_d^3 D\right), \quad (5)$$

208 where $I(t)$ are the signal intensities corresponding to each of the t_d values. Thus, I_0 is the
 209 signal intensity for the initial t_d value, T_2^* corresponds to the transverse magnetization
 210 attenuation constant between the periods t_d (according to the Figure 4b), γ is the gyromagnetic
 211 factor, G is the gradient and D the self-diffusion coefficient to be determined by the fitting.

212

213 Results

214 To measure the magnetic field gradient at the sweet spot, five consecutive self-diffusion NMR
 215 experiments were performed for bulk-water at 25°C using the solenoid probe. The magnetic
 216 field gradient was estimated for each experiment according to the equation (5) to match the
 217 well-established self-diffusion coefficient of water at 25°C of $2.299 \times 10^{-5} \text{ cm}^2\text{s}^{-1}$.⁴⁰ Results are
 218 presented in Table 3.

Table 3 - Sweet spot magnetic field gradient estimated with the bulk water diffusion coefficient at 25°C.

Experiment number	1	2	3	4	5	Average
G (G/cm)	35.43	35.60	35.84	36.33	35.67	35.7 ± 0.3

219

220 The average magnetic field measured by NMR (Table 3) is (35.7 ± 0.3) G/cm, which is in the
 221 same range of that obtained by Hall probe. Table 4 summarizes the measured self-diffusion
 222 coefficients for four fluids at 25°C, including water, which are in accordance with the self-
 223 diffusion established in the literature,^{40,41} corroborating the value of the measured magnetic
 224 field gradient.

Table 4 – Self-diffusion coefficients measured using the single-sided magnetic field gradient. The self-diffusion experiments were repeated n times for each sample, and the standard deviation calculated.

Bulk liquid	n	D ($\times 10^{-5} \text{ cm}^2\text{s}^{-1}$)(Literature)	D ($\times 10^{-5} \text{ cm}^2\text{s}^{-1}$)(Measured)
Water	5	2.299	2.31 ± 0.04
Methanol	5	2.41	2.5 ± 0.2
Ethanol	4	1.07	1.1 ± 0.1
Acetone	2	4.57	4.5 ± 0.8

225

226 T_1 - T_2 correlation experiments were performed for water-saturated Berea sandstone and
 227 Indiana limestone rocks, as well as a phantom composed of two glass tubes containing,
 228 separately, a 5-mM aqueous copper sulfate solution and mineral oil. The experiments were
 229 carried out using the eight-shaped probe, with the sample on top of the platform and centered
 230 on the sweet spot. The corresponding T_1 - T_2 maps are presented in Figure 5. For the three
 231 samples, one can observe the tendency of the distributions to be parallel to the main diagonal
 232 (white dash-line where $T_1=T_2$).

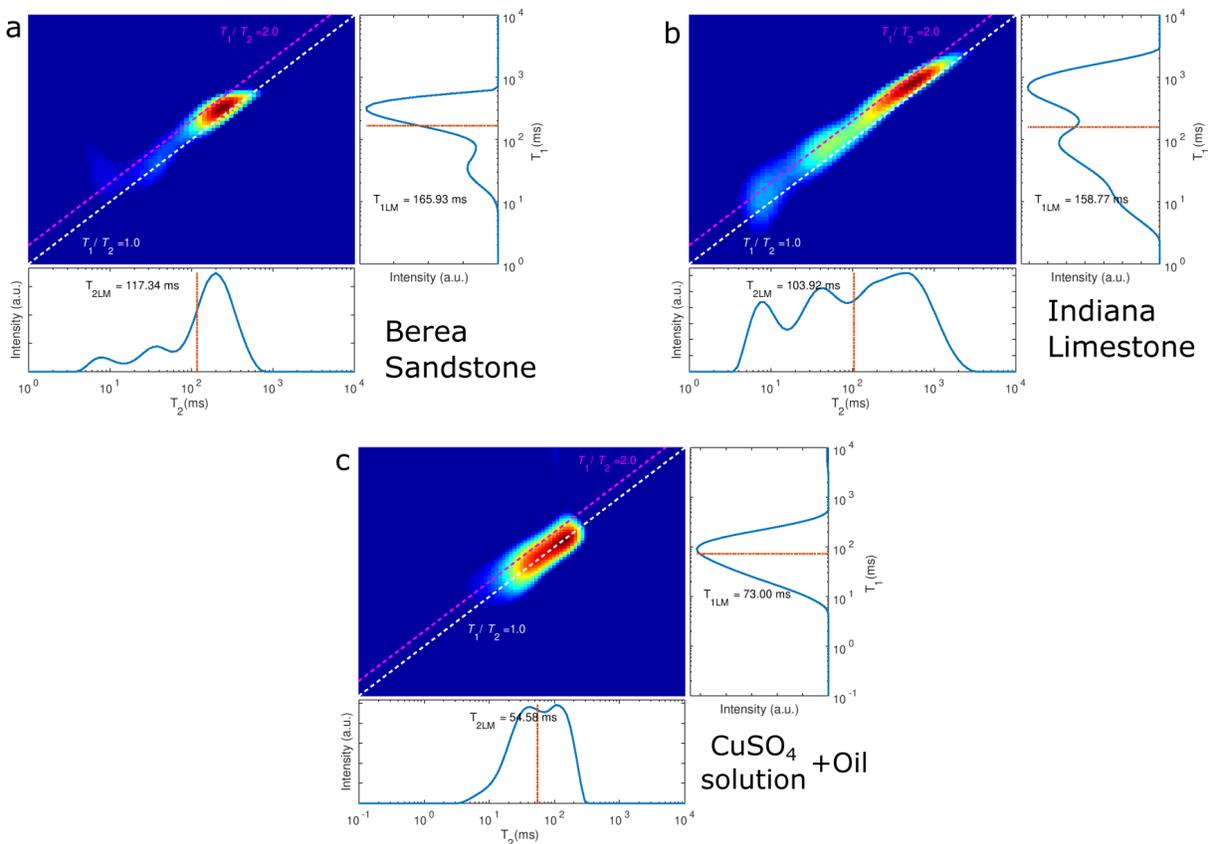


Figure 5 – T_1 - T_2 maps obtained on the single-sided magnet using the eight-shape probe for: a) Berea sandstone, b) Indiana limestone, and c) 5-mM aqueous CuSO_4 solution and mineral oil.

233

234 It is known that for water and light oil, the relaxation time T_2 tends to be close to T_1 , as observed
 235 in the T_1 - T_2 distribution, which shows the distribution overlapping the white dashed-line². In the
 236 case of the water saturating rocks, the fast diffusion regime ensures that the T_1 and T_2 are
 237 proportional to the pore sizes.^{42,43}

238 Recently, Lucas-Oliveira *et al.*⁶ evaluated 14 sandstones, including the same Berea sandstone
 239 used in this work. On that work, they measured the relaxation time in a conventional 0.047 T

240 magnet, which presented the same shape shown in Figure 5a, and, for both cases, the longest
 241 T_2 are ~ 200 ms. Additionally, the parallel behaviour obtained by the T_1 - T_2 maps results shown
 242 here, indicates that the surface relaxivity, estimated by Lucas-Oliveira *et al.*, could be
 243 considered uniform for all the pores, presenting the same interactions between the water and
 244 pore surfaces. Indiana limestone showed similar behaviour and a wide T_2 distribution, which
 245 indicates a wide pore size distribution as well.

246 D- T_2 experiments were performed for both Berea and Indiana samples with the solenoid probe,
 247 results are shown in Figure 6. The T_2 projections are in the same range of the T_2 projections
 248 shown in Figure 5. In this case, the diffusion coefficient is related to the restriction imposed by
 249 the pore structure, which is directly related to the size and connectivity of the pores.^{44,45} Given
 250 that, the water diffusion coefficient for water saturated Berea and Indiana Limestone showed to
 251 be slightly smaller than the bulk water. Additionally, the T_2 distribution appears to be shifted to
 252 shorter times, especially for the Indiana limestone, which suggests a contribution from the
 253 magnet gradient on the relaxation. Hürlimann *et al.*³⁸ showed that the Diffusion-editing
 254 technique measures not the D- T_2 correlations, but D- $T_{2\text{eff}}$ correlation. That is because, in the
 255 off resonance nuclei, the measured relaxation time ($T_{2\text{eff}}$) is affected by a combination of T_2 and
 256 T_1 .

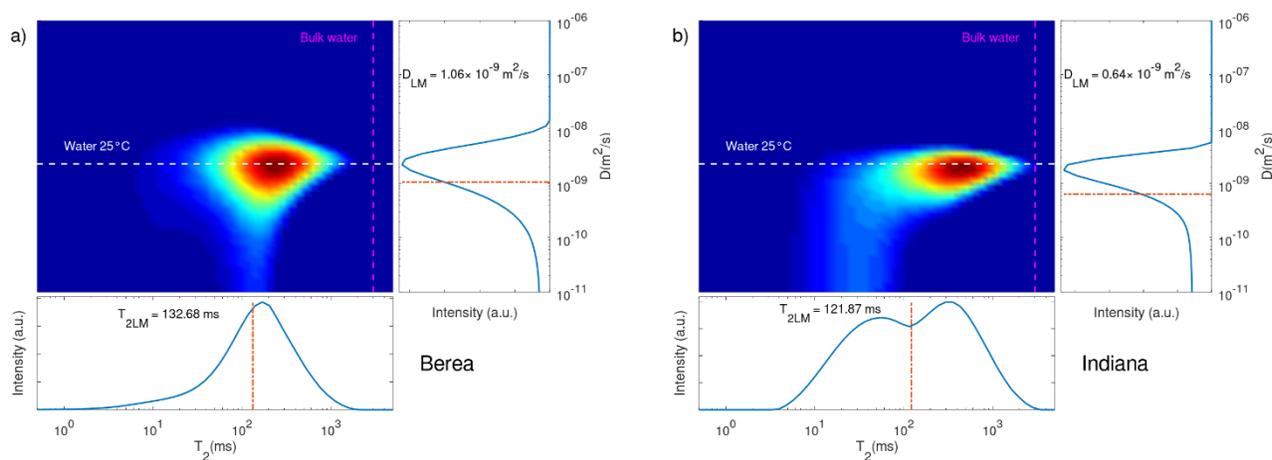


Figure 6 – D- T_2 2D distributions obtained for: a) Berea sandstone and b) Indiana limestone with the solenoid probe.

257

258 Conclusions

259 This work shows the first results obtained with a novel single-sided NMR sensor, designed with
 260 magnetic specifications similar to those used for well-logging tools. The characteristics of this
 261 new benchtop single-sided magnet are due to the design and manufacturing methods

262 proposed. The Hall probe field mapping showed that the desired sweet spot of 4 cm in diameter,
263 with central frequency of 2 MHz and a constant magnetic field gradient of (33 ± 5) G/cm, is
264 located 11 cm from the magnet surface. NMR also obtained similar parameters. With surface
265 and solenoid coils, experiments were performed to evaluate the magnet performance. Self-
266 diffusion experiments performed on bulk water at 25°C showed that the gradient in the sweet
267 spot is (35.7 ± 0.3) G/cm, which is in the same range of that obtained by Hall probe. This
268 gradient was used to measure the self-diffusion of other bulk liquids, and compare them to the
269 literature values.^{40,41} The D-T₂ correlation, measured on two standard rocks, presented broad
270 diffusion coefficients distributions, close to the bulk water diffusion values. T₁-T₂ correlation, as
271 expected for rocks and liquids in bulk, presented diagonal distributions, giving T₂ proportional
272 to T₁. Altogether, results show the system's reliability in the development of methods and the
273 study of fluids in porous materials to be applied in well logging applications, with the advantage
274 of being a lower cost and safer solution than stray field measurements from superconducting
275 magnets. In addition, this system is more flexible, enabling to emulate reservoir conditions in
276 the lab, such as controlled sample temperature and pressure, and even acquisitions with
277 relative motion between the sample and the magnet. This single-sided NMR equipment is
278 already being used for developing pulse sequences for well-logging applications, including high
279 pressure / temperature studies and measurements under logging while drilling (LWD)
280 conditions.⁴ Although this NMR equipment was originally built for applications in petroleum
281 science and engineering, it may also find uses in many other areas, such as in industry,
282 agriculture and medicine.

283

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