

1 Airflow Measurement Techniques for the Improvement of Forced-air Cooling, Refrigeration
2 and Drying Operations

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10
11 Abstract

12
13 Flowrate and distribution of air is a critical design factor in the cooling, refrigeration and
14 drying of horticultural food products. These operations rely on a constant supply of air
15 distributed throughout bulk arrangements of the produce. Local distribution of the air is
16 critical to optimizing the design and efficiency of these processes. Identification of the key
17 parameters affecting the airflow distribution has been done either experimentally (using
18 intrusive point-wise or bulk measurement techniques) or numerically. The detailed
19 information provided by the use of computational fluid dynamic models has facilitated
20 unique opportunities to investigate alternative system designs, without the need for expensive
21 and time consuming experiments. This study provides a review of the techniques available to
22 measure airflow (thermal and rotatory vane anemometry, pressure differential devices, tracer
23 gases, LDA and PIV). Their advantages and disadvantages (accuracy, resolution, application
24 range, cost, and ease of use) as well as their application in the validation of numerical models
25 are reviewed. The novel and scientifically based design guidelines developed by a better
26 understanding of the airflow behaviour within the system for each of the operations under
27 study are also presented.

28

29 *Keywords:* numerical model validation; experimental; laser doppler anemometry; particle
30 image velocimetry; thermal anemometry; flow visualisation.

31

32 1. Introduction

33

34 Common cooling and drying operations of food are typically based on the heat exchange
35 between a food product and a constant supply of airflow through the system (Ghisalberti and
36 Kondjoyan, 1999). For the cooling, refrigeration and drying of food the flowrate, distribution
37 and temperature of the airflow throughout the entire packaging structure ultimately
38 determines the rate, uniformity and efficiency of these processes. As uniform temperatures
39 are desired in all three operations any operating and/or design feature capable of affecting the
40 local distribution of the airflow behaviour within the system will have a profound effect on
41 the performance of these processes.

42

43 In forced-air cooling, the size and location of the openings of the ventilated packages have
44 been found to have a particular effect on the rate and uniformity of the process (Defraeye et
45 al., 2013; Defraeye et al., 2014; Delele et al., 2008; Ferrua and Singh, 2009a; van der Sman,
46 2002; Vigneault et al., 2006). Ventilated packaging should be designed to provide uniform
47 airflow distribution. However, uniform cooling does not always go hand in hand with higher
48 cooling rates, and package design is a determining factor (Defraeye et al., 2014). The vents or
49 openings determine how much air can come in contact with the product, how it is distributed
50 inside the package, and what the air velocity magnitude is. Hence, cooling heterogeneity
51 within packages is often a result of uneven airflow distribution (Dehghannya et al., 2008;

52 2011; 2012). A comprehensive review by Pathare et al. (2012) gives the recommended vent
53 areas for a wide range of ventilated packages for horticultural produce.

54

55 In refrigerated rooms pallet stacking patterns can result in an uneven airflow distribution.
56 When pallets are stacked high and closely packed together those centrally located and at the
57 rear of the room (away from the evaporator fans) will receive smaller volumetric flows of
58 refrigerated air compared to the pallets at the front of the room (adjacent to the evaporator
59 fans). These local differences in flowrate throughout the room cause differences in the air
60 temperature, with warm spots developing depending on pallet location (Verboven et al.,
61 2003). Similarly, for refrigerated transport vehicles, pallet compactness can lead to high
62 airflow resistances and uneven airflow distribution, with the formation of stagnant zones with
63 higher air temperatures in the rear of the vehicle (Smale et al., 2006).

64

65 Typically, in forced-convection drying, warm, dry air exits an inlet and is distributed under a
66 bed of horticultural produce. This air tends to follow a streamline flow and if not redirected
67 will be distributed along the centre and towards the back of system, with regions not in the
68 main pathway receiving smaller volumetric airflows, resulting in a non-uniform final
69 moisture content (Nagle et al., 2010). When using impinging hot air jets for drying, the
70 location and direction of the jet can affect the rates of heat and mass transfer spatially along
71 the product width, as a higher percentage of the airflow is directed to one section of the
72 product (Marcroft et al., 1999).

73

74 To improve the performance of these food operations a detailed understanding of how
75 different design parameters and operating conditions affect the airflow behaviour within the
76 systems is essential. This information has been traditionally obtained by measuring the local

77 distribution of the airflow within the system using a wide range of experimental techniques.
78 In addition, experimental information collected on the behaviour of the airflow has been also
79 recently used for the validation of numerical models of the process (Smale et al., 2006).
80 Beginning in the 1990s engineering simulation tools, such as Computational Fluid Dynamics
81 (CFD), have become increasingly used in the analysis of cooling and drying processes within
82 the food industry. Relevant examples are given in Wang et al. (2003). Advanced CFD tools
83 can predict complex airflow patterns in food operation systems in a level of detail difficult to
84 achieve experimentally, facilitating a better and more fundamental understanding of the effect
85 of the design and operating conditions on the efficiency of the process.

86

87 This study reviews not only the airflow measurement techniques currently employed to
88 characterise airflow behaviour in forced-air cooling, refrigerated and drying applications but
89 also their application in developing a better understanding and design of these processes.

90

91 2. Airflow measurement techniques

92

93 2.1 Direct airflow measurement

94

95 Direct flow measurement techniques are generally devices placed in the flow field which
96 measure point-values in a system. They are widely used due to their robustness, ease of use
97 and competitive price compared to non-invasive image analysis. These techniques include
98 thermal anemometry, vane anemometry and differential pressure flowmeters.

100 2.1.1 Thermal anemometers

101

102 Thermal anemometers consist of a small, electronically heated sensor, initially kept at a
103 constant temperature above that of the fluid flow temperature. Once the sensor is placed in
104 the flow field it experiences a certain amount of cooling. As the electrical resistance of the
105 sensor is dependent upon its temperature, a relationship can be obtained between the flow
106 speed and the voltage output from the sensor.

107

108 Thermal anemometers can be operated to maintain a constant temperature or constant current
109 through the sensor. In the case of constant temperature anemometers, the sensor's resistance
110 is constant and the required voltage (or current) to maintain the temperature is measured.

111 Conversely, for constant current anemometers the applied current is held constant and the
112 sensor's voltage drop (or electrical resistance) is measured (Fingerson and Freymuth, 1996).

113 The air velocity can then be inferred from the power required to maintain the temperature or
114 current of the sensor. The sensor placed in the fluid flow is a wire for hot-wire anemometers
115 and a film in the case of hot-film anemometers.

116

117 Thermal anemometers can be made at a relatively low cost and when thin wires are used a
118 high sampling frequency can be used (up to 10^5 Hz). Limitations of thermal anemometers
119 include the requirement for regular calibration, which often involves the device being sent
120 back to the manufacturer once a year. The recorded velocities may be affected by impurities
121 in the fluid that adhere to the wire, interfering with the heat transfer. Thin hot wire systems
122 while very sensitive and accurate are very fragile and need to be combined with a portable

123 support, positioning system, a probe calibrator, A/D converter, thermal anemometry software
124 and a computer. Such systems can become quite expensive. For use in more industrial
125 relevant environments, more robust (thicker hot wires) and compact solutions can be used.
126 However, these hot wire/film anemometers are unsuitable when attempting to measure very
127 high or low air velocities. At low air velocities (i.e. below 0.1 m.s^{-1}) natural convection can
128 become prevalent and as a result heat transfer is no longer solely dominated by forced
129 convection (Page et al., 2009).

130 Alternatively, at high air velocities (i.e. above 100 m.s^{-1}) the heat from the sensor tends to
131 dissipate extremely quickly, reducing its sensitivity to changes in the velocity field (Jing et
132 al., 2011).

133

134 The ability of hot-wire anemometers to capture turbulent high-frequency velocity fluctuations
135 is limited by the sensor size. Depending on the level of turbulence the fluctuating components
136 of the air velocity can have a broad frequency spectrum, from as low as 10^{-2} Hz to in excess
137 of 10^5 Hz (Webster, 2000). Robust hot wire systems (diameter between $0.5 - 1.0 \text{ mm}$) are
138 unable to capture these high frequency velocity variations, however, the fluctuations do
139 increase the heat transfer between the sensor and the air, causing the average velocity to be
140 overestimated. To compensate for this a sensor with an extremely small diameter ($\sim 5 \mu\text{m}$)
141 and electronics that can account for the fluctuating frequencies and allow for a flat frequency
142 response between $0 - 10^4 \text{ Hz}$ must be employed (Webster, 2000).

143

144 When the turbulent velocity fluctuation is more than 30 % of the average velocity the probe
145 must be moved through the flow field at a speed high enough to compensate for sudden drops
146 in the air velocities as a result of turbulence, a technique known as “flying hot-wire system”

147 (Jorgensen, 2002). This requires sufficient open space for the hot-wire anemometer, which is
148 usually not found in food processing operations.

149

150 For accurate measurements the airflow direction must be known before the experiment is
151 started and the sensor wire mounted perpendicular to the flow, unless otherwise stated by the
152 manufacture (Jorgenson, 2002). In the case of 2D and 3D flows, multisensory hot-wire
153 probes are used to measure the different components of the velocity field. Spherical hot wire
154 probes that can measure the air speeds, while being insensitive to the airflow direction also
155 exist (Lomas, 1986).

156

157 Despite the small diameter of the sensor the probe itself often has a length in excess of 0.5 m.
158 This can create problems when investigating the airflow conditions within confined spaces
159 such as in between horticultural packages stacked in a pallet, as the introduction of a thermal
160 anemometer may change the airflow conditions within them (Alvarez and Flick, 1999a).

161

162 Examples of hot-wire anemometry for measuring airflow measurements in food operations
163 include: Alvarez and Flick, 1999a; Amanlou and Zomordian, 2011; Delele et al., 2008;
164 2009a; 2009b; Janjai et al., 2006; Kashaninejad et al., 2010; Ngcobo et al., 2013; Santonico et
165 al., 2010; Verboven et al., 2005.

166

167 2.1.2 Vane anemometry

168

169 Vane anemometers measure the average velocity of the airflow of a particular region within a
170 system. A vane anemometer operates on the principle that when fluid flow hits the vanes it
171 causes them to rotate. The higher the flow speed the faster the rotation. This rotational speed

172 is sensed by an optical or magnetic sensor and the signal is converted to a velocity
173 measurement.

174

175 The simplicity of vane anemometers has resulted in the manufacturing of hand held devices,
176 which are advantageous if a portable measurement device is required. The accuracy of the
177 anemometer is heavily dependent on the vane angle with respect to the airflow direction,
178 which must be precisely known before any velocity measurements can be taken (Mirade,
179 1998). Additionally, there is a minimal threshold velocity required to cause initial rotation of
180 the vanes.

181

182 The relatively bulky size of vane anemometers renders them as an unsuitable selection for use
183 within small void spaces (e.g. horticultural produce packaging), but is a viable method for
184 measuring the airflow in larger spaces such as before or after it encounters horticultural
185 produce.

186

187 Examples of vane anemometry for measuring airflow measurements in food measurements
188 include: Hossain and Bala, 2007; Lawrence and Maier, 2011; Kadam et al., 2008; Motevali,
189 2013; Nagle et al., 2010.

190

191 2.1.3 Differential pressure flowmeters

192

193 Differential pressure flow meters determine the flow velocity by either measuring the
194 pressure losses over obstructions of known dimensions, such as orifice plates and Venturi
195 meters, or by calculating the different pressure components (Coulson et al., 1999).

196

197 The devices used to record pressure differences can be classified into U-tube manometers and
198 pressure transducers. U-tube manometers are simple to construct. However, they are not
199 suitable when it comes to measuring very low flow rates and cannot be used in unsteady-state
200 systems. In the case of very low rates the accuracy of the small pressure differences to be
201 evaluated could be compromised. If the system is in transient operation the pressure
202 difference, measured by the height difference of the fluid within each port of the U-tube, will
203 be constantly fluctuating, making it difficult to record a single value.

204

205 Unlike U-tube manometers, pressure transducers operate by converting a pressure difference
206 to an electrical signal that can be recorded on a data acquisition system. This represents an
207 advantage over the U-tube manometer as it facilitates the automatic recording of pressure,
208 including instantaneous fluctuations. They are also smaller than U-tube manometers and can
209 operate with low airflow volumes.

210

211 Pressure devices can't provide unobtrusive measurements of the flow in packed domains and
212 they can only measure unidirectional flows along a streamline. Their sensitivity is limited, as
213 they require a reasonable flowrate, to cause a detectable pressure difference. Taking the Pitot
214 tube as an example if the flowrate is 0.6 m.s^{-1} and an accuracy of 1% is required in its
215 determination, then the manometer must be sensitive to changes of approximately 0.02 mm
216 of a water column (Rathakrishnan, 2007). Practically, if a water column height change of 1
217 mm is the limiting sensitivity then the corresponding minimum air velocity that can be
218 measured is 4 m.s^{-1} . Hence, pressure devices cannot be used in room cooling or storage
219 facilities, where low velocity and stagnant zones may exist. Due to their intrusive

220 characteristics pressure measuring devices are generally used to measure the total flow rate
221 into or out of a system and not within it.

222

223 Examples of differential pressure flowmeters for measuring airflow measurements in food
224 operations include: Dehghannya et al., 2008; 2011; 2012; Gill et al., 2012; Khatchatourian et
225 al., 2009; Mohanraj and Chandrasekar, 2008; Ngcobo et al., 2012; O’Sullivan et al., 2013.

226

227 2.2. Non-invasive qualitative methods

228

229 Non-invasive flow visualisation techniques have been pivotal in developing a better
230 understanding of postharvest cooling and refrigeration processes, as they facilitate a more
231 detailed and accurate assessment of airflow behaviour throughout the system. By introducing
232 visible particles (e.g. smoke) in the flow these methods can not only provide a better
233 understanding of the flow patterns generated within the system but also facilitate a
234 quantitative assessment (as discussed in the next section).

235

236 Smoke and helium bubbles make up the most common seeding particles to visualise airflow
237 (Maghirand and Manbeck, 1993; Ruegg et al., 1994). The motion of the particles, within an
238 illuminated thin laser light sheet is measured by tracking their location in time by a camera
239 situated normal to the plane. The tracer particles must be sufficiently small and light so they
240 can closely follow the flow field behaviour but large enough, so they scatter a sufficient
241 amount of light, to be photographed or recorded with a camera.

242

243 Tracer particles are commonly generated by using a smoke-wire technique (Lohan, 2002;
244 Wang et al., 2000). “Smoke” is generated by vaporising oil from a small diameter wire (~0.1
245 mm) through a resistive heating (Cornaro et al., 1999). Commonly used wire materials
246 include steel and tungsten. This technique is limited to situations where the Reynolds
247 number, based on the wire diameter, is small, approximately 20 since the smoke will become
248 too dispersed in the fluid if the Reynolds number is higher. In practice, this low Reynolds
249 number limitation restricts airflow experiments to maximum velocities of approximately 3
250 m.s⁻¹ (Rathakrishnan, 2007).

251 Smoke particles can also be generated by commercially available generators which vaporise a
252 glycerine or alcohol solution, forming a non-toxic smoke.

253

254 The helium bubble method represents a flow visualisation technique that can be used in
255 systems with airflow speeds of up to 60 m.s⁻¹ and moderate levels of turbulence
256 (Rathakrishnan, 2007). Unlike smoke particles they can still be visualised even when
257 dispersed. Filling soap bubbles with helium allows both the size (typically 1-3 mm) and
258 buoyancy to be controlled, making it an ideal tracing particle (Biwole et al., 2009;
259 Klimentjew et al., 2010; Suzuki and Kasagi, 2000). However, these bubbles tend to only
260 reflect about 5% of incident light (Mueller, 1996), resulting in increasing importance of
261 placement of light sources. Using the maximum possible amount of light on the bubbles,
262 while maintaining a dark background, assists in bubble visualisation (Randall, 1979).

263

264 Examples of flow visualisation to identify flow patterns in food operations include:
265 Hellickson et al., 2003; Sarkar and Singh, 2004.

266

267 2.3. Non-invasive quantitative methods

268

269 Non-invasive quantitative techniques expand upon flow visualisation by quantifying particles
270 displacement. Examples of this technique that have been used to investigate the airflow
271 behaviour during forced-air cooling, refrigeration and drying operations are tracer gas
272 methods, laser doppler anemometry (LDA) and particle image velocimetry (PIV). These
273 techniques do not interfere with airflow and, in the case of LDA and PIV, can be extremely
274 accurate.

275

276 2.3.1 Tracer gas methods

277

278 Tracer gas methods determine the air movement in a system by measuring the concentration
279 of the gas at a specific point downstream from its release into the system. Available
280 techniques include decay, constant injection and constant-concentration measurements
281 (Sherman, 1990). The tracer decay technique infers the flow rate by measuring the temporal
282 drop in tracer concentration. In constant injection a uniform concentration of tracer is
283 continuously injected and the flow determined by measuring its concentration at specific
284 points within the domain. In constant-concentration the amount of the injected tracer is
285 controlled to ensure a constant concentration of the tracer at a particular location. The fluid
286 flow rate is then calculated from the required flow rate of the tracer injected divided by the
287 concentration of the tracer (mol tracer/mol air). The tracer (gas) itself must be safe and freely
288 available (Smale, 2004). The most common tracer gas to fit these requirements is carbon
289 dioxide (Yan et al., 2009). However, in situations where natural convection is likely to occur,
290 such as the static cooling of horticultural produce, carbon monoxide becomes a better choice
291 than carbon dioxide (Amos, 2005). The airflow pattern is then analysed from time profiles of
292 gas concentration at different positions in the system.

293

294 The tracer gas method requires sensors with fast response times and a sufficiently small size
295 to avoid interfering with the airflow pattern (as they need to be located in different spatial
296 positions within the system). Tracer gases are not suitable for use in a system where
297 measurements are required over an extended time period, due to the volume of tracer
298 required. The errors in this technique are typically in the range of 5-10% (McWilliams,
299 2003).

300

301 Examples of the tracer method for measuring airflow measurements in food operations
302 include: Amin et al., 2009; 2010; 2011; 2012; Amos, 2005; Tanner et al., 2000.

303

304 2.3.2 Laser Doppler Anemometry

305

306 Both LDA and PIV are based on the analysis of movement of small (neutrally buoyant) tracer
307 particles, which are seeded in the flow. In LDA laser light of a known frequency illuminates
308 the particles in the air flow and the scattered light is detected by a photomultiplier tube. The
309 principle behind LDA is that when light is reflected from a moving object the frequency of
310 the scattered light will be altered in proportion to the speed of the object under investigation.
311 By observing the frequency shift, the speed of the object can be estimated (Durst et al., 1981).
312 This process is graphically presented in Figure 1.

313

314 LDA measurements are linear with velocity and the device does not require external
315 calibration (Wu et al., 2007). LDA can measure a wide range of velocities, from 10^{-4} m.s⁻¹ to

316 10^3 m.s^{-1} . It possesses a high frequency response and is insensitive to fluid temperature,
317 density or composition. However, only a single point can be sampled at any given time.

318

319 Examples of LDA for measuring airflow measurements in food operations include: Alvarez
320 et al., 2003; Foster et al., 2002; Macroft et al., 1999; Macroft & Karwe, 1999; Moureh et al.,
321 2004, 2009a, 2009b, 2009c.

322

323 2.3.3 Particle image velocimetry

324

325 In PIV the flow is successively illuminated by thin layers of laser light, within a short period
326 of time. The location of the particles is then determined within each laser pulse by measuring
327 the light scattered by them into a CCD (Charge Coupled Device) camera. Once the location
328 of the particles is determined for each laser pulse the particle displacement is then determined
329 by cross-connecting their location in two successive laser pulses. From these correlations, a
330 velocity vector can be obtained for each small region of the imaged domain, resulting in a
331 vector field (Adrian, R., 1991). For a comprehensive and more detailed explanation of the
332 PIV technique, the reader is referred to Prasad (2000). The PIV technique is illustrated in
333 Figure 2.

334

335 PIV has advantages compared to LDA in that it is a whole-flow-field measurement technique
336 that provides instantaneous velocity vector measurements in an entire cross-section of the
337 fluid flow, as opposed to the single point measurements associated with LDA. Planer flows,

338 as well as 3D flows can be obtained and continued advances in the acquisition frequency of
339 digital cameras have facilitated the assessment of turbulent structures in greater detail.

340

341 For LDA and PIV a clear line of sight (e.g. transparent window) must be provided to the fluid
342 flow so the movement of the tracer particles can be recorded. Unlike the tracer gas method,
343 LDA and PIV require an unobstructed view of the point being measured, reducing their
344 applicability in actual food processing rooms filled with produce (Amos, 2005). This
345 requirement has meant that although LDA and PIV have been used extensively in
346 aerodynamics (Jeffrey et al., 2000; Raffel and Kost., 1998) and biomechanics (Gijssen et al.,
347 1996; Lim et al., 2001) it is only recently that the techniques have been applied to complex
348 flow systems found in food operations. LDA and PIV are also relatively expensive
349 techniques.

350

351 Examples of PIV for measuring airflow measurements in food operations include: Laguerre
352 et al., 2008; 2009; 2010; 2012; Ferrua and Singh, 2008; 2009a; 2009b; 2009c; 2011.

353

354 3. Design and efficiency of post-harvest cooling

355

356 3.1 Forced-air cooling

357

358 In forced-air cooling field heat is removed from freshly harvested produce by placing the
359 produce inside palletised ventilated packages through which refrigerated air, at relatively high
360 flow rates, is forced through by means of a fan (Figure 3) (Brosnan and Sun, 2001). For the

361 tunnel cooler, the most common forced-air cooling device, the fan creates a vacuum which
362 draws refrigerated air through two palletized rows of horticulture produce.

363

364 As refrigerated air is pulled through ventilated packages preferential airflow pathway are
365 formed, along with areas of maximum and minimum airflow velocities (Alvarez and Flick,
366 1999a, 2003). This uneven distribution of the refrigerated air leads to cooling heterogeneity
367 within the packages.

368

369 Alvarez and Flick (1999a) conducted an experimental aerodynamic study to better understand
370 the relationship between the cooling heterogeneity during the forced-air cooling process and
371 the behaviour of the airflow within food bins stacked in a pallet. PVC spheres were used to
372 represent the horticultural products and a hot-wire anemometer measured the air velocity.
373 The results showed preferential airflow pathways through the bins, along with back-mixing
374 zones at the inlet corners. This uneven distribution of the flow was then directly related to the
375 significant differences (up to 40 %) in the heat transfer coefficients measured, resulting in
376 non-uniform cooling of the produce.

377

378 Alvarez et al. (2003) used LDA to determine the semiempirical constants needed to
379 numerically model the turbulent kinetic energy and the heat transfer process that develop
380 within a porous structure of stacked spheres in vented boxes. By seeding water droplets
381 (2×10^{-6} m mean diameter) and incense smoke in the flow field the velocities upstream,
382 downstream and in between stacked PVC spheres representing the produce were measured.
383 The numerical model developed then identified maximum air velocities within the centre of
384 the vented box and decreasing velocities towards the corners of the box, which could explain
385 the cooling heterogeneity observed within the box.

386

387 Delele et al. (2008) used hot-wire anemometry to validate a CFD model for the forced-air
388 cooling of a box containing 32 spheres representing horticultural produce. After validation
389 the CFD model was used to simulate various scenarios (box vent hole ratio, product size,
390 etc...). The results showed a decay in air velocity through the box, hence cooling potential, as
391 the distance from the box inlet increased.

392

393 Delele et al. (2013b) measured the air velocity flowing through vented packages of citrus
394 fruit and the corresponding airflow resistance across a stack during a typical forced air
395 cooling application. The experimental data, obtained by using a hot-wire thermal anemometer
396 and a differential pressure transmitter, was then used to validate a 3D CFD model of the
397 forced-air cooling process. The CFD model showed that the cooling of individual pieces of
398 produce was dependent on their location within the package. Produce near the package vents,
399 specifically behind the entrance vents, experienced relatively high air velocities and,
400 consequently, experienced the fastest cooling. Airflow homogeneity was found to improve
401 with decreasing air velocity as the air flowed from the entrance to the exit vents in the
402 package.

403

404 Recent studies into the packaging of table grapes have shown that the airflow can be
405 significantly affected by the presence of inner packaging, such as carry-bags and liner films.
406 Ngcobo et al. (2012) used a pressure transducer in a wind tunnel, simulating forced-air
407 cooling, to show that liner films inside a ventilated package caused a significant increase in
408 pressure drop (typically over 50 %) through ventilated packages of table grapes. Ngcobo et
409 al. (2013) used a hot wire anemometer to measure the air velocity entering ventilated
410 packages of table grapes stacked on a pallet during an experimental forced-air cooling set-up.

411 The pressure drop through the packages was also measured using a pressure transducer
412 device. Results showed that the inner packaging significantly restricted the airflow through
413 the box.

414

415 Using airflow resistance measurements from previous work Delele et al. (2013a) generated a
416 CFD model of room cooling of table grape packages. The study showed that the half cooling
417 times were increased by 61 % when a carry-bag was included in the package. Adding a liner
418 film to the package, in addition to the carry-bag, further increased the half cooling time by
419 169 %.

420

421 3.2 Improvements to forced-air cooling operations

422

423 Dehghannya et al. (2008; 2011; 2012) investigated the size and location of vented areas on
424 the cooling heterogeneity. A setup, involving a forced air tunnel to draw air through a bed of
425 solid polymer balls, was designed to simulate postharvest cooling of spherical produce inside
426 a ventilated package. A pitot tube recorded the air speed downstream of ventilated packages
427 with a variety of vent areas open to incoming airflow, ranging from 2.4 % to 12.1%. The
428 same airflow was pulled through each ventilated package allowing the effect of the vent area
429 on the cooling profile to be evaluated. Results indicated that while cooling uniformity
430 increases with the increase in vent area the rate of cooling is more dependent on the
431 distribution of the vent areas and may actually be lower if the vents are not distributed
432 properly. The cooling rate can be improved, for the same overall vent area, if the vents are
433 evenly distributed along the package wall. For example, three vents, with one vent located
434 near both edges of the package wall and one at the centre will facilitate a faster cooling rate

435 then if the same three vents are located beside each other in the centre of the package wall
436 (Dehghannya et al., 2012). The evenly distributed configuration promotes a more
437 homogeneous distribution of the airflow throughout the package, hence faster cooling.

438

439 Using a previous developed and experimentally validated CFD model Delele et al. (2013c)
440 analysed the effect of the area, shape, number and position of package vents on the forced-air
441 cooling of packed produce. For a given airflow rate, the cooling rate and airflow uniformity
442 were found to improve with an increase in the vent area up to 7 %. For a given pressure drop
443 across the system, cooling rates were found to improve as the vent area increases, with the
444 highest decrease in cooling time observed for an increase in vent area from 1 % to 3 % and
445 the cooling rate becoming less sensitive to increases in vent area after 7 %. The airflow and
446 cooling uniformity, but not cooling rate, could be improved by increasing the number of
447 vents, even if the total vent area was kept constant. Changing the location of vents from the
448 centre of the package to the top and bottom sections would change the location of the coldest
449 sections but not cooling rate or uniformity while the cooling rate and uniformity was
450 unaffected by the vent shape.

451

452 In order to improve upon the forced-air cooling of strawberry clamshells Ferrua and Singh
453 (2008) developed an optically transparent model, representative of retail clamshells of
454 strawberries to investigate the airflow behaviour. This model involved not only the use of a
455 transparent solid material to reproduce the packaging structure (fused silica) but also a perfect
456 refractive index matching between it and the working fluid (a mineral oil mixture). This set-
457 up allowed the airflow behaviour within the packaging system to be measured by PIV and
458 was then used to validate a numerical model for the forced-air cooling process of fresh

459 strawberries in commercial packages (Ferrua and Singh, 2009a; 2009b). The authors were
460 then able to make recommendations for a future package design, such as periodically
461 reversing the direction is pulled through the pallet, based on guidelines formulated from the
462 developed CFD model. In particular they found that increasing the vent area of the
463 clamshells, hence forcing more air through the clamshells will not necessarily lead to
464 improvements in the cooling rate of the process. Forcing more air through the clamshells
465 causes a faster increase in the air temperature along the system which has a significant and
466 detrimental effect on the cooling rate of the clamshells located at the end of the system
467 (Ferrua and Singh, 2009c). It was found that the cooling rate and uniformity of the process
468 could be improved by decreasing the temperature of the air been delivered at the warmest
469 points within the system. This was achieved by bypassing half the airflow entering the pallet
470 structure into the second part of the pallet, ensuring a supply of refrigerated air to the
471 warmest clamshells located in the back half of the pallet (Ferrua and Singh, 2011). By doing
472 this a decrease of 6 % in the time taken for the warmest part of the pallet to reach seven-
473 eights cooling was observed.

474

475 4. Design and efficiency of refrigeration

476

477 4.1.1 Room cooling

478

479 Refrigerated rooms for the storage of food produce constantly circulate refrigerated air to
480 maintain the produce at a low temperature. During storage, pallets of horticulture produce are

481 placed within a room where an evaporator-fan circulates and cools the air within the unit
482 (Figure 4).

483

484 An uneven airflow distribution in refrigerated rooms (Figure 4) can result in centrally located
485 bins receiving very little airflow (Amos, 2005) and low air speeds towards the rear of the
486 room (Delele et al., 2009a), effects that could be associated with the presence of warm spots
487 and temperature heterogeneity within the produce. Within the last decade a number of studies
488 have been done to better understand the relationship that exists between the distribution of the
489 airflow within the system and the rate and uniformity of the refrigeration process.

490

491 Amos (2005) used the tracer gas technique to identify the airflow patterns within a cool store
492 filled with horticulture produce stacked in bins. Carbon monoxide sensors were placed in a
493 cool store containing 622 bins. The sensors were placed in front of the evaporator, at the rear
494 of the cool store and within 5 sections spread uniformly between the bins where determined.
495 Carbon monoxide was then injected into a variety of positions within the cool store and the
496 mean velocity was calculated from the time of arrival from the injection point to each sensor.
497 The results showed an uneven distribution of air flow within the cool store with the top layers
498 and side columns of bins experiencing the highest air speeds while bins located centrally
499 experienced much lower airflows. These areas of low air velocity coincided with warm spots
500 in the cool room.

501

502 Using hot-film omni-directional anemometers Delele et al. (2009a) investigated the velocity
503 profile around a stack of 72 boxes uniformly distributed within two rows inside a cool store.

504 Results were used to validate a developed a multiscale CFD model of chicory root cool store
505 to investigate how humidification intervals can reduce chicory root weight loss during
506 cooling. The validated model clearly illustrated how the low velocity cooling towards the rear
507 of room was unable to completely remove the heat of respiration from the produce.

508

509 4.1.1 Improvements to room cooling

510

511 Hellickson et al. (2003) used flow visualisation to study the air circulation during the
512 postharvest cooling of apples and pears in a controlled atmosphere refrigerated storage room.
513 Helium-filled soap bubbles where dispersed inside a commercial sized fruit storage room and
514 the bubble motion recorded by video. The authors concluded that air-circulation and fruit
515 cooling during this operation could be improved by ensuring a minimum space of 0.6 m
516 between the rear walls and the bin stacks and a space of 0.2 m between the sidewalls and bin
517 rows.

518

519 Using the developed multiscale CFD model of the chicory root cool store Delele et al.
520 (2009b) tested potentially scenarios to improve the system. Numerical results suggested that
521 elongating the air deflector to direct refrigerated air to the rear of the room and reducing the
522 stack height to increase the free air space at the top of the room, would lead to an
523 improvement in the cooling time and overall process efficiency.

524

525 4.2.1 Refrigerated transport trailers

526

527 For transport vehicles of horticulture produce, such as highway trailers and trucks, a top-air
528 delivery system is employed to continuously circulate refrigerated air (Figure 5). Air is blown
529 from the refrigeration unit at the front, over the top of the horticulture produce, down
530 between the pallets and returns to the refrigeration unit at the front of the vehicle.

531

532 In refrigerated transport trailers the product temperature and homogeneity are directly
533 controlled by the airflow patterns (Moureh et al., 2009c). Refrigerated air must be delivered
534 to all parts of the container to compensate for heat fluxes through container walls and/or the
535 heat of respiration of the product. To understand airflow patterns in refrigerated transport
536 trailers Moureh et al. (2004) constructed a reduced-scale model (1:3.3) of a refrigerated truck,
537 containing slotted boxes filled with spheres, to validate a CFD model of the airflow within it.
538 Atomised oil particles of 4 μm mean diameter were seeded in the airflow and LDA was used
539 to measure the air velocity at 1,110 points. Moureh et al. (2009a) used this technique when
540 studying the airflow in slot-ventilated enclosures partially filled with vented boxes, such as
541 refrigerated transport trucks loaded with horticultural produce. The experiments as well as
542 numerical results showed that air circulation was found to be dependent on the porosity of the
543 boxes. For ventilated packages the refrigerated air supply jet had an increased penetration
544 depth along the truck length compared to non-permeable boxes. Non-permeable boxes
545 promoted short-circuiting of the airflow in the front part of the truck. This allowed produce in
546 the front of the truck to receive a sufficient supply of refrigerated air to maintain the produce
547 at low temperatures and remove the heat of respiration. However, the airflow rate was
548 inadequate to produce located at the back of the truck promoting temperature heterogeneity
549 within the truck.

550

551 4.2.2 Improvements to refrigerated transport trailers

552

553 Air-ducts located at the ceiling of refrigerated trucks can improve the overall homogeneity of
554 the airflow, and consequently temperature, in the truck (Moureh et al., 2009c). When air-
555 ducts are included the airflow is blown into the truck at three positions (at the front, 1/3 of the
556 truck length from the front and 2/3 of the truck length from the front). The authors combined
557 experimental and numerical work to show that the use of air-ducts avoids the occurrence of
558 stagnant zones and low velocities in the rear (region furthest from the evaporator fan) of the
559 truck, while reducing the air velocities at the front. Air-ducts were shown to prevent over-
560 chilling of produce, due to high air velocities, in the front of the trailer and overheating of the
561 produce, due to low air velocities, at the rear of the trailer.

562

563 4.3.1 Refrigerated display cabinets/domestic refrigerators

564

565 In open refrigerated display cabinets (Figure 6) and domestic refrigerators cooled air, at a low
566 airflow rates, is circulated to the refrigerator shelves. In open refrigerated display cabinets
567 (typically found in retail stores) warm air from outside is constantly infiltrating the cabinet,
568 although an air curtain can reduce the amount, while in domestic refrigerators this occurs
569 each time the door is opened.

570

571 By tracing a continuous and uniform injection of CO₂ gas Amin et al. (2009) investigated the
572 amount of warm air infiltration into an open refrigerated display cabinet. The concentration
573 of the tracer gas was measured at the discharge air grille, return air grille and the ambient
574 outside environment. By finding the percentage of tracer gas that escapes to the ambient a
575 relationship between tracer gas concentration and the amount of air infiltration can be
576 established. Depending on the amount, this warm air infiltration can cause significant
577 temperature heterogeneity within the cabinet resulting in temperature differences between the
578 food products.

579

580 PIV has been used to characterise the air flow behaviour that develops from natural
581 convection within a transparent model of a domestic refrigerator and its influence on water
582 evaporation (Laguerre et al., 2008; 2009). By analysing the dynamics of smoke particles
583 (generated using a low-temperature water-glycol mixture to seed the airflow) the authors
584 showed the occurrence of natural convection within the refrigerator, with warm air flowing to
585 the top of the refrigerator and cool air flowing to the bottom. In addition, the experimental
586 results were used to validate a CFD model that simulated the simultaneous heat and moisture
587 transfer in the refrigerator. By using the validated model Laguerre et al. (2010) showed the
588 dehydration of the food product near the top the refrigerator due to the higher air temperature.
589 Likewise, as the air flowed down towards the bottom of the refrigerator its temperature
590 decreased resulting in condensation on the food products in this region. Further work by
591 Laguerre et al. (2012) uses PIV to measure the air velocity profiles in a vertical open
592 refrigerated display cabinet. The results showed the highest air velocity near the air supply
593 and return ducts. As a consequence, due to the higher heat transfer coefficients, the
594 temperature of food products located in these areas was particularly affected by the

595 temperature of the air flowing past compared to the food located at the top of the display
596 cabinets.

597

598 4.3.2 Improvements to open refrigerated display cabinets

599

600 The infiltration rate of warm air into display cabinets can be minimised by reducing the
601 cabinet height and adjusting the angle of the jet nozzle supplying refrigerated air (Amin et al.
602 (2011; 2012). By tracing a continuous and uniform injection of CO₂ Amin et al., (2011, 2012)
603 used the previously developed tracer gas approach to relate primary curtain design
604 parameters, such as the height of the opening and flow rate ratio, and secondary variables,
605 including space between shelves filled with food products, to the infiltration rate of open
606 refrigerated cavities. In particular the authors found that the infiltration rate was dependent on
607 interacting variables. For example an extreme infiltration point could be reached by varying
608 the height of the cabinet and the throw angle, the angle of the jet nozzle supplying
609 refrigerated air relative to a vertical line through the cabinet.

610

611 5. Design and efficiency of drying operations

612

613 5.1 Understanding of convective drying systems

614

615 Drying operations use warm, dry air to lower the moisture content of horticulture produce.

616 Although there are many set-up methods for drying food, in a typical forced convection dryer

617 heated air is vertically blown across a bed of produce supported by a mesh (Figure 7). During
618 the drying of a bed of horticultural produce the distribution of the warm air before it
619 encounters the product (Janjai et al., 2006) and the bed depth and porosity (Lawrence and
620 Maier, 2011) impact upon the overall drying efficiency. For impingement jet drying
621 technology the number of jets, airflow exiting the jets and food product location relative to
622 the nozzle(s) impact upon the drying rate and uniformity (Macroft & Karwe, 1999; Macroft
623 et al., 1999).

624

625 To understand airflow distribution in a conventional longan dryer Janjai et al. (2006)
626 manually moved a hot-wire anemometer to different points on a predetermined grid. The
627 results showed that the airflow distribution was not symmetric with respect to the position of
628 the warm air inlet. Regions directly to the left and right of the air inlet were found to receive
629 very little airflow and consequently experienced low drying rates, leading to non-uniform
630 drying of the produce.

631

632 Lawrence and Maier (2011) used a vane anemometer to measure the air velocity at the grain
633 surface at four locations near the centre of grain bins as well as near the periphery at four
634 cardinal (north, south, east and west) directions. The results showed a non-uniform
635 distribution of the air within the system and were used to validate a CFD model of the
636 process. Results from the CFD model showed that the depth and porosity of the bed can have
637 a major impact on the airflow distribution within the bed and the overall efficiency of the
638 drying process. Lower porosity and greater bed depths result in a higher resistance to airflow
639 and consequently an uneven airflow distribution, which causes non-uniform drying.

640

641 LDA was used to analyse the axial and radial air velocity components in a commercial jet
642 impingement oven, used for conventional drying or toasting, from a single jet (Marcroft &
643 Karwe, 1999), and multiple jets (Marcroft et al., 1999). In both cases sublimed CO₂ (dry ice
644 fog) was used as the seeding particles. It was found that when using multiple jets the food
645 product, on a conveyer belt would experience uneven heating rates as it passed under
646 multiple jets. When the food product was directly under jet it experiences a high air velocity,
647 leading to heat transfer rates 2 to 3 times higher than when the product is not under the any
648 jet, and hence experience smaller air velocities. Hence, the areas of the food product
649 receiving the higher heat transfer rates dry quicker than the other areas of the product.

650

651 5.2 Improvements to forced convection drying systems

652

653 Nagle et al. (2010) used the portable hand held vane anemometer to record the velocity
654 distribution at a drying facility as a way to investigate the effect of different modifications,
655 such as a mesh to redirect the airflow, on the quality and energy performance of a hot air
656 convection fixed-bed longan dryer. The air speed at the top of the produce bulk (25 cm depth)
657 was determined, at 25 points in a 5x5 grid, at the beginning, middle and end of three drying
658 operations where the inclusion of an inverted mesh evenly distributed the incoming airflow
659 before it reached the produce. By improving the airflow distribution within the bed of
660 products to be dried the mesh improved the uniformity of drying and overall dryer
661 performance.

662 Janjai et al. (2006) increased the space under the perforated floor of a convective dryer and
663 installed air guides after the air inlet to redirect the airflow. This improved the airflow
664 distribution and hence drying uniformity of the process.

665

666 Sarkar and Singh (2004) used flow visualisation when investigating the relative importance
667 of nozzle exit velocity, nozzle design and impingement equipment design on food processing,
668 such as drying, using air impingement technology, consisting of jets emitting high-velocity
669 air. A custom-built air impingement system allowed various nozzles sizes and equipment
670 designs to be tested. Helium filled bubbles were introduced into the plenum and a camera was
671 used to track the flow pattern of the jets. Experimental results showed that major
672 improvements could be made to the air impingement systems drying performance by
673 optimising the height to diameter ratio, in the region of 6-8, of the air jets and using fully
674 developed jets.

675

676 6. Conclusions

677

678 For forced-air cooling, refrigeration and drying an even delivery of the airflow to each area of
679 the system is essential to optimizing the performance of the operations. In forced-air cooling
680 preferential airflow pathways, which cause significant differences to the air speeds within
681 ventilated packages, and an inadequate delivery of cool air to packages centrally located and
682 at the rear of pallets result in cooling heterogeneity in the system. The cooling rate can be
683 improved by increasing the vent area to certain percentage, specific to each package while
684 airflow and cooling uniformity can be improved by increasing the number of vents. In room
685 cooling and refrigerated transport trailers pallets located furthest from the evaporator fans
686 receive a small volume of the total airflow, resulting in the presence of warm spots at these
687 locations. In open refrigerated display cabinets localised high air speeds and warm air
688 infiltration can result in a fluctuating air temperatures, and consequently fluctuating food

689 product temperatures. Uneven airflow distribution causes non-uniform bed drying while the
690 location of the food product to impingement jets can cause uneven drying rates along the
691 width of the produce.

692

693 In order to improve these systems airflow measurements which can identify areas receiving
694 maximum and minimum airflow rates must be identified. While on-site measurements will
695 always remain important, non-intrusive quantitative techniques like LDA and PIV can
696 validate numerical models which can then be used to predict the product temperature and
697 storage life depending on the initial and environmental conditions.

698

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703

704

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706

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967 Figures

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969 Figure 1. Tunnel cooler, the most common forced-air cooling device. The fan creates a
970 vacuum which draws refrigerated air through two palletized rows of horticulture produce.

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972 Figure 2. Refrigerated storage room for horticulture produce. Evaporator fans circulate
973 refrigerated air through the room.

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975 Figure 3. Open refrigerated display cabinet.

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977 Figure 4. Refrigerated truck with a top-air delivery system. Air is blown from the
978 refrigeration unit at the front, over the top of the horticulture produce, down between the
979 pallets and returns to the refrigeration unit at the front of the vehicle.

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981 Figure 5. Forced convection dryer. Heated air is blown under a mesh which supports the
982 horticultural produce.

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984 Figure 6. Laser Doppler Anemometry measurement technique for measuring fluid velocity

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986 Figure 7. Figure 7. Particle Image Velocimetry technique for measuring fluid velocity

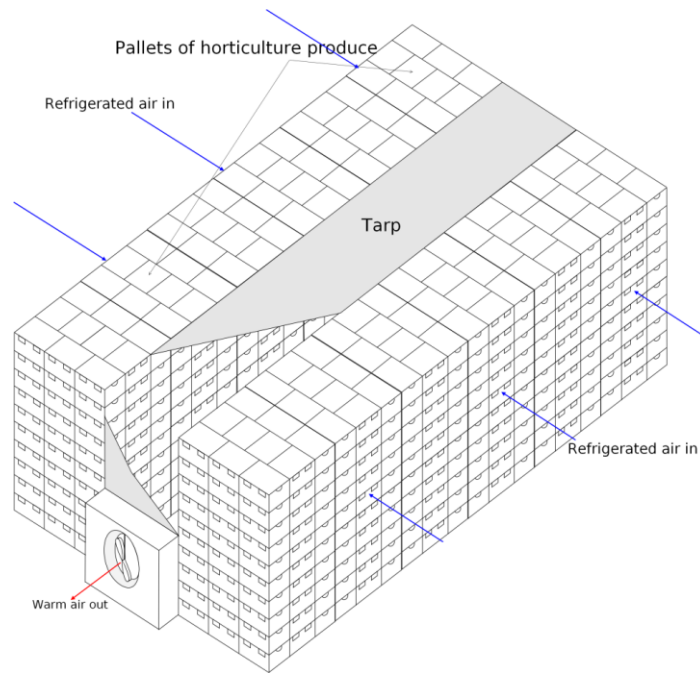
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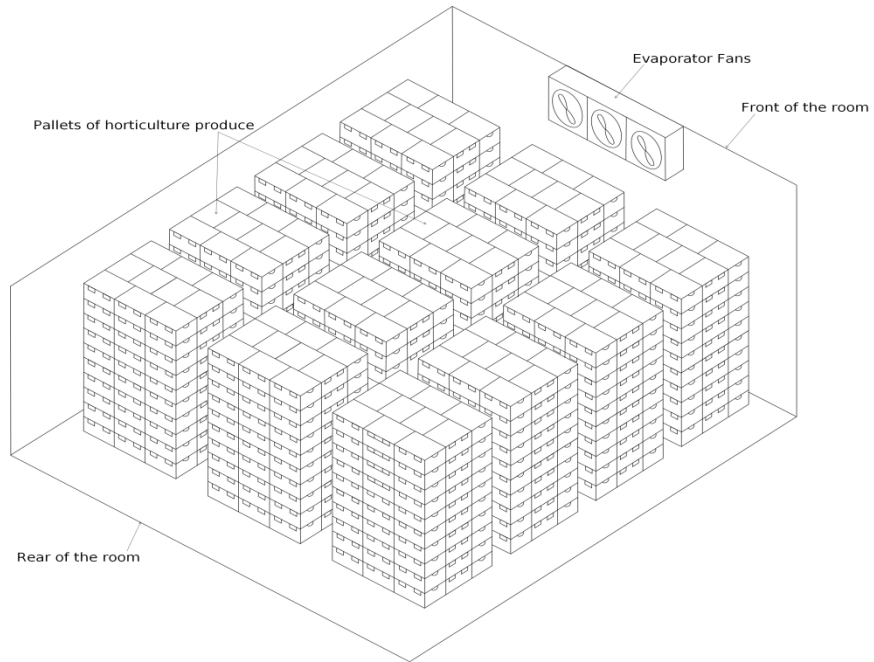
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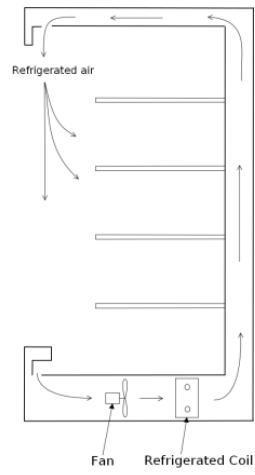
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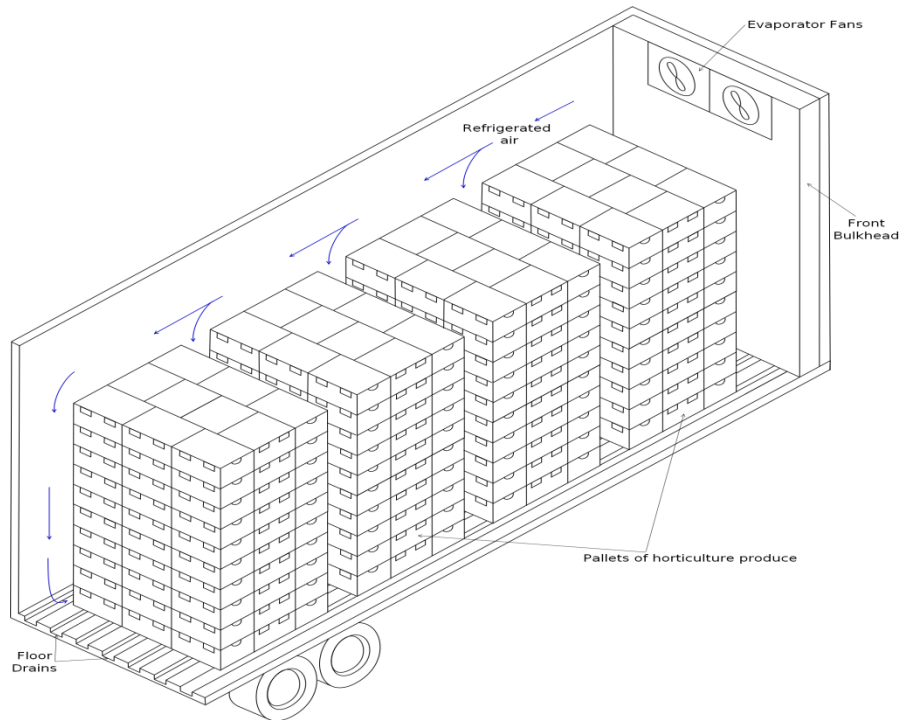


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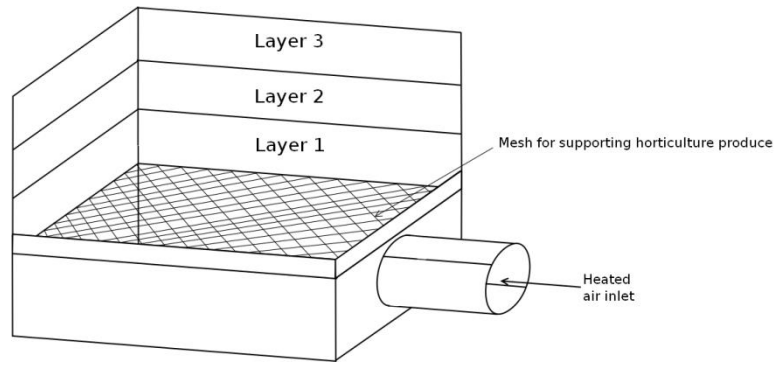
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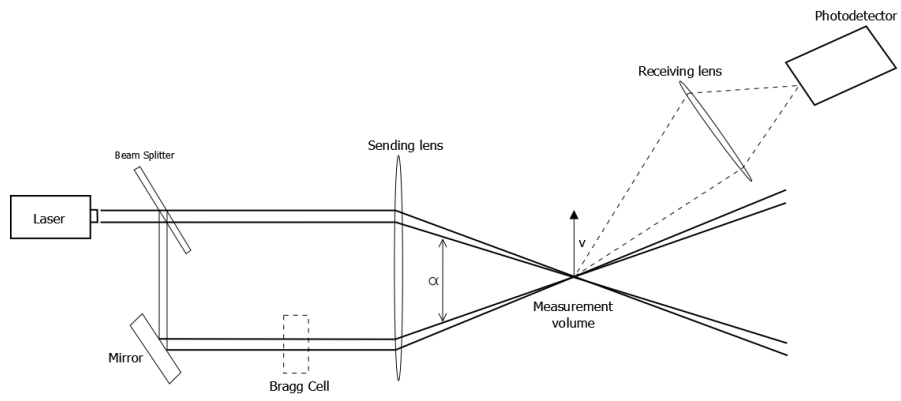
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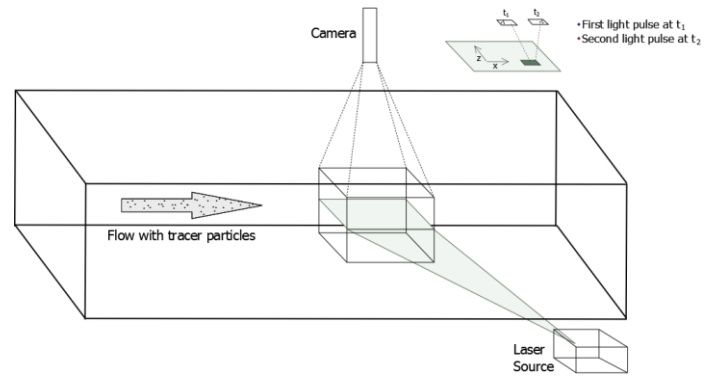


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