

Fitting mixtures of Erlangs to uncensored and untruncated data using the EM algorithm - Addendum

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Abstract

In this addendum, we present the EM algorithm of Lee and Lin (2010) customized for fitting mixtures of Erlang distributions with a common scale parameter to uncensored and untruncated data. We work out the details with zero-one component indicators inspired by McLachlan and Peel (2001) and Lee and Scott (2012).

1 Likelihood

Let $\mathbf{x} = (x_1, \dots, x_n)$ be an observed sample from the mixture of Erlang distributions with density given by

$$f(x; \boldsymbol{\alpha}, \mathbf{r}, \theta) = \sum_{j=1}^M \alpha_j \frac{x^{r_j-1} e^{-x/\theta}}{\theta^{r_j} (r_j - 1)!} = \sum_{j=1}^M \alpha_j f(x; r_j, \theta) \quad \text{for } x \geq 0. \quad (1)$$

The parameters to be estimated are the mixing proportions or weights $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_M)$ with $\alpha_j > 0$ and $\sum_{j=1}^M \alpha_j = 1$ and the common scale parameter θ , which are bundled by denoting $\boldsymbol{\Theta} = (\boldsymbol{\alpha}, \theta)$. The number of Erlangs M in the mixture and the corresponding positive integer shapes \mathbf{r} are fixed. The value of M is, in most applications, however unknown and has to be inferred from the available data, along with the shape parameters. The log likelihood is given by

$$l(\boldsymbol{\Theta}; \mathbf{x}) = \sum_{i=1}^n \ln \left(\sum_{j=1}^M \alpha_j \frac{x_i^{r_j-1} e^{-x_i/\theta}}{\theta^{r_j} (r_j - 1)!} \right).$$

which is difficult to numerically optimize due to logarithm of a summation.

2 Construction of the complete data vector

The EM algorithm provides a computationally much easier way for fitting this finite mixture. The main clue is to regard the observed sample $\mathbf{x} = (x_1, \dots, x_n)$ as being incomplete since their associated component-indicator vectors $\mathbf{z} = (z_1, \dots, z_n)$ with

$$z_{ij} = \begin{cases} 1 & \text{if observation } x_i \text{ comes from } j\text{th component density } f(x; r_j, \theta) \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

for $i = 1, \dots, n$ and $j = 1, \dots, M$, are not available (McLachlan and Peel (2001)). The component-label vectors $\mathbf{z}_1, \dots, \mathbf{z}_n$ are taken to be realized values of the random vectors

$$\mathbf{Z}_1, \dots, \mathbf{Z}_n \stackrel{\text{i.i.d.}}{\sim} \text{Mult}_M(1, \boldsymbol{\alpha}).$$

The log likelihood of the complete data vector (\mathbf{x}, \mathbf{z}) equals

$$l(\boldsymbol{\Phi}; \mathbf{x}, \mathbf{z}) = \sum_{i=1}^n \sum_{j=1}^M z_{ij} \ln(\alpha_j f_X(x_i; r_j, \theta)). \quad (3)$$

The EM algorithm exploits the simpler form of the complete data log likelihood to compute the maximum likelihood estimators based on the observed data.

3 Initial step

Initialization of θ and $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_M)$ is based on the denseness property (see Appendix A):

$$\theta^{(0)} = \frac{\max(\mathbf{x})}{r_M} \quad \text{and} \quad \alpha_j^{(0)} = \frac{\sum_{i=1}^n I(r_{j-1}\theta^{(0)} < x_i \leq r_j\theta^{(0)})}{n}, \quad \text{for } j = 1, \dots, M, \quad (4)$$

with $r_0 = 0$ for notational convenience. These starting values ensure that the initial guess is immediately quite decent.

4 E-step

In the E-step, we take the conditional expectation of the complete log likelihood (3) given the observed data \mathbf{x} and using the current estimate $\boldsymbol{\Theta}^{(k-1)}$ for $\boldsymbol{\Theta}$. Define, for $i = 1, \dots, n$ and $j = 1, \dots, M$, the posterior probability $z_{ij}^{(k)}$ that observation i belongs to the j th component in the mixture,

$$z_{ij}^{(k)} = E(Z_{ij} | \mathbf{x}; \boldsymbol{\Theta}^{(k-1)}) = \frac{\alpha_j^{(k-1)} f(x_i; r_j, \theta^{(k-1)})}{\sum_{m=1}^M \alpha_m^{(k-1)} f(x_i; r_m, \theta^{(k-1)})}. \quad (5)$$

Then

$$\begin{aligned} Q(\boldsymbol{\Theta}; \boldsymbol{\Theta}^{(k-1)}) &= E(l(\boldsymbol{\Theta}; \mathbf{x}, \mathbf{Z}) | \mathbf{x}; \boldsymbol{\Theta}^{(k-1)}) \\ &= \sum_{i=1}^n \sum_{j=1}^M E(Z_{ij} | \mathbf{x}; \boldsymbol{\Theta}^{(k-1)}) \ln(\alpha_j f_X(x_i; r_j, \theta)) \\ &= \sum_{i=1}^n \sum_{j=1}^M z_{ij}^{(k)} \left[\ln(\alpha_j) + (r_j - 1) \ln(x_i) - \frac{x_i}{\theta} \right. \\ &\quad \left. - r_j \ln(\theta) - \ln((r_j - 1)!) \right], \end{aligned} \quad (6)$$

The E-step hence reduces to calculating all posterior probabilities.

5 M-step

The M-step requires the global maximization of (6) obtained in the E-step with respect to $\Theta = (\alpha, \theta)$ with $\alpha_i > 0$, $\sum_{i=1}^M \alpha_i = 1$ and $\theta > 0$. We first maximize (6) with respect to the mixing proportions α . This can be done separately of the updated estimate for θ as it requires the maximization of

$$\sum_{i=1}^n \sum_{j=1}^M z_{ij}^{(k)} \ln(\alpha_j) = \sum_{i=1}^n \sum_{j=1}^{M-1} z_{ij}^{(k)} \ln(\alpha_j) + \sum_{i=1}^n z_{iM}^{(k)} \ln \left(1 - \sum_{j=1}^{M-1} \alpha_j \right)$$

with respect to $\alpha_1, \dots, \alpha_{M-1}$. Note that we implement the restriction $\sum_{j=1}^M \alpha_j = 1$ by setting $\alpha_M = 1 - \sum_{j=1}^{M-1} \alpha_j$. Setting the partial derivatives at $\alpha^{(k)}$ equal to zero yields

$$\left. \frac{\partial Q(\Theta; \Theta^{(k-1)})}{\partial \alpha_j} \right|_{\alpha=\alpha^{(k)}} = \sum_{i=1}^n \frac{z_{ij}^{(k)}}{\alpha_j} - \sum_{i=1}^n \frac{z_{iM}^{(k)}}{\alpha_M} \Big|_{\alpha=\alpha^{(k)}} = 0 \quad \text{for } j = 1, \dots, M-1.$$

This implies that the optimizer satisfies

$$\alpha_j^{(k)} = \frac{\sum_{i=1}^n z_{ij}^{(k)}}{\sum_{i=1}^n z_{iM}^{(k)}} \alpha_M^{(k)} \quad \text{for } j = 1, \dots, M-1. \quad (7)$$

Using the restriction that the mixing weights must sum to one, we obtain

$$1 = \sum_{j=1}^M \alpha_j^{(k)} = \frac{\sum_{i=1}^n \left(\sum_{j=1}^M z_{ij}^{(k)} \right) \alpha_M^{(k)}}{\sum_{i=1}^n z_{iM}^{(k)}} = \frac{n \alpha_M^{(k)}}{\sum_{i=1}^n z_{iM}^{(k)}}.$$

Hence

$$\alpha_M^{(k)} = \frac{\sum_{i=1}^n z_{iM}^{(k)}}{n}$$

and by plugging this expression in (7), the same form also follows for $j = 1, \dots, M-1$:

$$\alpha_j^{(k)} = \frac{\sum_{i=1}^n z_{ij}^{(k)}}{n} \quad \text{for } j = 1, \dots, M.$$

This solution has a nice intuitive interpretation. The new estimate for the prior probability α_j is the average over all observations i of the posterior probability $z_{ij}^{(k)}$ of belonging to the j th component in the mixture. The optimizer indeed corresponds to a maximum since

$$\begin{aligned} \left. \frac{\partial^2 Q(\Theta; \Theta^{(k-1)})}{\partial \alpha_j^2} \right|_{\alpha=\alpha^{(k)}} &= - \sum_{i=1}^n \frac{z_{ij}^{(k)}}{\alpha_j^2} - \sum_{i=1}^n \frac{z_{iM}^{(k)}}{\alpha_M^2} \Big|_{\alpha=\alpha^{(k)}} \\ &= - \frac{n^2}{\sum_{i=1}^n z_{ij}^{(k)}} - \frac{n^2}{\sum_{i=1}^n z_{iM}^{(k)}} \end{aligned}$$

for $j = 1, \dots, M$ and

$$\begin{aligned} \left. \frac{\partial^2 Q(\Theta; \Theta^{(k-1)})}{\partial \alpha_j \partial \alpha_m} \right|_{\alpha=\alpha^{(k)}} &= - \sum_{i=1}^n \frac{z_{iM}^{(k)}}{\alpha_M^2} \Big|_{\alpha=\alpha^{(k)}} \\ &= - \frac{n^2}{\sum_{i=1}^n z_{iM}^{(k)}}, \end{aligned}$$

for $j = 1, \dots, M$ and $m = 1, \dots, M$, implying that the matrix of second order partial derivatives is negative definite matrix with a compound symmetry structure.

We next maximize (6) with respect to θ :

$$\begin{aligned} \left. \frac{\partial Q(\Theta; \Theta^{(k-1)})}{\partial \theta} \right|_{\theta=\theta^{(k)}} &= \sum_{i=1}^n \sum_{j=1}^M z_{ij}^{(k)} \left(\frac{x_i}{\theta^2} - \frac{r_j}{\theta} \right) \Big|_{\theta=\theta^{(k)}} \\ &= \frac{1}{\theta^2} \sum_{i=1}^n \left(\sum_{j=1}^M z_{ij}^{(k)} \right) x_i - \frac{n}{\theta} \sum_{j=1}^M \left(\frac{\sum_{i=1}^n z_{ij}^{(k)}}{n} \right) r_j \Big|_{\theta=\theta^{(k)}} \\ &= \frac{1}{\theta^2} \sum_{i=1}^n x_i - \frac{n}{\theta} \sum_{j=1}^M \alpha_j^{(k)} r_j \Big|_{\theta=\theta^{(k)}} = 0. \end{aligned}$$

Hence

$$\theta^{(k)} = \frac{\sum_{i=1}^n x_i / n}{\sum_{j=1}^M \alpha_j^{(k)} r_j}, \quad (8)$$

which is a maximum since

$$\begin{aligned} \left. \frac{\partial^2 Q(\Theta; \Theta^{(k-1)})}{\partial \theta^2} \right|_{\theta=\theta^{(k)}} &= \frac{-2}{\theta^3} \sum_{i=1}^n x_i + \frac{n}{\theta^2} \sum_{j=1}^M \alpha_j^{(k)} r_j \Big|_{\theta=\theta^{(k)}} \\ &= n \sum_{j=1}^M \alpha_j^{(k)} r_j \left[\frac{-2 \sum_{i=1}^n x_i / n}{\theta^3 \sum_{j=1}^M \alpha_j^{(k)} r_j} + \frac{1}{\theta^2} \right] \Big|_{\theta=\theta^{(k)}} \\ &= n \sum_{j=1}^M \alpha_j^{(k)} r_j \left[\frac{-1}{(\theta^{(k)})^2} \right] < 0. \end{aligned}$$

The new estimate $\theta^{(k)}$ in (8) for the common scale parameter θ equals the sample mean divided by the weighted average shape parameter in the mixture. The updating scheme (8) for the scale parameter makes intuitively sense since the expected value of a mixture of Erlangs equals $E(X) = \sum_{j=1}^M \alpha_j r_j \theta$.

The E- and M-steps are iterated until the difference in log likelihood values $l(\Theta^{(k)}; \mathcal{X}) - l(\Theta^{(k-1)}; \mathcal{X})$ is sufficiently small.

Appendix A Denseness

In this Appendix, we formulate the theorem stating that the class of mixtures of Erlang distributions with a common scale parameter is dense in the space of distributions on \mathbb{R}^+ (see Tijms (1994, p. 163)).

Theorem A.1. *The class of mixtures of Erlang distributions with a common scale parameter is dense in the space of distributions on \mathbb{R}^+ . More specifically, let $F(x)$ be the cumulative*

distribution function of a positive random variable. Define the following cumulative distribution function of a mixture of Erlang distributions with a common scale parameter $\theta > 0$,

$$F(x; \theta) = \sum_{j=1}^{\infty} \alpha_j(\theta) F(x; j, \theta),$$

where $F(x; j, \theta)$ denotes the cumulative distribution function of an Erlang distribution with shape j and scale θ ,

$$F(x; j, \theta) = 1 - \sum_{n=0}^{j-1} e^{-x/\theta} \frac{(x/\theta)^n}{n!},$$

and the mixing weights are given by

$$\alpha_j(\theta) = F(j\theta) - F((j-1)\theta) \quad \text{for } j = 1, 2, \dots.$$

Then

$$\lim_{\theta \rightarrow 0} F(x; \theta) = F(x),$$

for each point x at which $F(\cdot)$ is continuous.

References

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