

isl: An Integer Set Library for the Polyhedral Model

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Outline

- 1 Introduction
- 2 Internals
- 3 Operations
 - Set Difference
 - Set Coalescing
 - Parametric Vertex Enumeration
 - Bounds on Quasi-Polynomials
- 4 Conclusion

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An Integer Set Library

`isl` is an **LGPL thread-safe C** library for manipulating **sets and relations** of **integer tuples** bounded by **affine constraints**

↪ finite unions of projections of parametric lattice polytopes

An Integer Set Library

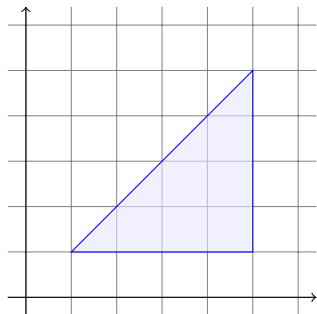
`isl` is an **LGPL thread-safe C** library for manipulating **sets and relations of integer tuples** bounded by **affine constraints**

↪ finite unions of projections of parametric lattice polytopes

- very similar to `Omega` and `Omega+` libraries
- similar to `polymake`, but different focus/philosophy
 - ▶ integer values instead of rational values
 - ▶ designed for the polyhedral model for program analysis and transformation (but also useful for other applications)
 - ▶ library (“calculator” interface is available too)
 - ⇒ embeddable in a compiler
 - ▶ works best on sets of small dimensions (up to about 10; some operations also work for higher dimensions)
 - ▶ self-contained (apart from GMP)
 - ▶ closed representation
 - ▶ objects may be sets or relations (or piecewise quasipolynomials)

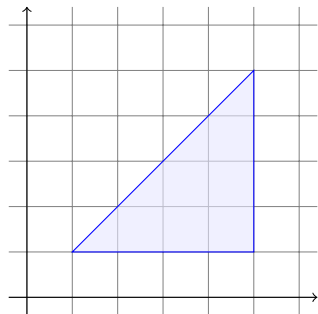
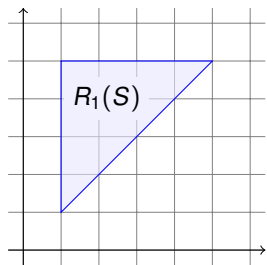
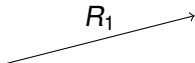
Examples of Sets and Relations

$$S = \{(x, y) \mid 1 \leq y \leq x \leq 5\}$$



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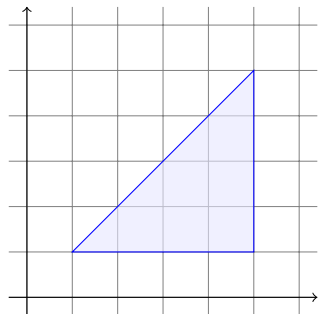
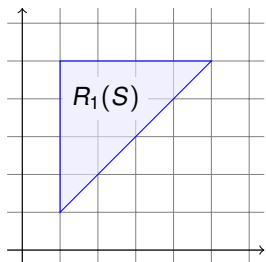
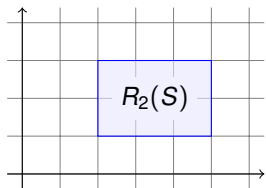
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 R_2


$$R_1 = \{(x, y) \rightarrow (y, x)\} = \{(x, y) \rightarrow (x', y') \mid x' = y \wedge y' = x\}$$

$$R_2 = \{(x, y) \rightarrow (x, y') \mid x \geq 2 \wedge 1 \leq y' \leq 3\}$$

Sets and Relations in the Polyhedral Model

```
for (i = 0; i < n; ++i)
  for (j = 0; j < i; ++j)
    f(a[j][i+j][2*i]);
```

Typical sets and relations

- Iteration domain
⇒ set of all possible values of the iterators

$$n \rightarrow \{(i, j) \mid 0 \leq i < n \wedge 0 \leq j < i\}$$

- Access relation
⇒ maps iteration vector to array index

$$\{(i, j) \rightarrow (j, i + j, 2i)\}$$

Comparison to Related Libraries

- Compared to double description based libraries (PolyLib, PPL)
 - ▶ All operations are performed on constraints
Reason: objects in target application domain usually have few constraints, but may have many vertices
 - ▶ Full support for parameters
 - ▶ Built-in support for existentially quantified variables
 - ▶ Built-in support for relations
 - ▶ Focus on integer values

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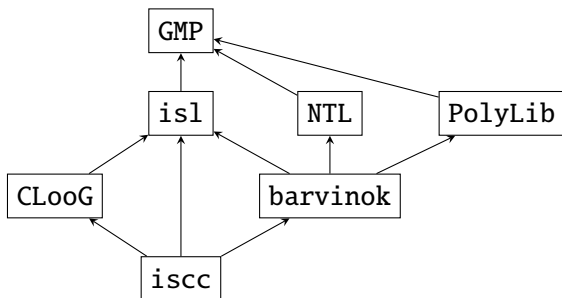
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 - ▶ Built-in support for relations
 - ▶ Focus on integer values
- Compared to Omega and Omega+
 - ▶ All operations are performed in arbitrary integer arithmetic using GMP
 - ▶ Different way of handling existentially quantified variables
 - ▶ Named and nested spaces
 - ▶ Parametric vertex enumeration
⇒ useful for the `barvinok` counting library and for computing bounds
 - ▶ Support for piecewise quasipolynomials
⇒ results of counting problems

Interaction with Other Libraries and Tools

barvinok: counts elements in parametric affine sets and relations

CLooG: generates code to scan elements in parametric affine sets

iscc: interactive isl calculator (included in barvinok distribution)

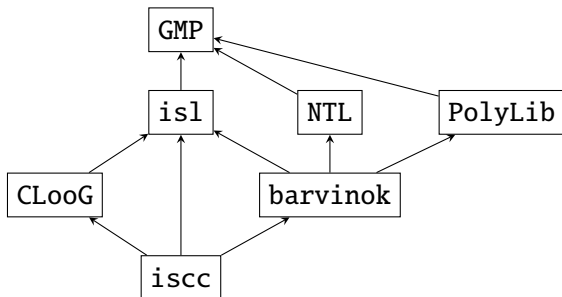


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Future work:

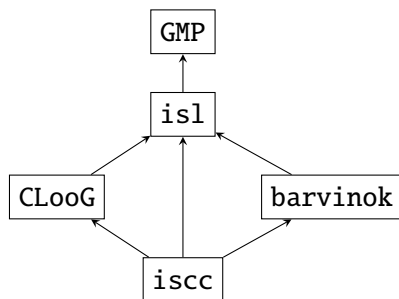
- remove dependence on PolyLib and NTL

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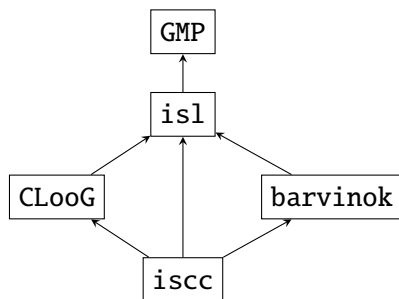
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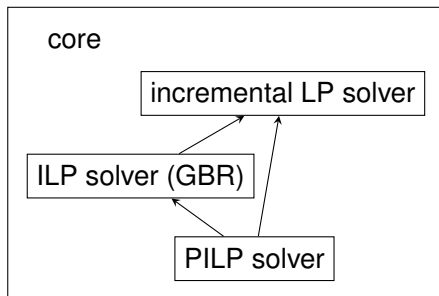
Future work:

- remove dependence on PolyLib and NTL
- merge barvinok into isl

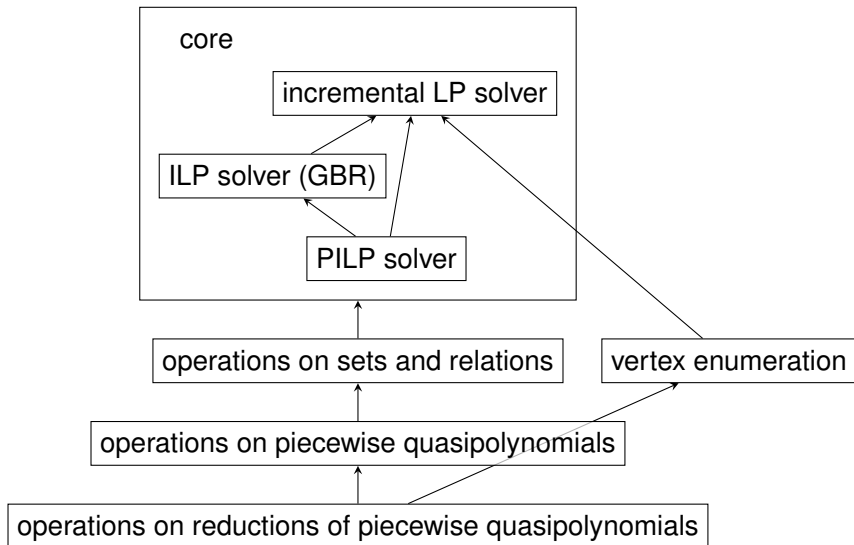
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Internal Structure



Internal Structure



Internal Representation

$$S(\mathbf{s}) = \{ \mathbf{x} \in \mathbb{Z}^d \mid \exists \mathbf{z} \in \mathbb{Z}^e : A\mathbf{x} + B\mathbf{s} + D\mathbf{z} \geq \mathbf{c} \}$$

$$R(\mathbf{s}) = \{ \mathbf{x}_1 \rightarrow \mathbf{x}_2 \in \mathbb{Z}^{d_1} \times \mathbb{Z}^{d_2} \mid \exists \mathbf{z} \in \mathbb{Z}^e : A_1\mathbf{x}_1 + A_2\mathbf{x}_2 + B\mathbf{s} + D\mathbf{z} \geq \mathbf{c} \}$$

- “basic” types: “convex” sets and maps (relations)
 - ▶ equality + inequality constraints
 - ▶ parameters \mathbf{s}
 - ▶ (optional) explicit representation of existentially quantified variables as integer divisions
 - ⇒ useful for aligning dimensions when performing set operations (e.g., set difference)
 - ⇒ can be computed using PILP

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- sets and maps
 - ⇒ (disjoint) unions of basic sets/maps
- union sets and union maps
 - ⇒ unions of sets/maps in different spaces

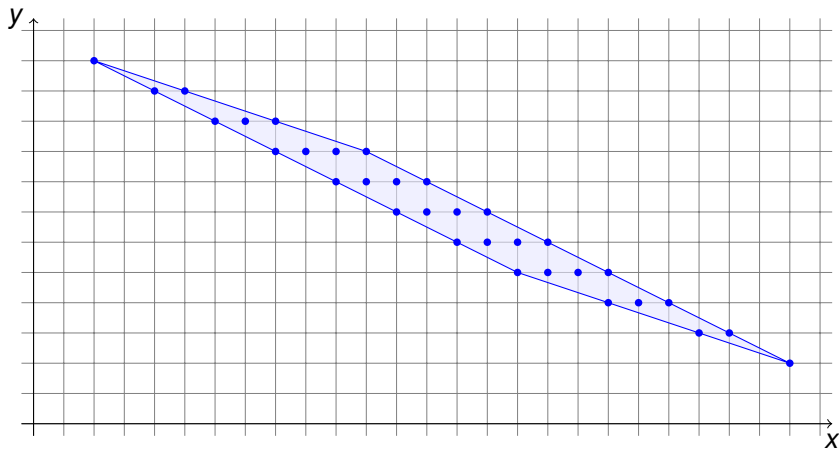
Parametric Integer Linear Programming

$$R(\mathbf{s}) = \{ \mathbf{x}_1 \rightarrow \mathbf{x}_2 \in \mathbb{Z}^{d_1} \times \mathbb{Z}^{d_2} \mid \exists \mathbf{z} \in \mathbb{Z}^e : A_1 \mathbf{x}_1 + A_2 \mathbf{x}_2 + B\mathbf{s} + D\mathbf{z} \geq \mathbf{c} \}$$

Lexicographic minimum of R :

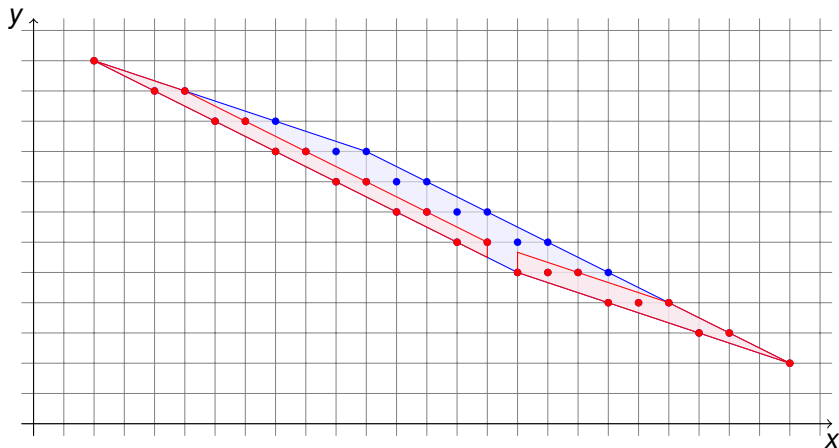
$$\text{lexmin } R = \{ \mathbf{x}_1 \rightarrow \mathbf{x}_2 \in R \mid \forall \mathbf{x}'_2 \in R(\mathbf{s}, \mathbf{x}_1) : \mathbf{x}_2 \preceq \mathbf{x}'_2 \}$$

Parametric Integer Linear Programming Example



$$R = \{x \rightarrow y \mid 3y \geq 31 - x \wedge 2y \leq 29 - x \wedge 3y \leq 38 - x \wedge 2y \geq 26 - x\}$$

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$$\text{lexmin } R = \{x \rightarrow y \mid (x \leq 25 \wedge x \geq 16 \wedge 3y \geq 31 - x \wedge 3y \leq 33 - x \wedge 2y \leq 29 - x) \vee (3y \leq 38 - x \wedge x \leq 15 \wedge x \geq 2 \wedge 2y \geq 26 - x \wedge 2y \leq 27 - x)\}$$

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Parametric integer linear programming computes $\text{lexmin } R$ in the form

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- explicit representation of existentially quantified variables
- explicit representation of range variables

Technique: dual simplex + Gomory cuts

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- explicit representation of existentially quantified variables
- **explicit representation of range variables**

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PILP Example: Dataflow Analysis

Given a read from an array element, what was the last write to the same array element before the read?

Simple case: array written through a single access

```
for (i = 0; i < N; ++i)
  for (j = 0; j < N - i; ++j)
    a[i+j] = f(a[i+j]);
for (i = 0; i < N; ++i)
  Write(a[i]);
```

PILP Example: Dataflow Analysis

*Given a read from an array element, what was the last write to the **same array element** before the read?*

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Access relations:

$$A_1 = \{(i, j) \rightarrow (i + j) \mid 0 \leq i < N \wedge 0 \leq j < N - i\}$$

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Map to all writes: $R' = A_1^{-1} \circ A_2 = \{(i) \rightarrow (i', i - i') \mid 0 \leq i' \leq i < N\}$

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In general: impose lexicographical order on shared iterators

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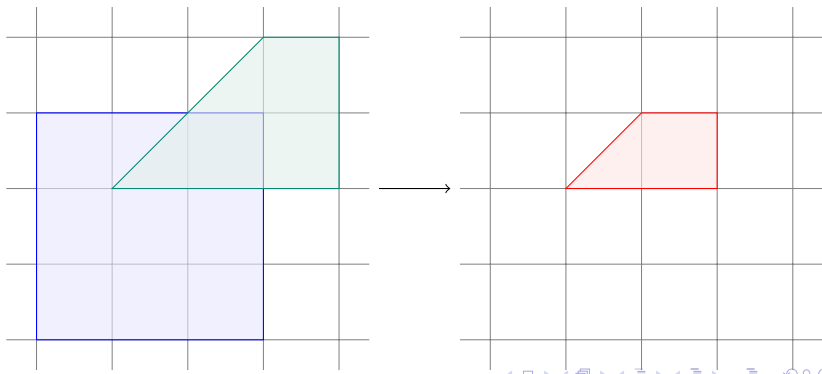
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
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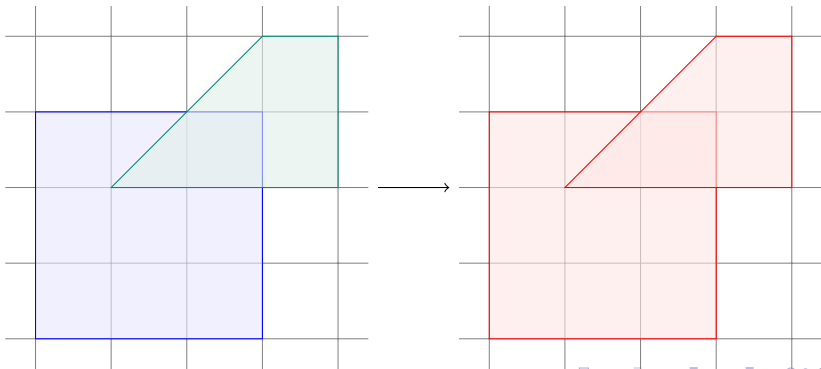
Supported Operations

- Intersection





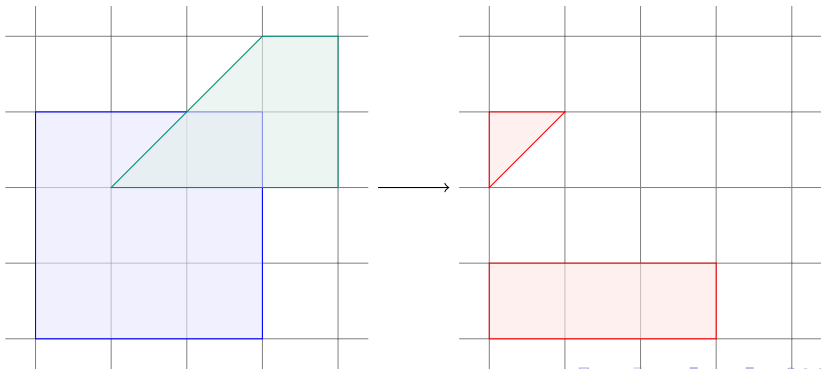
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Supported Operations

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- Union 
- Set difference



is1 Operation: Set Difference

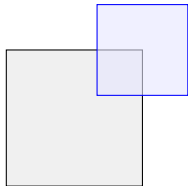
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Set difference $S_1 \setminus S_2$

- no existentially quantified variables

$$S_2(\mathbf{s}) = \{ \mathbf{x} \in \mathbb{Z}^d \mid \bigwedge_i \langle \mathbf{a}_i, \mathbf{x} \rangle + \langle \mathbf{b}_i, \mathbf{s} \rangle \geq c_i \}$$

$$S_1 \setminus S_2 = \bigcup_i (S_1 \cap \{ \mathbf{x} \mid \neg(\langle \mathbf{a}_i, \mathbf{x} \rangle + \langle \mathbf{b}_i, \mathbf{s} \rangle \geq c_i) \})$$



is1 Operation: Set Difference

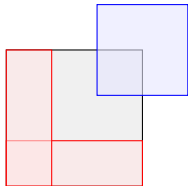
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$$\begin{aligned} S_1 \setminus S_2 &= \bigcup_i (S_1 \cap \{ \mathbf{x} \mid \neg(\langle \mathbf{a}_i, \mathbf{x} \rangle + \langle \mathbf{b}_i, \mathbf{s} \rangle \geq c_i) \}) \\ &= \bigcup_i (S_1 \cap \{ \mathbf{x} \mid \langle \mathbf{a}_i, \mathbf{x} \rangle + \langle \mathbf{b}_i, \mathbf{s} \rangle \leq c_i - 1 \}) \end{aligned}$$



is1 Operation: Set Difference

$$S(\mathbf{s}) = \{ \mathbf{x} \in \mathbb{Z}^d \mid \exists \mathbf{z} \in \mathbb{Z}^e : \mathbf{A}\mathbf{x} + \mathbf{B}\mathbf{s} + \mathbf{D}\mathbf{z} \geq \mathbf{c} \}$$

Set difference $S_1 \setminus S_2$

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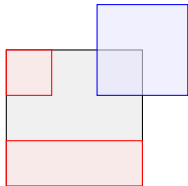
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

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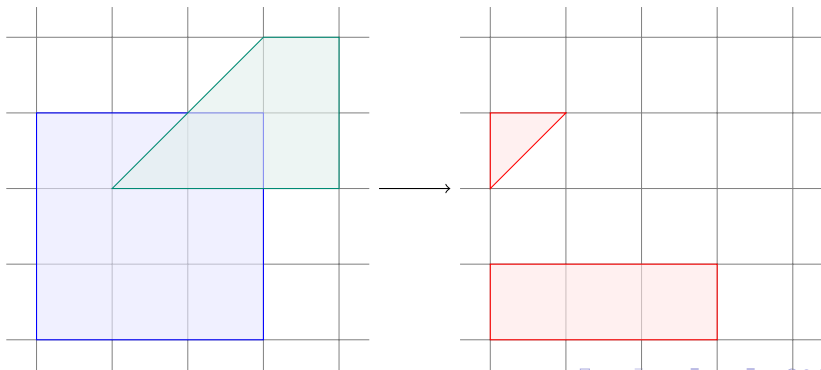
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- with existentially quantified variables
 \Rightarrow compute explicit representation




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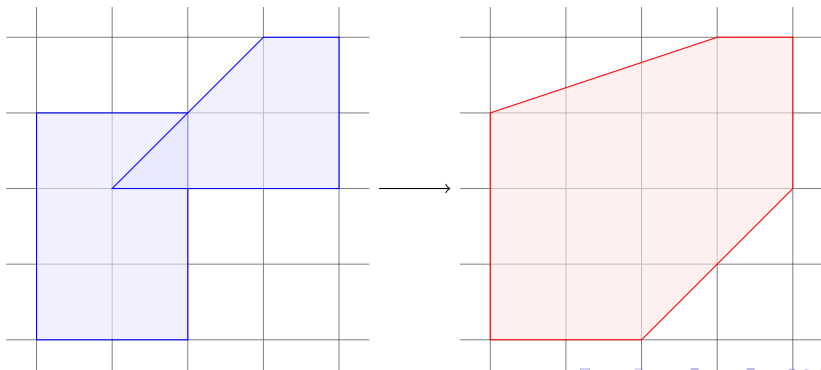
Supported Operations

- Intersection 
- Union 
- Set difference







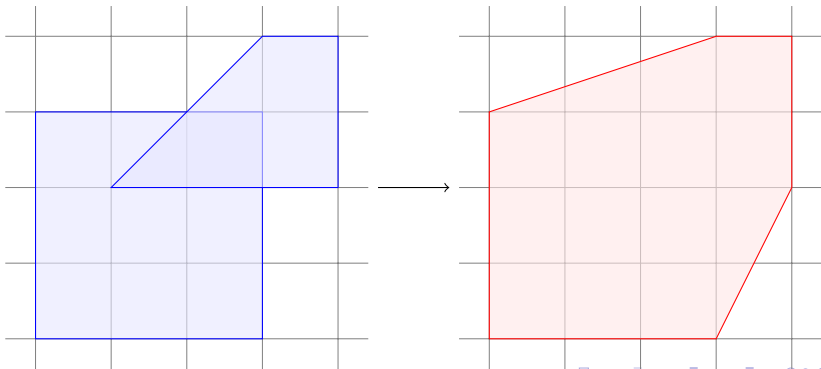
Supported Operations

- Intersection 
- Union 
- Set difference 
- Closed convex hull (“wrapping”, FLL2000)



Supported Operations

- Intersection 
- Union 
- Set difference 
- Closed convex hull ("wrapping", FLL2000) 
- Coalescing



isl Operation: Set Coalescing

After many applications of projection, set difference, union,
a set may be represented as a union of many basic sets
⇒ try to combine several basic sets into a single basic set

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PolyLib way:

- 1 Compute $H = \text{conv.hull}(S_1 \cup S_2)$
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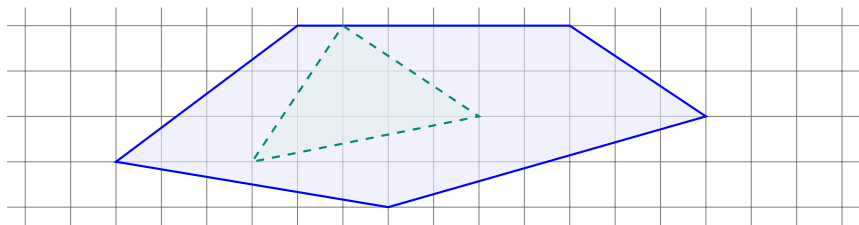
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2 Case distinction

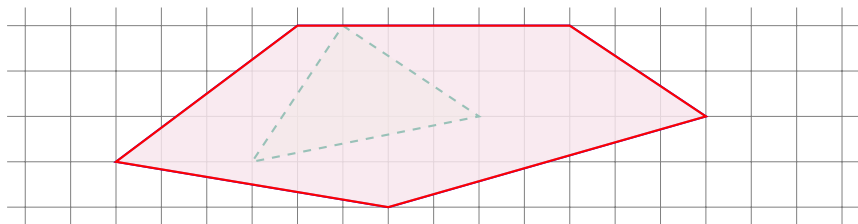
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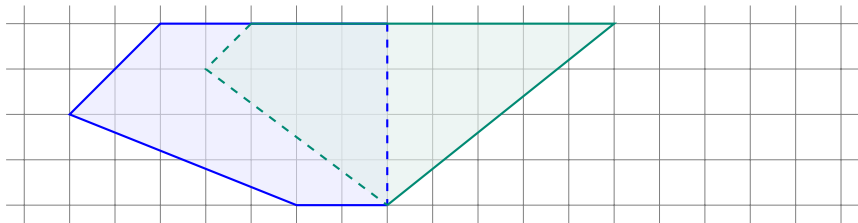
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 \Rightarrow replace S_1 and S_2 by basic set with all valid constraints

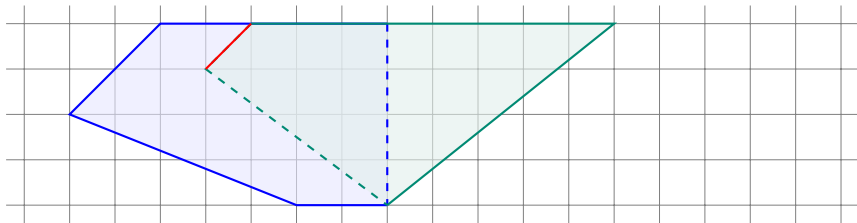
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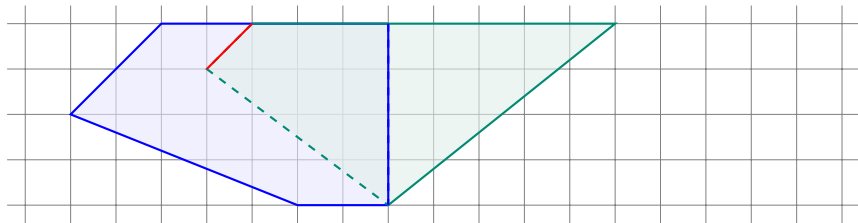
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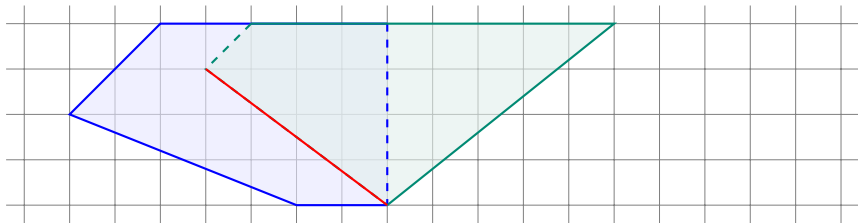
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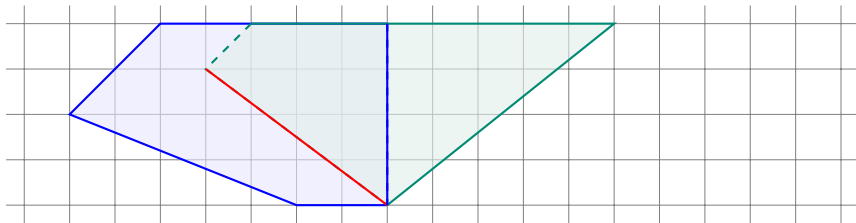
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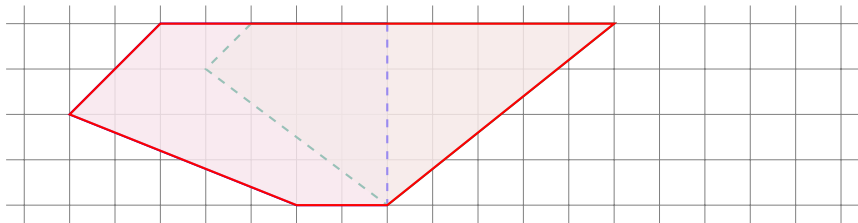
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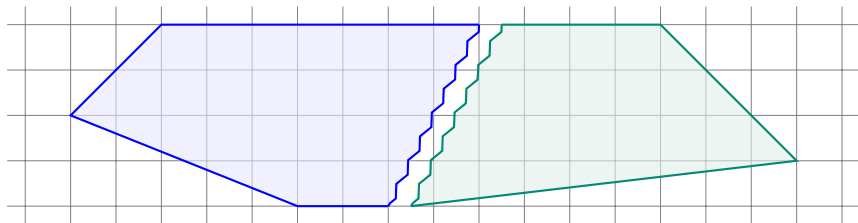
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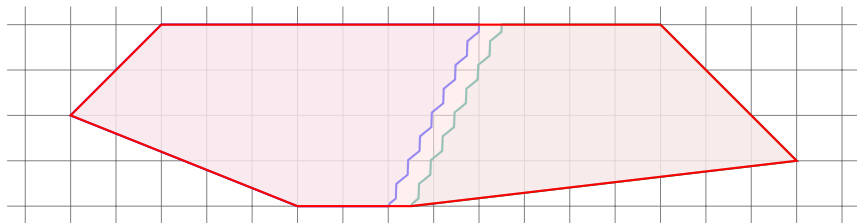
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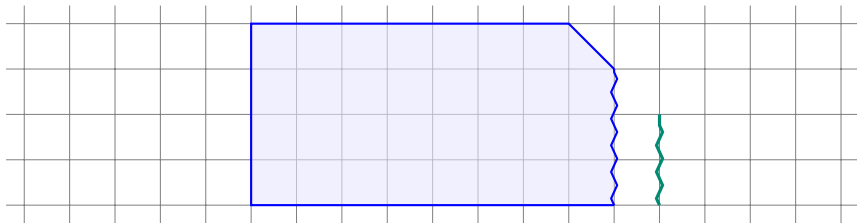
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 - \Rightarrow drop S_2 and relax adjacent inequality of S_1

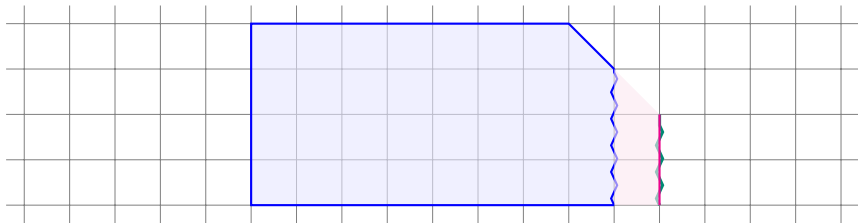
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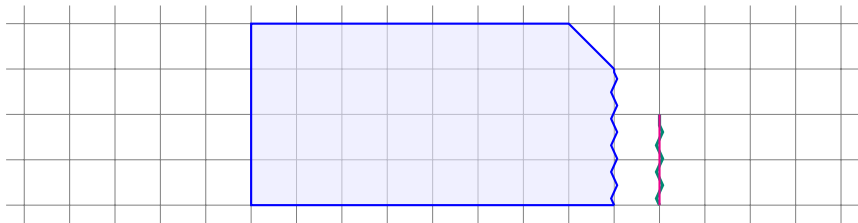
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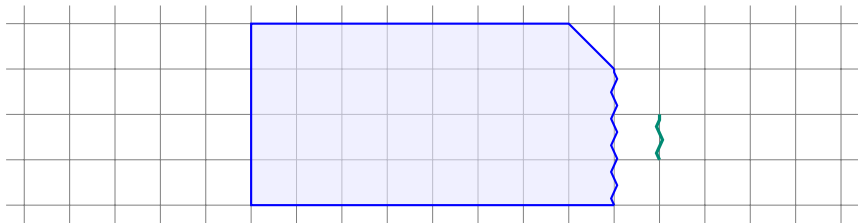
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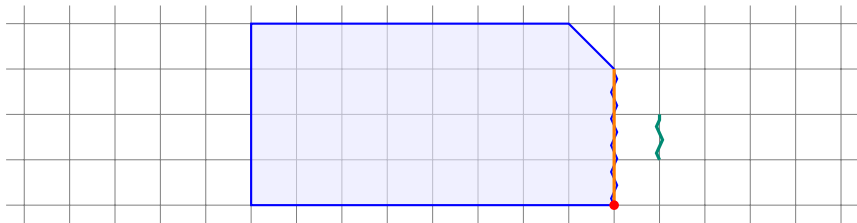
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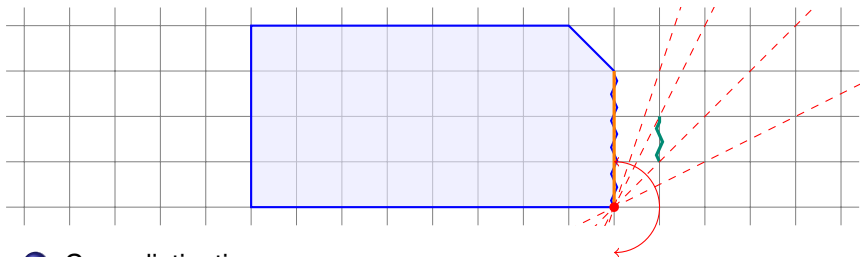
is1 Operation: Set Coalescing



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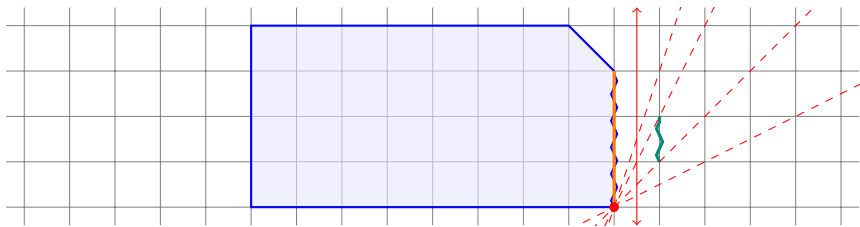
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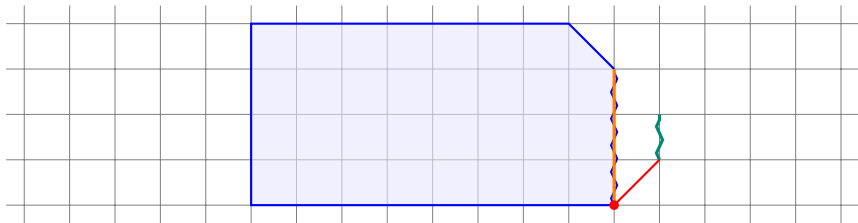
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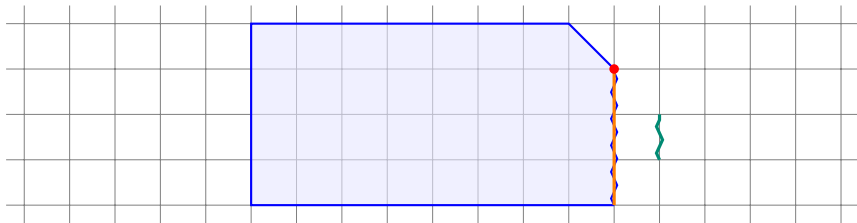
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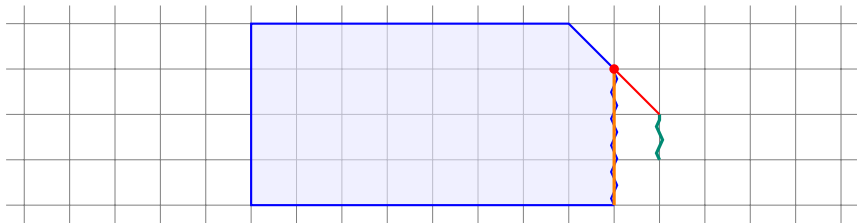
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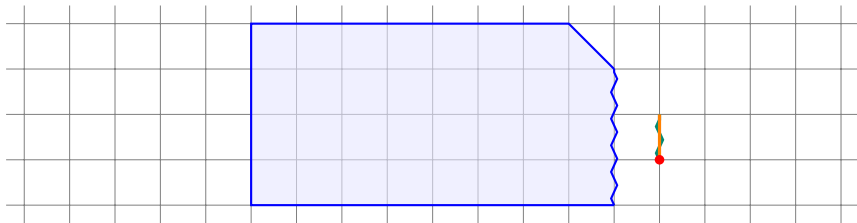
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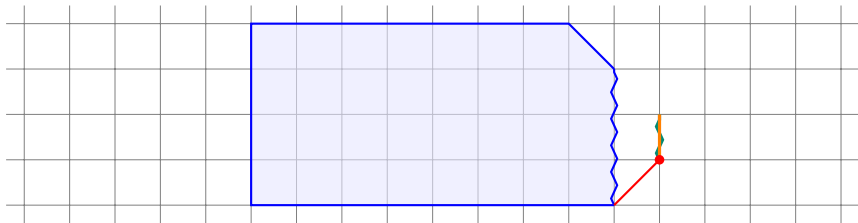
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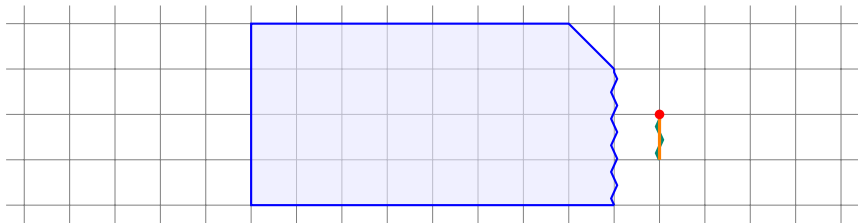
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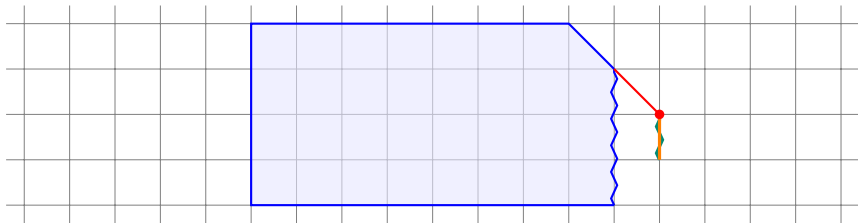
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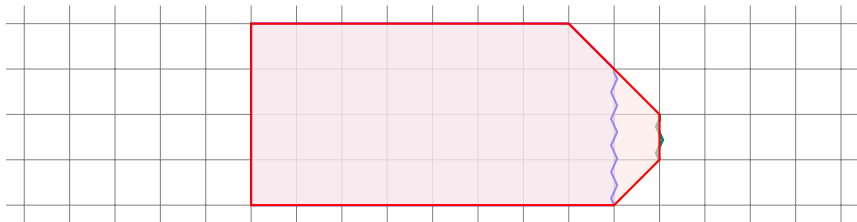
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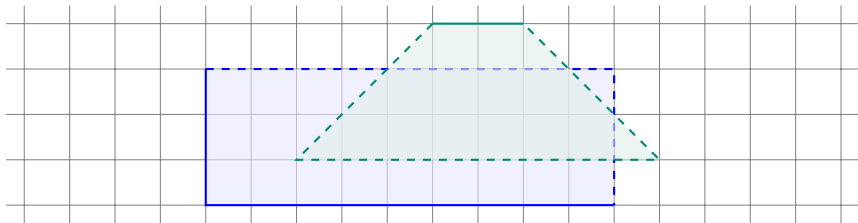
1 Classify constraints

- ▶ redundant: $\min \langle \mathbf{a}_i, \mathbf{x} \rangle > c_i - 1$ over remaining constraints
 - ▶ valid: $\min \langle \mathbf{a}_i, \mathbf{x} \rangle > c_i - 1$ over S_2
 - ▶ separating: $\max \langle \mathbf{a}_i, \mathbf{x} \rangle < c_i$ over S_2
- special cases:
- ★ adjacent to equality: $\langle \mathbf{a}_i, \mathbf{x} \rangle = c_i - 1$ over S_2
 - ★ adjacent to inequality: $\langle (\mathbf{a}_i + \mathbf{b}_j), \mathbf{x} \rangle = (c_i + d_j) - 1$ over S_2
- ▶ cut: otherwise

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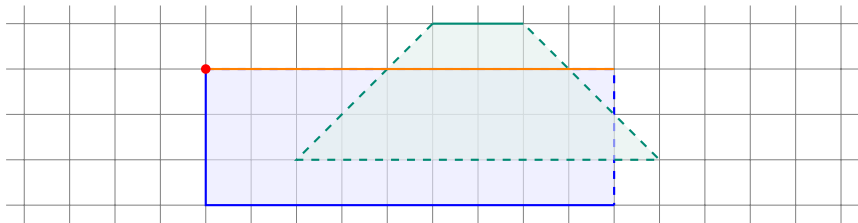
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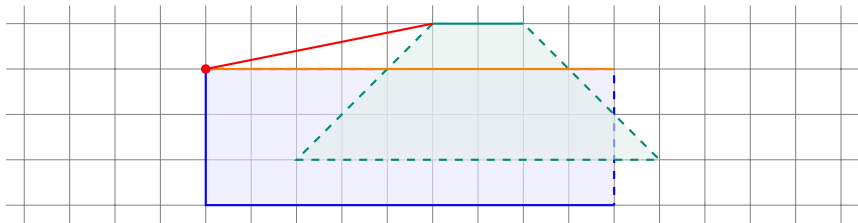
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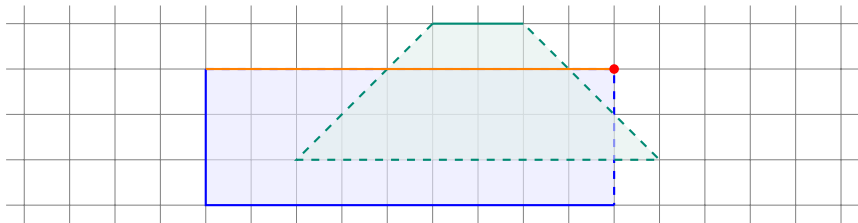
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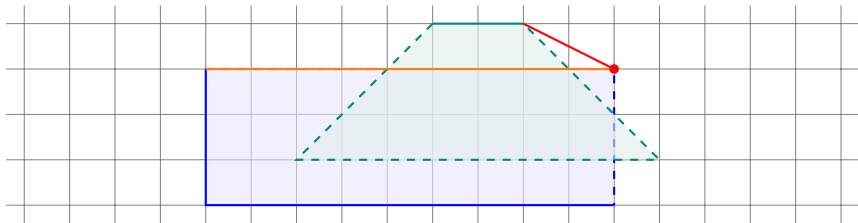
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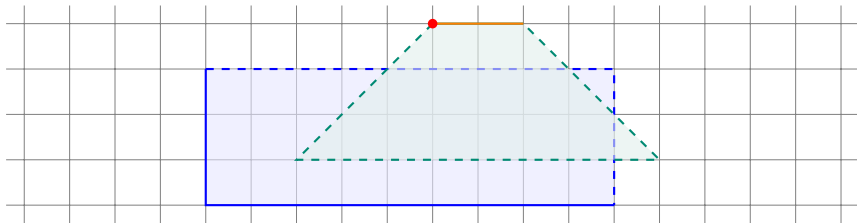
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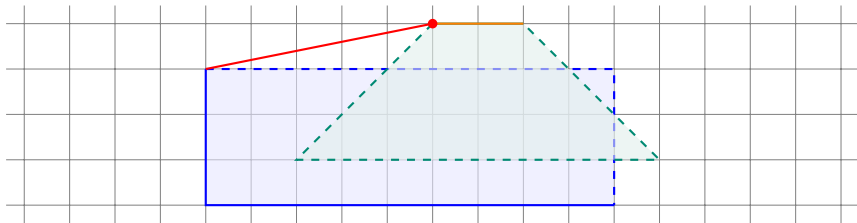
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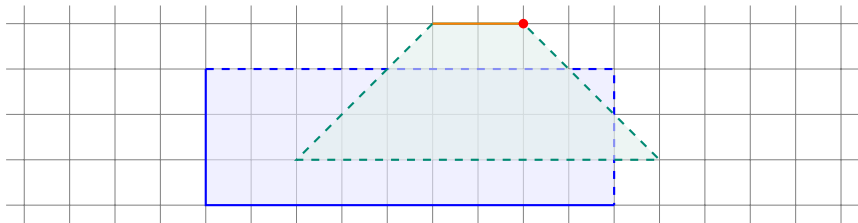
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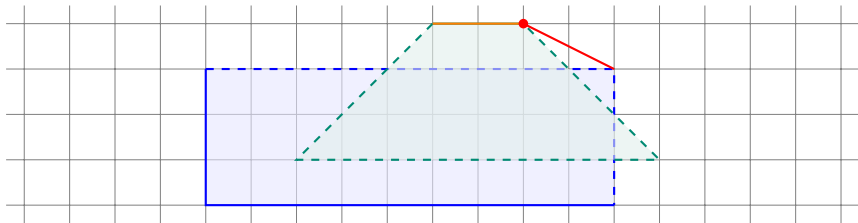
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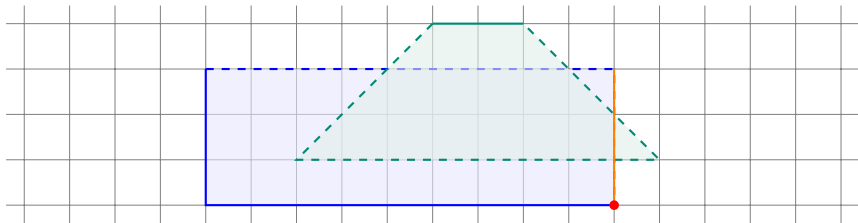
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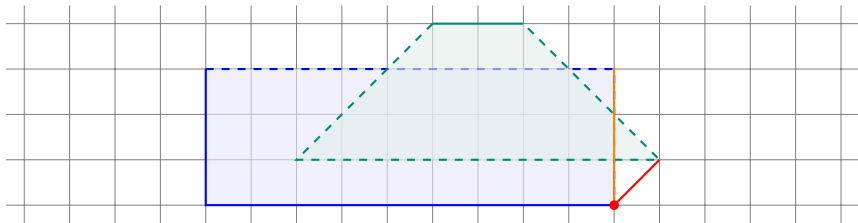
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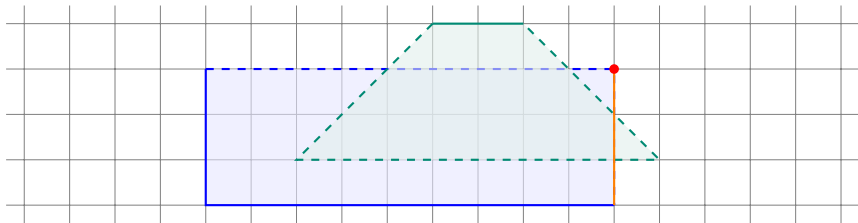
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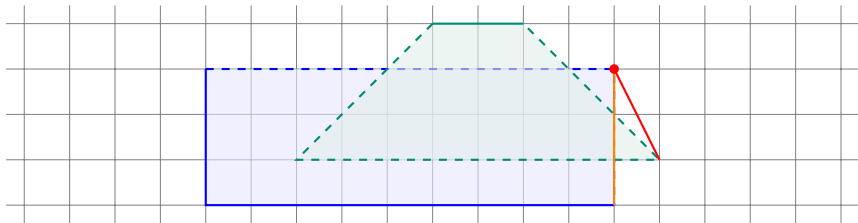
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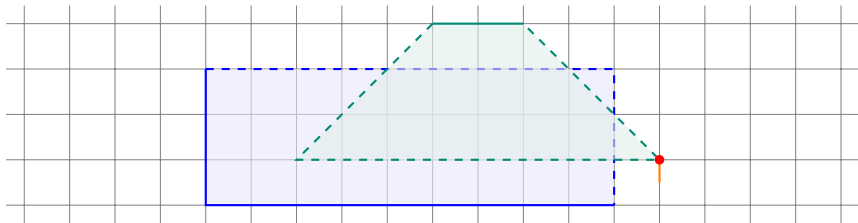
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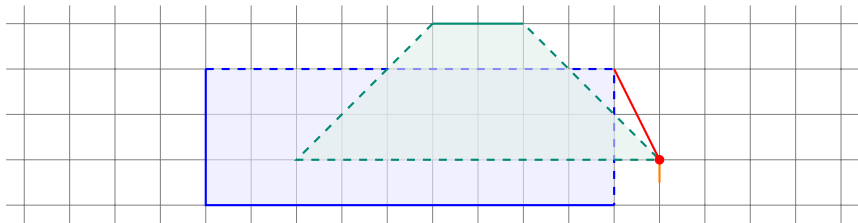
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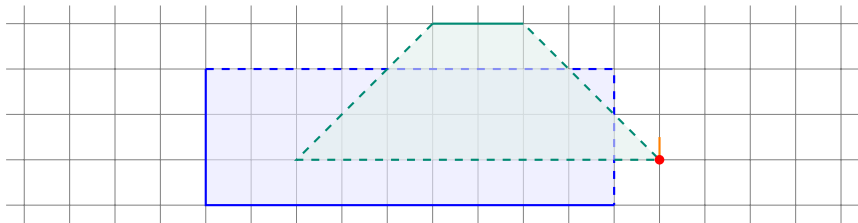
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- 6 S_2 extends beyond S_1 by at most one and all cut constraints of S_1 and parallel slices of S_2 can be wrapped to include union
 \Rightarrow replace S_1 and S_2 by valid and wrapping constraints

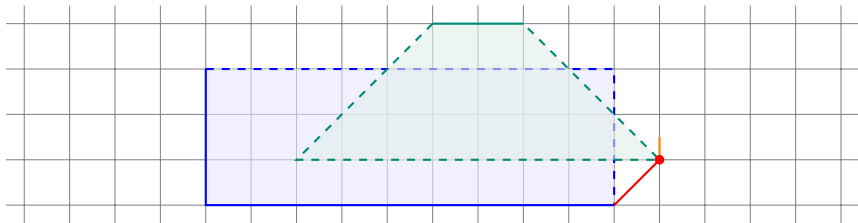
is1 Operation: Set Coalescing



② Case distinction

- ① non-redundant constraints of S_1 are valid for S_2 , i.e., $S_2 \subseteq S_1$
- ② no separating constraints and cut constraints of S_2 are valid for cut facets of S_1 (similar to BFT2001)
- ③ single pair of adjacent inequalities (other constraints valid)
- ④ single adjacent pair of an inequality (S_1) and an equality (S_2)
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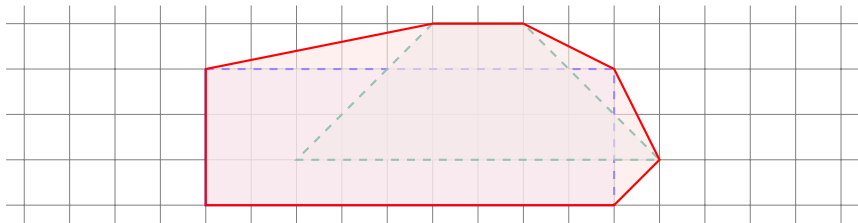
is1 Operation: Set Coalescing



2 Case distinction

- 1 non-redundant constraints of S_1 are valid for S_2 , i.e., $S_2 \subseteq S_1$
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



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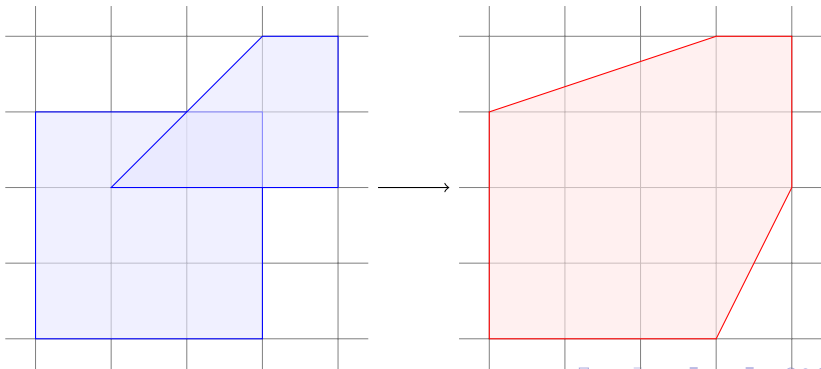


2 Case distinction






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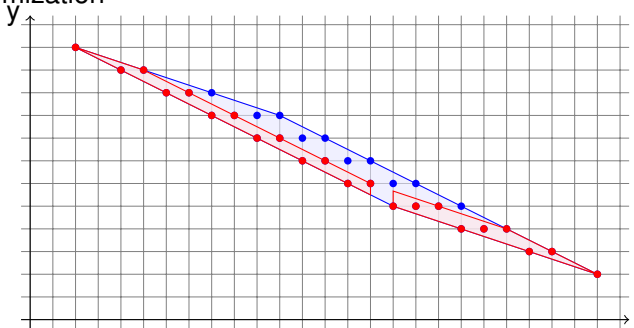
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- Closed convex hull ("wrapping", FLL2000) 
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







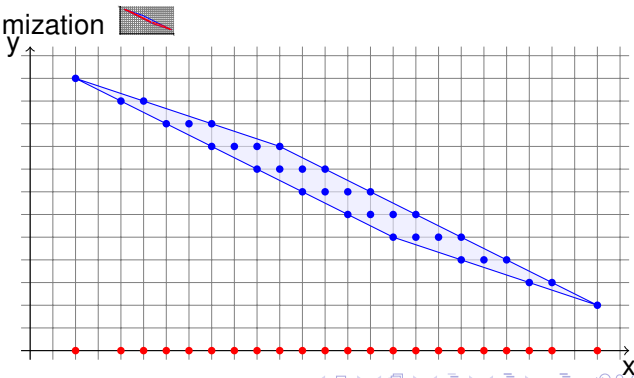
Supported Operations

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- Lexicographic minimization









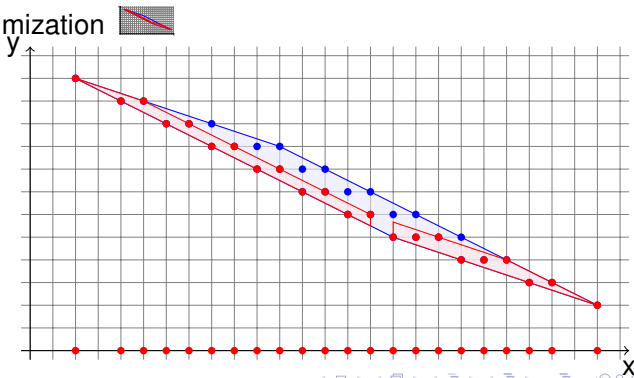
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



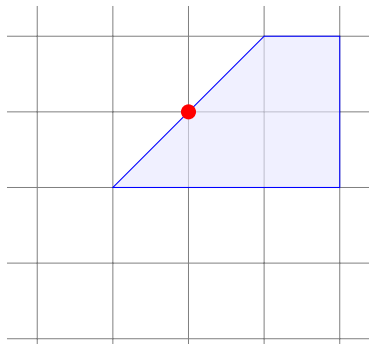
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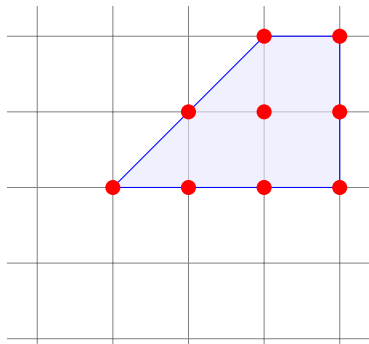
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







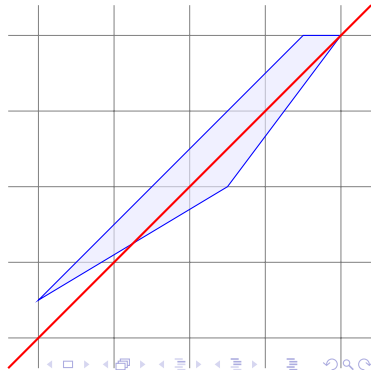
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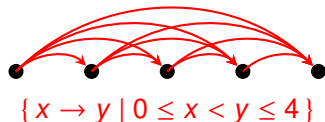
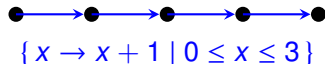
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












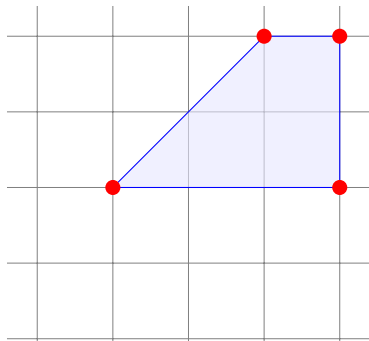
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- Integer affine hull (GBR) 
- Transitive closure (approx.)



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- Transitive closure (approx.) 
- Parametric vertex enumeration



\mathcal{H} -Parametric Polytopes and their Vertices

Polytopes described by hyperplanes that depend linearly on parameters

$$P(\mathbf{s}) = \{ \mathbf{x} \in \mathbb{Q}^d \mid A\mathbf{x} + B\mathbf{s} \geq \mathbf{c} \}$$

Example:

$$P(N) = \{ (i, j) \mid i \geq 1 \wedge i \leq N \wedge j \geq 1 \wedge j \leq i \}$$

Parametric vertices:

$$P = \text{conv.hull} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} N \\ 1 \end{bmatrix}, \begin{bmatrix} N \\ N \end{bmatrix} \right\}$$

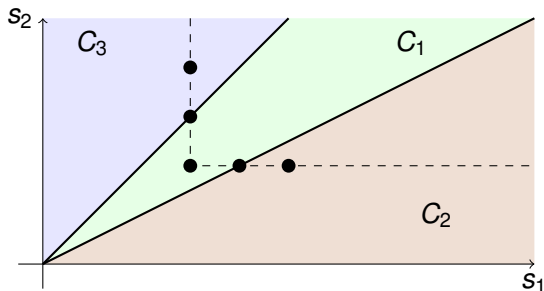
In general: different (active) vertices on different parts of the parameter space (chamber decomposition)

Chamber Decomposition

$$\left\{ \mathbf{t} \in \mathbb{Q}^2 \mid -s_1 + 2s_2 + t_1 - 2t_2 \geq 0 \wedge s_1 - s_2 - t_1 + t_2 \geq 0 \wedge t_1 \geq 0 \wedge t_2 \geq 0 \right\}$$

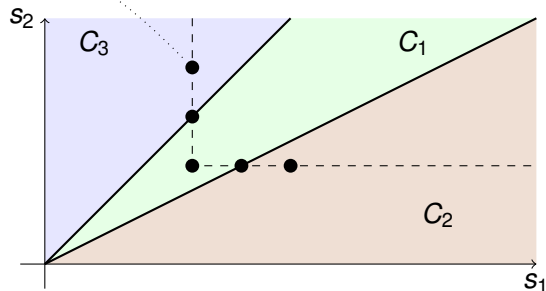
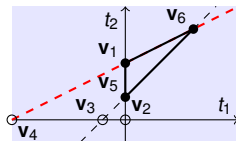
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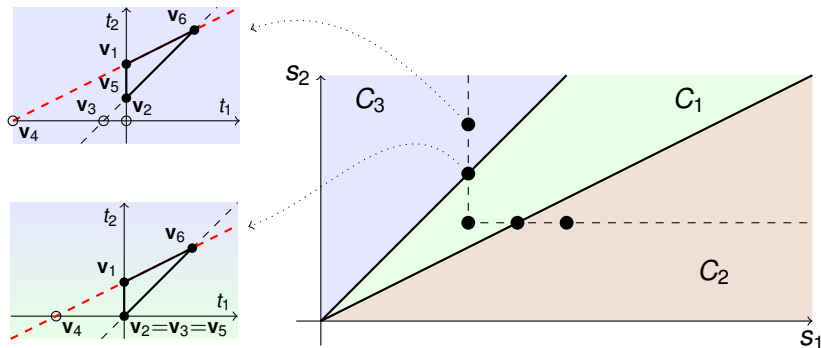
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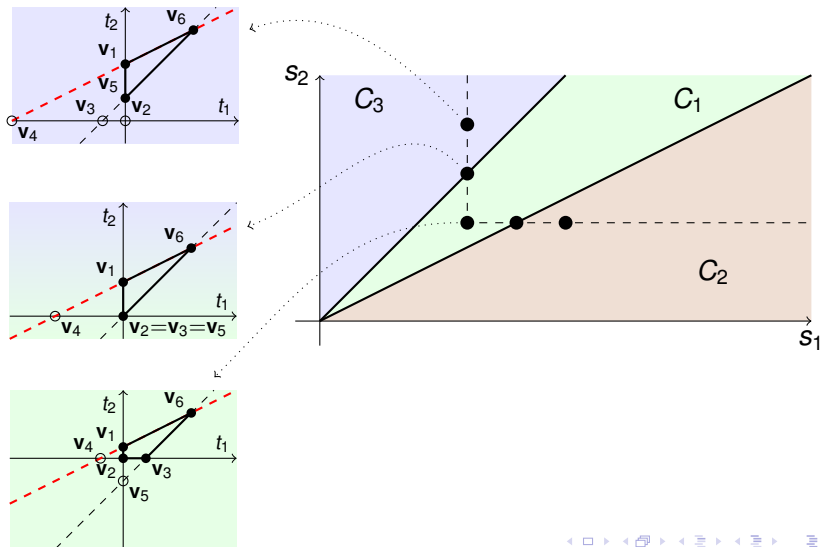
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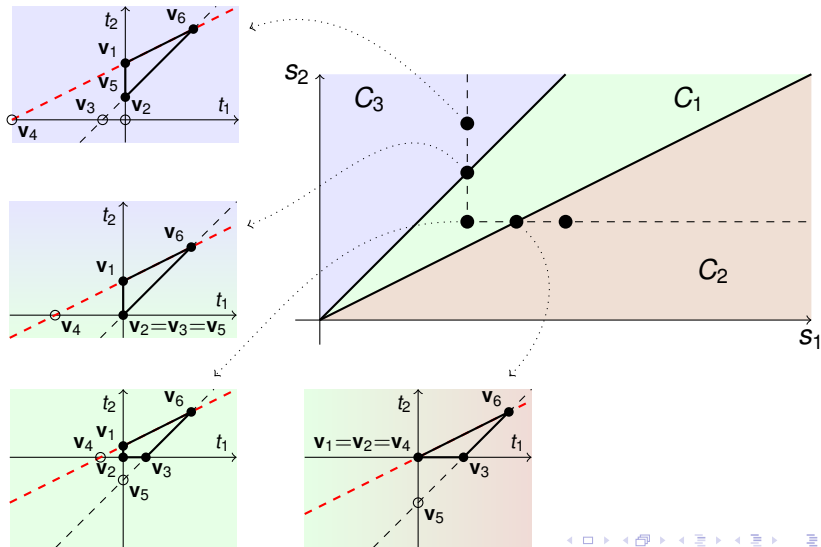
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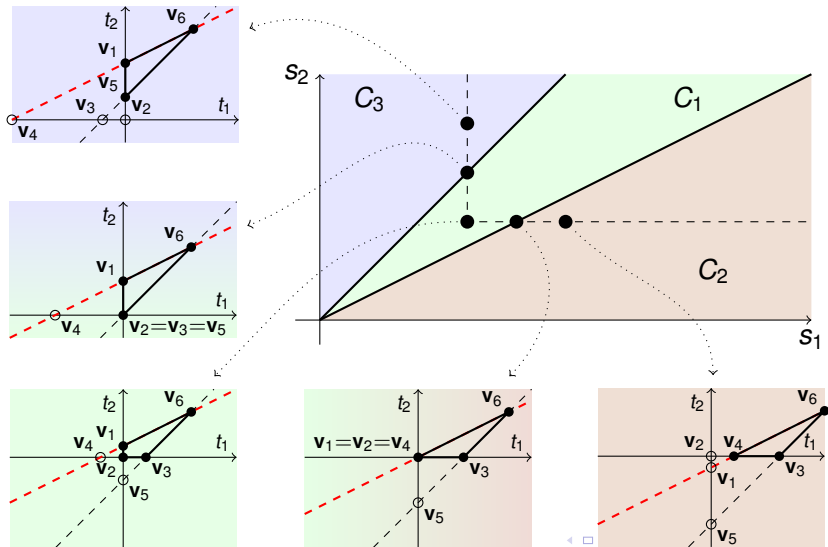
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Parametric Vertex Enumeration

- Vertex computation
 - ▶ Consider all combinations of d inequalities
 - ▶ Turn them into equalities
 - ▶ Record vertex and activity domain if non-empty

Parametric Vertex Enumeration

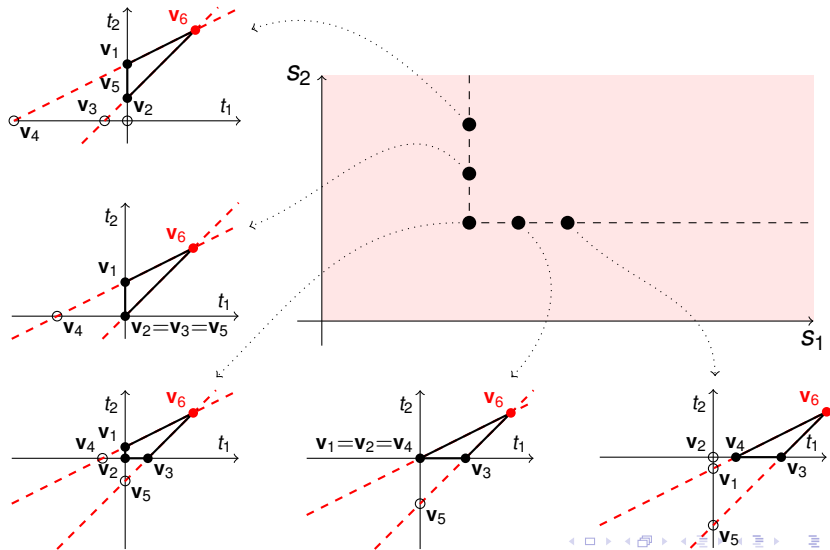
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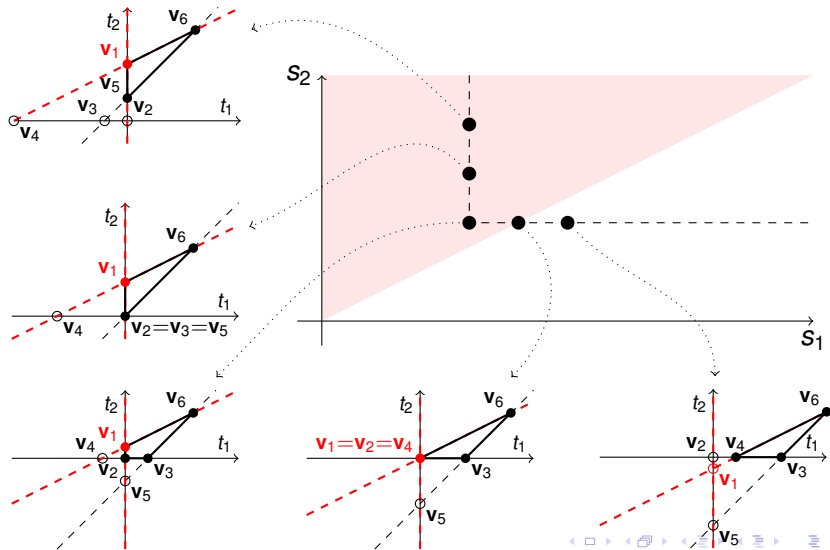
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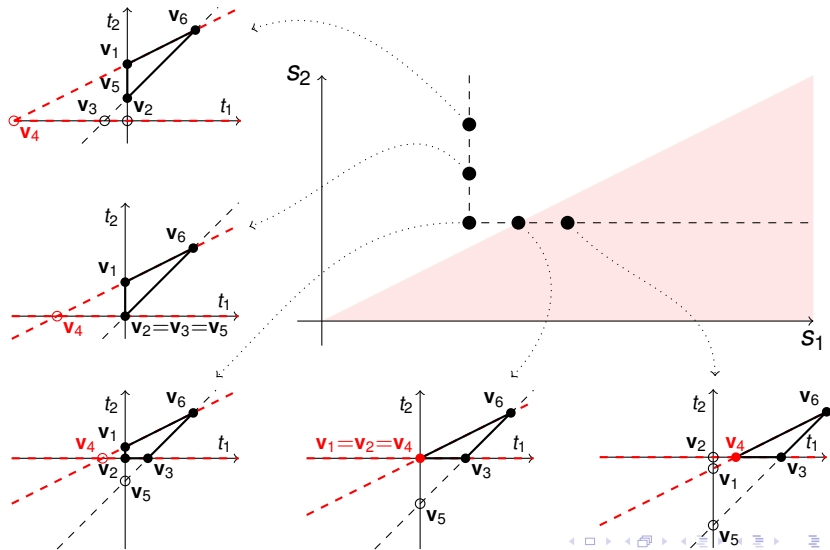
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PolyLib:
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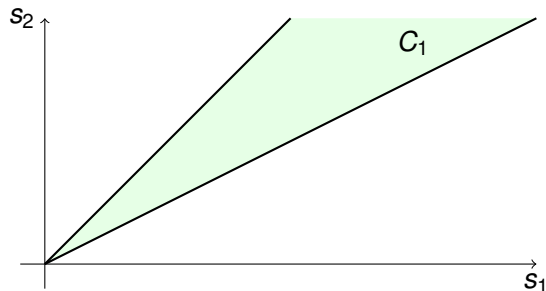
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isl:

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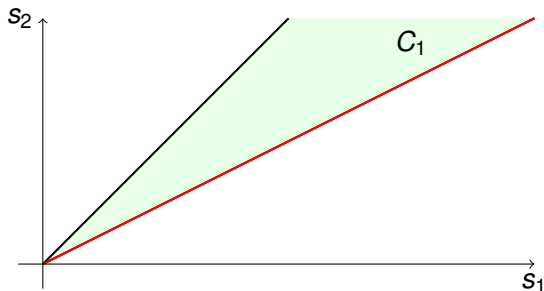
Chamber Decomposition

$$\{ \mathbf{t} \in \mathbb{Q}^2 \mid -s_1 + 2s_2 + t_1 - 2t_2 \geq 0 \wedge s_1 - s_2 - t_1 + t_2 \geq 0 \wedge t_1 \geq 0 \wedge t_2 \geq 0 \}$$



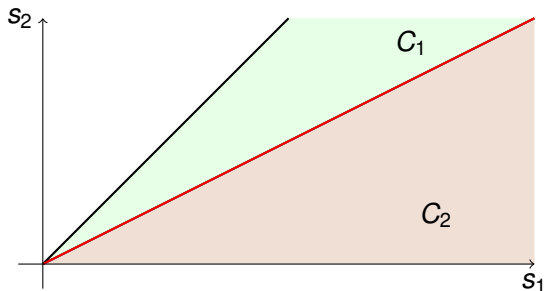
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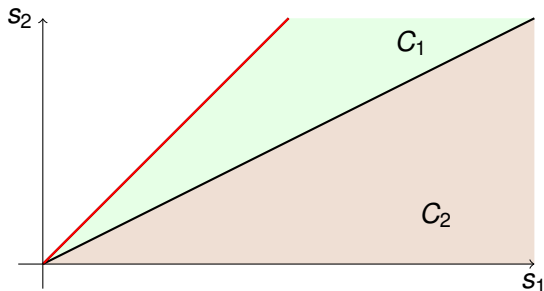
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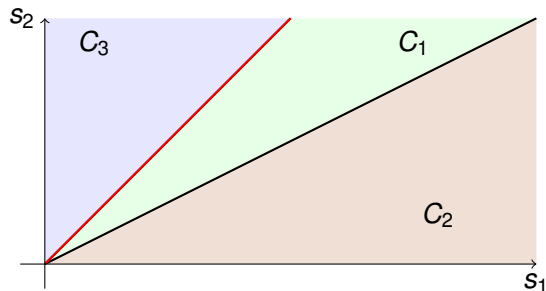
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Parametric Vertex Enumeration

- Vertex computation
 - ▶ Consider all combinations of d inequalities
 - ⇒ using backtracking and incremental LP solver
 - ▶ Turn them into equalities
 - ▶ Record vertex and activity domain if non-empty
 - ⇒ only record for lexmin inequalities
- Chamber decomposition (note: only full-dimensional chambers)

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










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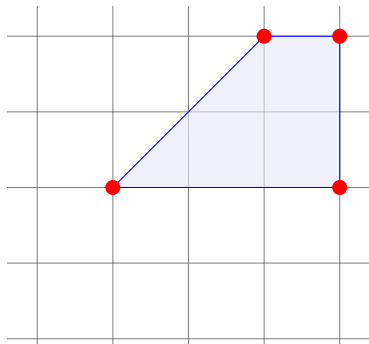
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⇒ much faster than PolyLib; similar to TOPCOM 0.16.2

Supported Operations

- Intersection 
- Union 
- Set difference 
- Closed convex hull (“wrapping”, FLL2000) 
- Coalescing 
- Lexicographic minimization 
- Integer projection 
- Sampling (GBR) 
- Scanning (GBR) 
- Integer affine hull (GBR) 
- Transitive closure (approx.) 
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- Bounds on quasipolynomials (approx.)

\mathcal{V} -Parametric Polytopes and Bounds on Polynomials

- \mathcal{V} -parametric polytopes

$$P : D \rightarrow \mathbb{Q}^n :$$

$$\mathbf{q} \mapsto P(\mathbf{q}) = \{ \mathbf{x} \mid \exists \alpha_i \in \mathbb{Q} : \mathbf{x} = \sum_i \alpha_i \mathbf{v}_i(\mathbf{q}), \alpha_i \geq 0, \sum_i \alpha_i = 1 \}$$

$D \subset \mathbb{Q}^f$: parameter domain

$\mathbf{v}_i(\mathbf{q}) \in \mathbb{Q}[\mathbf{q}]$ arbitrary polynomials in parameters

$\mathbf{v}_i(\mathbf{q})$ are generators of the polytope

Note: \mathcal{V} -parametric polytope can be computed from \mathcal{H} -parametric polytope through parameter vertex enumeration + chamber decomposition

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- Bounds on quasipolynomials (CFGV2009)

Input: Parametric polytope P and quasipolynomial $p(\mathbf{q}, \mathbf{x})$

Output: Bound $B(\mathbf{q})$ on quasipolynomial over polytope

$$B(\mathbf{q}) \geq \max_{\mathbf{x} \in P(\mathbf{q})} p(\mathbf{q}, \mathbf{x})$$

Note: \mathcal{V} -parametric polytope can be computed from \mathcal{H} -parametric polytope through parameter vertex enumeration + chamber decomposition

Bounds on Quasipolynomials: Example

$$p(x_1, x_2) = \frac{1}{2}x_1^2 + \frac{1}{2}x_1 + x_2 \quad P = \text{conv.hull}\{(0, 0), (N, 0), (N, N)\}$$

To compute:

$$M(N) = \max_{(x_1, x_2) \in P} p(x_1, x_2)$$

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How? \Rightarrow Bernstein expansion

- Express $\mathbf{x} \in P$ as convex combination of vertices

$$(x_1, x_2) = \alpha_1(0, 0) + \alpha_2(N, 0) + \alpha_3(N, N), \quad \alpha_i \geq 0, \quad \sum_i \alpha_i = 1$$

$$p(\alpha_1, \alpha_2, \alpha_3) = \frac{1}{2}N^2\alpha_2^2 + N^2\alpha_2\alpha_3 + \frac{1}{2}N^2\alpha_3^2 + \frac{1}{2}N\alpha_2 + \frac{3}{2}N\alpha_3$$

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$$p(\alpha) = \frac{N^2}{2}\alpha_2^2 + N^2\alpha_2\alpha_3 + \frac{N^2}{2}\alpha_3^2 + \frac{N}{2}\alpha_2 + \frac{3N}{2}\alpha_3 \quad \alpha_i \geq 0, \quad \sum_i \alpha_i = 1$$

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- 1 Introduction
- 2 Internals
- 3 Operations
 - Set Difference
 - Set Coalescing
 - Parametric Vertex Enumeration
 - Bounds on Quasi-Polynomials
- 4 Conclusion

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- currently used in
 - equivalence checking tool
 - barvinok
 - CLooG
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Future work: port `barvinok` to `isl`; now uses

- `PolyLib`: GPL, ...
 - ⇒ `isl` already supports operations provided by `PolyLib`, but a lot of code still needs to be ported
- `NTL`: not thread-safe, C++
 - ⇒ `isl` needs LLL