

1 **The forearm and hand musculature of terrestrial rhesus macaques (*Macaca mulatta*) and arboreal**
2 **gibbons(*fam. Hylobatidae*). Part I. Description and comparison of the muscle configuration.**

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6

7 Short title: forearm and hand musculature of gibbons and rhesus macaques

8 Abstract

9 Primates live in very diverse environments and, as a consequence, show an equally diverse locomotor
10 behaviour. During locomotion, the primate hand interacts with the superstrate and/or substrate and will
11 therefore probably show adaptive signals linked with this locomotor behaviour. While the morphology
12 of the forearm and hand bones have been studied extensively, the functional adaptations in the hand
13 musculature have been documented only scarcely. To evaluate if there are potential adaptations in
14 forelimb musculature to locomotor behaviour, we investigated the the forearm and hand musculature of
15 the highly arboreal gibbons (including *Hylobates lar*, *Hylobates pileatus*, *Nomascus leucogenys*,
16 *Nomascus concolor*, *Symphalangus syndactylus*) and compared this with the musculature of the
17 predominantly terrestrial rhesus macaques (*Macaca mulatta*) by performing complete and detailed
18 dissections on a sample of fifteen unembalmed specimens. We found that the overall configuration of
19 the upper arm and hand musculature is highly comparable between arboreal gibbons and terrestrial
20 macaques, and follows the general primate condition. Most of the identified differences in muscle
21 configuration are located in the forearm. In macaques, a prominent *m. epitrochleoanconeus* is present,
22 which potentially helps to extend the forearm and/or stabilize the elbow joint during quadrupedal
23 walking. The *m. flexor carpi radialis* shows a more radial insertion in gibbons, which might be
24 advantageous during brachiation as it can aid radial deviation. The fingers of macaques are controlled
25 in pairs by the *m. extensor digiti secundi et tertii proprius* and the *m. extensor digiti quarti et quinti*
26 *proprius* – a similar organization can also be found in their flexors – which might aid in efficient
27 positioning of the hand and fingers on uneven substrates during quadrupedal walking. In contrast,
28 extension of the little finger in gibbons is controlled by a separate *m. extensor digiti minimi*, while digits
29 2 to 4 are extended by the *m. extensor digitorum brevis*, suggesting that simultaneous extension of digits
30 2-4 in gibbons might be important when reaching or grasping an overhead support during brachiation.
31 In conclusion, the overall configuration of the forelimb and hand musculature is very similar in gibbons
32 and macaques with some peculiarities which can be linked to differences in forelimb function and which
33 might be related to the specific locomotor behavior of each group.

34

35 Keywords: primates, anatomy, hylobatids, macaques, locomotion, adaptation

36 **Introduction**

37 The primate hand displays a large variety of phenotypes which reflects an equally diverse functional
38 repertoire (Horn, 1972; Vereecke, D’Août and Aerts, 2006; Marzke, 2009; Williams, 2010; Almécija,
39 Smaers and Jungers, 2015; Liu, Xiong and Hu, 2016; Thompson *et al.*, 2018). Understanding how these
40 phenotypes correlate to different locomotor behaviours of distinct primate taxa may facilitate the
41 interpretation of hand function from primate fossil remains. Nonhuman primates use their hands for
42 manipulation as well as for locomotion, and adaptive signals to these specific functions in the
43 morphology of the forearm and hand bones have been studied extensively. For example, gibbons have
44 a large wrist mobility in all directions as a potential adaptation to suspensory locomotion (Richmond,
45 2001), which is associated with a ball-and-socket configuration of the midcarpal joint (Lemelin and
46 Schmitt, 1998; Orr *et al.*, 2010; McMahon, Zijl and Gilad, 2015; Prime and Ford, 2016; Orr, 2017,
47 2018). In macaques, the articular surface of the basal manual phalanges is proximodorsally excavated
48 to enable hyperextension, which is a specialization for digitigrade locomotion (Hayama, Chatani and
49 Nakatsukasa, 1994; Lemelin and Schmitt, 1998). In addition, macaques have a broad midcarpal joint
50 morphology which is interpreted as being advantageous for loading during quadrupedal walking (Lewis,
51 1985; Lemelin and Schmitt, 1998; Richmond, 2001; Daver, Berillon and Grimaud-Hervé, 2012). These
52 previous studies focused on adaptations in skeletal morphology, while functional adaptations in the hand
53 musculature have been documented only scarcely. Detailed descriptions of forelimb musculature in
54 different primate taxa, as well as comparative analyses between those taxa, are limited in the current
55 literature (Tuttle, 1967, 1969; Lemelin and Diogo, 2016). In 2009, Michilsens *et al.* conducted a study
56 on the functional anatomy of the gibbon forelimb, with a detailed account on the upper and lower arm
57 musculature in four different gibbon species (*Hylobates lar*, *H. pileatus*, *H. moloch*, *Symphalangus*
58 *syndactylus*; n=11)(Michilsens *et al.*, 2009). Here, we extend this dataset with eight gibbon specimens
59 (*H. lar*, *H. pileatus*, *Nomascus concolor*, *N. leucogenys*, *S. syndactylus*) and also include detailed
60 information on intrinsic hand musculature. In addition, we compare the forelimb muscle configuration
61 of the highly arboreal gibbons with that of the predominantly terrestrial macaques (Fam.
62 *Cercopithecidea*) to evaluate if there are specific adaptations in forelimb musculature that could be

63 related to locomotor behaviour. A full quantification of the forelimb and hand musculature in both
64 primate taxa will be presented as Part 2 of this study.

65 **Methods**

66 *Specimen collection*

67 As multiple species of the hylobatid family are included in this study, they are further referred to as
68 “gibbons”. The forearm and hand of eight (sub)adult gibbons were obtained via collaborations with
69 different European Zoos and institutes: the National Museum of Scotland (Edinburgh, UK), Ghent
70 University (campus Merelbeke, Belgium), the Zoological and Botanical Park of Mulhouse (France),
71 Pakawi Park (Belgium). The forearm and hand of seven adult rhesus macaques were obtained via
72 collaboration with the Ghent University (campus Merelbeke, Belgium) and KU Leuven (campus
73 Gasthuisberg, Belgium). All specimens were collected opportunistically, no animals were sacrificed for
74 this study. The forelimbs were disarticulated at level of the shoulder in all specimens. Full specimen
75 details are provided in **Table 1**.

76 *Dissection procedure*

77 The specimens were stored at -18°C and were thawed at room temperature 24h prior to the dissections.
78 A complete dissection of the left or right forearm and hand was performed for all specimens (unilateral
79 sampling). All muscles were isolated one by one and their origins and insertions were documented and
80 compared to previous studies (Tuttle, 1969; Gibbs, Collard and Wood, 2002; Michilsens *et al.*, 2009;
81 Diogo and Wood, 2012; Aversi-Ferreira *et al.*, 2016; van Leeuwen *et al.*, 2018). Presence or absence of
82 muscles or abnormalities were also noted. The dissections were documented extensively using a
83 dedicated photography setup. Some specimens were skinned prior to transport to the university, which
84 caused damage to the thenar and hypothenar muscles, and/or the tendons of the extrinsic muscles in
85 some specimens (see **Table 1**).

86 **Results**

87 *Documentation of gibbon and rhesus macaque forearm and hand musculature*

88 The description of the extrinsic and intrinsic hand muscles discussed below are based on detailed
89 dissections of a macaque (n=7) and gibbon (n=8) sample. As some specimens were damaged, either due
90 to skinning or the dislocation at the level of the shoulder, the number of included specimens varies for
91 each muscle. The exact number of specimens is shown each time between parentheses. Details on the
92 origin and insertion of all extrinsic and intrinsic muscles are listed in the Supplementary material (**Table**
93 **S1**). Anatomical data on bonobos and humans from previous dissections are also added for comparison
94 (van Leeuwen *et al.*, 2018).

95

96 Upper arm musculature

97 The long head of the *m. biceps brachii* (Bb) originates from the supraglenoid tubercle of the scapula
98 (11/11) and inserts onto the radial tuberosity (14/14) in all macaque and gibbon specimens. In macaques,
99 the short head originates from the coracoid process of the scapula, similar as in modern humans and
100 most other primates, and fuses with the muscle belly of the long head (6/6). In gibbons, however, the
101 short head originates from the crest of the lesser tubercle of the humerus (7/7) and inserts on the bicipital
102 aponeurosis into the deep fascia on the medial forearm (connection with FDS) (8/8). This supports
103 previous findings that in most primates both the long head and short head of the Bb cross the shoulder
104 joint, while in gibbons only the long head crosses the shoulder (Jungers and Stern, 1980; Michilsens *et*
105 *al.*, 2009). The short head works as an elbow flexor and forearm supinator, without action at the shoulder
106 joint. This could imply that the humeral flexion capacity of the Bb is reduced in gibbons compared to
107 macaques and other primates with a bi-articular configuration of the short head of the Bb. In gibbons,
108 the short head of the Bb forms a ventral muscle chain between the *m. pectoralis major* (PM) and *m.*
109 *flexor digitorum superficialis* (FDS) (see (Jungers and Stern, 1980)). The fusion between these multiple-
110 joint muscles is thought to conduct the flexor force of the PM distally across the shoulder, elbow, and
111 wrist joints so that active or passive tension in this muscle results in automatic flexion of the forearm
112 and fingers without requiring activity in the distal muscles of the chain. While such ventral muscle chain

113 would indeed be advantageous for brachiating gibbons, the function of this chain remains debated
114 (Jungers and Stern, 1980; Michilzens *et al.*, 2009).

115

116 The *m. triceps brachii* (Tb) consists of three heads in all specimens (15/15). The Tb originates from the
117 infraglenoid tubercle of the scapula (long head) (12/12) and the humeral shaft (lateral and medial head)
118 (14/14), and inserts onto the oleocranon (14/14). In most macaques the long and medial head are
119 completely separate (5/6), while in all gibbons, the three heads are fused at the insertion (8/8), which is
120 also seen in modern humans. In macaques, the Tb is an important muscle during quadrupedal walking
121 as it produces the torque at the elbow joint during the first three-fourths of the step (Manter, 1938).
122 During brachiation in gibbons, the Tb will probably primarily act at the shoulder (Michilzens *et al.*,
123 2009).

124

125 The *m. dorso-epitrochlearis* (DET) originates in both macaques and gibbons from the muscle belly of
126 the *m. latissimus dorsi* (12/12), yet the insertion is variable. The DET inserts onto the oleocranon and
127 the fascia of Bb and Tb in all macaques (6/6) and some gibbons (3/8), but in most gibbons it inserts via
128 a tendon sheet onto the medial epicondyle of the humerus (5/8). The DET, clearly present in both
129 macaques and gibbons, is rarely seen in humans (Cheng and Scott, 2000) as fewer than 30 cases have
130 been reported over the past 200 years (Natsis *et al.*, 2012). The function of the DET is still debated as it
131 has long been speculated to facilitate force transmission from the shoulder to the fingertips by acting as
132 a dorsal muscle chain (Sonntag, 1922; Andrews and Groves, 1976). However, EMG studies have shown
133 that the DET might only be a morphological consequence of the rearrangement of the origin of the short
134 head of the Bb (Jungers and Stern, 1980). The DET has also been labeled as a “climbing muscle” because
135 of its connection with the *m. latissimus dorsi* as fusion of these muscles contributes to increased
136 concerted contraction (Sonntag, 1922).

137

138 The *m. brachialis* (B) originates from the distal half (13/14) or complete (1/14) shaft of the humerus and
139 inserts onto the tuberosity of the ulna (14/14). Occasional fusion with the *m. supinator* (SUP) in

140 macaques (1/6) or with the *m. pronator teres* (PT) in gibbons (1/8) can occur. It is considered a pure
141 elbow flexor in primates, including humans.

142

143 The *m. coracobrachialis* (CB) consists of a long (middle) and medial (deep) head in macaques (6/6) (cf.
144 (Aversi-Ferreira *et al.*, 2016)). Both heads originate from the coracoid process of the scapula and the
145 common coracoid tendon (6/6), and the long head is always fused with the short head of the Bb (6/6).
146 The long head inserts midway on the humeral shaft (6/6) and the medial head inserts more proximally,
147 onto the surgical neck of the humerus (6/6). In gibbons, the CB shows a one-headed configuration
148 similar to modern humans, originating from the coracoid process of the scapula (7/7) and a direct, muscle
149 fiber insertion onto the periosteum of the proximal (1/8) or middle (7/8) humeral shaft. In macaques, the
150 two-headed configuration might increase internal rotation and adduction of the arm during quadrupedal
151 walking (Aversi-Ferreira *et al.*, 2016).

152

153 The *m. epitrochleoanconeus* (ETA) is an separate, well-defined muscle in macaques, that originates
154 from the medial epicondyle of the humerus and inserts onto the medial border of the oleocranon (7/7)
155 (**Fig. 1**). A well-developed ETA is absent in gibbons (8/8), but a strong ligament – similar to the ulnar
156 collateral ligament in humans – can be found on the position of the macaque ETA (8/8). There is some
157 confusion about the presence or absence of the ETA in primates. In bonobos, and other great apes, the
158 presence is debated as it can easily be missed or considered part of the FCU during dissections of the
159 forearm (Diogo and Wood, 2012; Diogo, Molnar and Wood, 2017). Also in humans, there is still no
160 agreement whether the ETA is present (Hirasawa, Sawamura and Sakakida, 1979; Gessini *et al.*, 1981;
161 Usctin *et al.*, 2014; de Ruiter and van Duinen, 2017) or absent (Diogo, Richmond and Wood, 2012).
162 In present or past dissections that we conducted we never found a distinct ETA in either bonobos or
163 human cadavers (pers. obs.). In macaques, the ETA covers the cubital tunnel where it protects the ulnar
164 nerve as it passes through the elbow. Furthermore, activation of the ETA potentially facilitates forearm
165 extension and/or stabilization of the elbow joint during quadrupedal walking (Rui Diogo and Wood,
166 2012).

167

168 Forearm rotators

169 The *m. brachioradialis* (BR) invariably originates from the supracondylar ridge of the humerus (15/15)
170 and shows incidental proximal fusion with the *m. brachialis* (B) in both macaques (2/7) and gibbons
171 (2/8). In macaques, the BR muscle belly runs underneath the *m. extensor carpi radialis longus* (ECRL)
172 and *m. extensor carpi radialis brevis* (ECRB) at the origin, and inserts with a long tendon onto the styloid
173 process of the radius (7/7). In gibbons, the BR runs superficial to the ECRL and ECRB and its long
174 tendon either inserts directly onto the styloid process (3/8) or onto the shaft of the radius proximal to the
175 styloid (5/8), with the tendon running further along the radius to end on the styloid process (1/8) or just
176 proximal of it (4/8), a situation similar to bonobos. In humans, the BR is a strong elbow flexor when the
177 forearm is in a mid-position between pronation and supination at the radioulnar joint, and works
178 synergistic with the B and Bb, a function which is also important during brachiation in gibbons. During
179 pronation, the BR is more active during elbow flexion since the Bb is at a mechanical disadvantage, as
180 is probably also the case in macaques during quadrupedal walking (Boland, Spigelman and Uhl, 2008).

181

182 The *m. supinator* (SUP) originates from the lateral epicondyle of the humerus and inserts onto the
183 proximal half of the radius in all specimens (15/15), similar as in humans. In all macaques (7/7) and
184 most gibbon specimens, the SUP has an additional origin from the proximal third of the ulna, while in
185 bonobos this is the main origin of the SUP. In macaques, the SUP probably acts as a supinator of the
186 forearm like in modern humans, although the exact activity pattern of the SUP during quadrupedal
187 locomotion has not yet been investigated. In gibbons, EMG studies have indicated that the SUP mainly
188 acts in the support phase of brachiation, during which time the forearm passes increasingly into
189 supination (Stern and Larson, 2001).

190

191 The *m. pronator teres* (PT) consists of a single humeral head in macaques with its origin on the medial
192 epicondyle of the humerus (7/7). In gibbons, either a humeral head (7/8), as seen in macaques, or an
193 ulnar head, which originates from the proximal ulna (1/8), is present. Although Miller (1932) stated that
194 the PT of all hominoids has two heads (Miller, 1932), a configuration we also found in bonobos, a two-
195 headed configuration with a humeral and ulnar head as seen in humans and great apes was never

196 observed in the gibbon specimens. In all primate specimens, the PT inserts halfway the radius (15/15),
197 and fusion with the FCR (macaque: 3/7, gibbon: 1/8), the FDS (macaque: 3/7) or B (gibbon: 1/8) may
198 occur. Poor development or absence of the ulnar head seems to be a common variation in humans
199 (Jamieson and Anson, 1952; Caetano *et al.*, 2017), which is supported by phylogenetic development, as
200 in most mammals (except anthropoid apes) the ulnar head is completely missing (Macalister, 1868;
201 McMurrich, 1903). In humans, the median nerve passes between both heads of the PT which enhances
202 the risk of entrapment of the median nerve, also called the “pronator teres syndrome” (Nigst and Dick,
203 1979; Hartz *et al.*, 1981; Fuss and Wurzl, 1990). Absence of the ulnar head in all macaques and most of
204 the gibbons might be important to avoid such entrapment during locomotion. Another possible
205 explanation is that the presence of an ulnar head in humans allows pronation of the forearm independent
206 of the position of the elbow. In macaques, the angle of the elbow joint is relatively constant during
207 quadrupedal locomotion (Demes *et al.*, 1998), and an ulnar head might not be needed. In gibbons, the
208 PT is primarily active as the elbow is flexed in the middle of the swing phase of brachiation (Stern and
209 Larson, 2001), which might indicate that forearm pronation independent of elbow position is also not
210 important in gibbons. Indeed, an ulnar head in gibbons was only observed in one individual.

211

212 The *m. pronator quadratus* (PQ) has a rather consistent configuration in macaques and gibbons. It
213 originates from the distal ulna (13/15) and inserts onto the distal interosseous membrane and the distal
214 radius (13/15), similar to bonobos. In two gibbon specimens (2/8), the PQ appears as two fused muscle
215 bellies. The proximal belly (deep head) inserts with a tendinous portion onto the distal radius. The distal
216 belly (superficial head) is larger and originates from the distal radius and inserts with tendinous fibres
217 onto the distal ulna. As reported in literature, this configuration with two bellies is also commonly seen
218 in humans (Johnson and Shrewsbury, 1976; Stuart, 1996). In macaques and gibbons, the fibres of the
219 PQ consistently show an oblique orientation, which is also seen in bonobos, while in humans, only the
220 fibres of the deep head show an oblique orientation as the fibres of the superficial head are transversely
221 oriented from origin to insertion. It has been suggested that the human superficial head, due to its
222 transverse fibre orientation, is the initiator and rotator for pronation, while the deep head is mostly
223 involved in stabilizing the distal radioulnar joint (Johnson and Shrewsbury, 1976). This indicates that

224 the primary function of the PQ in gibbons and macaques, due to the oblique fibre orientation, is
225 stabilization of the distal radioulnar joint, which implies that the PT is the most important forearm
226 pronator in these primates. The idea that the PQ in gibbons and macaques plays a role as a dynamic
227 ligament does correspond to its positioning close to the distal radioulnar joint (small moment arm) and
228 relatively small size (distal 1/4th to 1/5th of the forearm) compared to modern humans (distal 1/3rd of the
229 forearm). In gibbons, the PQ is also used to position the hand prior to grasping a new support (Stern and
230 Larson, 2001).

231

232 Extrinsic hand musculature

233 The *m. extensor carpi radialis longus* (ECRL) and *m. extensor carpi radialis brevis* (ECRB) show a
234 similar configuration in both macaques and gibbons. The ECRL originates from the lateral
235 supracondylar ridge of the humerus, distal from the BR (15/15), and inserts onto the base of metacarpal
236 2 (MC2) (15/15), similar to the configuration in bonobos. In two gibbon specimens, the ECRL sends a
237 tendon slip to the base of MC1 at the insertion (2/8). This means that in these specimens, the ECRL
238 could also assist in thumb extension and abduction and/or stabilization of the trapeziometacarpal joint.
239 The ECRB originates from the lateral supracondylar ridge of the humerus, distal from the ECRL and
240 inserts onto the dorsoradial base of MC3 in all macaques (7/7). Fusion with the *m. extensor digitorum*
241 *communis* (EDC) (4/7) can occur. In gibbons, the ECRB originates either solely from the lateral
242 epicondyle of the humerus (1/8), or the lateral supracondylar ridge of the humerus (7/8) in combination
243 with the lateral epicondyle (1/8). In bonobos, the ECRB originates solely from the lateral epicondyle of
244 the humerus. As in macaques, fusion with the EDC is possible but is only observed in one gibbon
245 specimen (1/8). The ECRB inserts onto the dorsoradial base of MC3 (8/8). Both the ECRL and ECRB,
246 synergist muscles with a similar function, can be proximally fused in macaques (6/7) and gibbons (2/8),
247 which leads to a concerted action between both muscles.

248

249 The *m. extensor carpi ulnaris* (ECU) originates from the common extensor tendon at the lateral
250 epicondyle of the humerus and inserts with a long tendon onto the ulnar base of MC5 in all macaques
251 (7/7). In gibbons, the ECU also originates from the lateral epicondyle of the humerus (8/8), sometimes

252 in combination with the proximal ulna (1/8), which is the main origin in bonobos, or the oleocranon
253 (1/8). The insertion on MC5 is similar to that of macaques in all gibbon specimens (8/8). Given its
254 position in the forearm, the ECU functions as wrist extensor and ulnar deviator in macaques and gibbons,
255 common to what is observed in other primates, including humans.

256

257 The *m. extensor digitorum communis* (EDC) originates with a common tendon from the lateral
258 epicondyle of the humerus in all specimens (15/15), similar to bonobos and humans, and is proximally
259 fused with the *m. extensor digiti minimi* (EDM) in half of the gibbons (4/8). The EDC splits into four
260 individual tendons at the dorsum of the hand in macaques (7/7), while in gibbons, the tendon to digit 2
261 splits off proximally to the wrist, the tendon to digit 5 splits off at the level of the wrist, and the tendons
262 to digits 3 and 4 split off at the dorsum of the hand and commonly interconnect with the tendons of
263 digits 2 and 5 (*juncturae tendineum*) (**Fig. S1**). These *juncturae tendineum* are also found in bonobos,
264 between the tendons to digits 4 and 5. Each tendon inserts on the distal phalanx, after forming the
265 extensor mechanism with the *m. lumbricalis* and *mm. interossei* (see intrinsic musculature) (15/15). The
266 EDC acts as a wrist and digital extensor.

267

268 In the following paragraphs, the *m. extensor digiti quarti et quinti proprius* (EDQQ), *m. extensor digiti*
269 *secundi et tertii proprius* (EDST), *m. extensor digitorum brevis* (EDB), *m. extensor digiti minimi*
270 (EDM), and *m. extensor indicis* (EI) are discussed together because they are developmentally related
271 (Diogo *et al.*, 2009).

272

273 Macaques show the most primitive condition with a *m. extensor digiti secundi et tertii proprius* (EDST)
274 and *m. extensor digiti quarti et quinti proprius* (EDQQ), inserting onto digits 2-3 and digits 4-5
275 respectively, which corresponds to the *m. extensores digitorum breves* (EDB) of digits 2-3 and digits 4-
276 5 of other tetrapods (Diogo *et al.*, 2009). The EDST originates from the proximal half of the ulna (7/7)
277 and the tendons insert onto the ulnar side of the extensor mechanism of digits 2 and 3 (**Fig. 2A**). The
278 EDQQ originates from the lateral epicondyle of the humerus, from the same extensor tendon as the

279 EDC, and the tendons insert on the ulnar side of the extensor mechanism of digits 4 and 5, near the
280 proximal phalanx (**Fig. 2A**). Extension of the fingers is thus controlled in pairs in macaques.

281

282 In contrast to macaques, all gibbons show a more derived configuration as they possess a *m. extensor*
283 *digitorum brevis* (EDB) (**Fig. 2B**), which inserts onto digits 2-4, and a true *m. extensor digiti minimi*
284 (EDM), which inserts onto digit 5 (**Fig. 2B**). The EDB originates from the proximal half of the
285 interosseous membrane (8/8), and either the proximal (4/8) or distal half (4/8) of the ulna. The individual
286 tendons insert either onto the proximal phalanx of digits 2, 3 and 4 (6/8) or only onto digits 3 and 4 (1/8).
287 Occasional insertions onto the base of MC2, MC3 and MC4 may occur (1/8). The most important
288 function of the EDB is the coordinated extension of digits 2, 3 and 4. The EDM originates from the
289 lateral epicondyle of the humerus (7/8) or the distal half of the ulna (1/8), and inserts onto the distal
290 phalanx of digit 5 together with the tendon of the EDC (8/8). Proximal fusion of the EDM with the ED
291 can occur (4/8).

292

293 Modern humans show the most derived condition. They possess an EDM – similar to gibbons – in
294 combination with a separate *m. extensor indicis* (EI), which inserts onto the distal phalanx of digit 2, a
295 configuration also seen in great apes (Aversi-Ferreira *et al.*, 2010; Zihlman, Farland and Mi, 2011). The
296 EI and EDM of modern humans and great apes are phylogenetically derived from the EDB of other
297 tetrapods (Diogo *et al.*, 2009), and replace the EDB. Gibbons present an intermediate configuration in
298 that they preserve an EDB and have an EDM. In one gibbon specimen, we even identified an EI,
299 originating from the distal third of the ulna and the interosseous membrane and inserting onto the distal
300 phalanx of the index finger together with the tendon of the EDC (1/8). Variation in the extensor
301 musculature is, however, also present in humans. The EDB has been reported as a rare anatomical
302 variation in humans (2.3% of the human population; (Suwannakhan, Tawonsawatruk and Meemon,
303 2016; Georgiev *et al.*, 2018)), and an ‘EI’ with a tendon running to both the index and middle finger
304 (i.e. *m. extensor indicis et medii communis*), as seen in macaques, does also occur in humans (0-6%)
305 (Suwannakhan, Tawonsawatruk and Meemon, 2016; Georgiev *et al.*, 2018).

306

307 The specific configuration of these extensors in macaques, gibbons, and humans has important
308 functional implications. In macaques, the fingers are controlled in pairs by the EDST and EDQQ. A
309 similar organization is found in the finger flexors of macaques, where the fingers are also controlled in
310 pairs. This specific organization might aid in efficient positioning of the hand and fingers during palmi-
311 or digitigrade quadrupedal walking, such as pairwise extension (and little abduction) of the fingers to
312 accommodate to uneven substrates, which might prevail over individual finger control. Although one
313 could argue that the substrates that macaques need to move along are not any more uneven than those
314 of gibbons, the hand positioning in palmi/digitigrade quadrupedalism is very different from that used in
315 brachiation. Gibbons typically use a hook grip during brachiation, and the hands are positioned on the
316 superstrate in an overhead position, without visual input. In such hook grip position, individual
317 positioning of the fingers seems less important and simultaneous flexion of the four fingers prevails
318 (Tuttle, 1969; Susman, Jungers and Stern, 1982). In gibbons, extension of the little finger is controlled
319 by a separate EDM, while digits 2-4 are extended by the EDB. This suggests that simultaneous extension
320 of digits 2-4 in gibbons might be important when reaching or grasping a support during brachiation (cf.
321 hook grip position described above). Humans and bonobos have a separate EDM and EI, resulting in a
322 functional dissociation between the extension of the index finger and little finger, which is also distinct
323 to that of digits 3 and 4 which is primarily mediated by the EDC. This individualization of finger
324 extension, in combination with a separate *m. flexor pollicis longus* to the thumb, is likely linked to the
325 high manual dexterity of humans.

326

327 The *m. abductor pollicis longus* (APL) originates from the interosseous membrane and the proximal
328 shaft of the ulna in all macaque and gibbons specimens (15/15). In macaques, the APL consists of one
329 muscle belly with a tendon that splits at the level of the trapezium, inserting with one slip onto the base
330 of MC1 and with the other onto the prepollex (7/7) (**Fig. 3A**). In gibbons, however, the APL consists of
331 two muscle bellies, APL I and II, each with its own tendon, and the bellies are either proximally fused
332 (6/8) or easily separable (2/8). The tendon of APL I always inserts on the base of the MC1 (8/8), while
333 the tendon of APL II inserts most often on the trapezium (7/8), with an additional insertion on the
334 prepollex (2/8), or it may insert solely on the capitate (1/8) (**Fig. 3B**). The configuration seen in gibbons,

335 with a distinct APL I and II, is also observed in bonobos and humans (van Leeuwen *et al.*, 2018) even
336 though this is largely overlooked in other literature. This specific configuration makes that only the APL
337 I can be considered a true abductor of the thumb, while the APL II functions as radial deviator of the
338 wrist and has no function on the thumb. The insertion onto the prepollex, as seen in macaques and some
339 gibbons (and bonobos), might not entail a functional difference to an insertion on the trapezium, given
340 the close association between the prepollex and trapezium in most nonhuman primates (Le Minor, 1994).

341

342 The *m. extensor pollicis longus* (EPL) has its origin on the proximal ulna (15/15), and often also from
343 the interosseous membrane both in macaques (4/7) and gibbons (3/8). It inserts with a long tendon onto
344 the distal phalanx of digit 1 (14/15). This configuration is also seen in bonobos. In one gibbon specimen,
345 the insertion could not be reported due to tissue damage. Both macaques and gibbons (and bonobos)
346 lack a *m. extensor pollicis brevis* (EPB) in contrast to humans, although absence of the EPB in humans
347 has also been reported (Nayak *et al.*, 2008). The EPB in humans displays some anatomical variations,
348 such as the *m. extensor pollicis et indicis accessorius* with a tendon to digit 1 and 2 (Yoshida, 1995). It
349 has been proposed in literature that the EPB of modern humans is a derivative of APL I (Straus, 1941;
350 Diogo *et al.*, 2009), as the primitive mammalian condition shows an APL with a single tendon (Aversi-
351 Ferreira *et al.*, 2010) while the APL in macaques splits distally, and gibbons clearly show two separate
352 tendons (APL I and II). However, this interpretation is still debated as both the APL I and EPB have a
353 different insertion, i.e. the base of MC1 versus the proximal phalanx of the thumb. In addition, humans
354 can have an EPB present next to an APL with multiple tendons (cfr. APL I) inserting around the first
355 carpometacarpal joint (Lacey, Goldstein and Tobin, 1951; Celik, Sendemir and Simsek, 1994; Sehirli,
356 Cavdar and Yüksel, 2001).

357

358 The *m. flexor carpi radialis* (FCR) shows a similar configuration in both macaques and gibbons (and
359 bonobos). It originates from the common flexor tendon at the medial epicondyle of the humerus and
360 inserts with a long tendon onto the palmar base of MC2, running deep to the thenar muscles (15/15).
361 Proximal fusion with the muscle belly of the FDS (1/7) and/or PT (3/7) might occur in macaques. In one
362 gibbon specimen, the FCR also originates from the proximal ulna (1/8). Given its position in the

363 macaque and gibbon forearm, it functions as a wrist flexor and radial deviator, and probably a weak
364 pronator.

365

366 The *m. flexor carpi ulnaris* (FCU) originates from the common flexor tendon at the medial epicondyle
367 of the humerus (*caput humerale*) in all macaque and gibbon specimens (15/15). An additional origin
368 from the oleocranon (*caput ulnare*) occurs in both macaques (4/7) and gibbons (1/8). This configuration
369 is also seen in bonobos. The FCU inserts with a long tendon onto the pisiform bone in all specimens
370 (15/15). The FCU functions as wrist flexor and ulnar deviator in both macaques and gibbons. In
371 macaques, the long pisiform, which is directed perpendicular to the palmar surface of the hand, gives
372 the FCU an optimal leverage for flexing an extended wrist (Lewis, 1985; Sarmiento, 1988), which is
373 important during quadrupedal walking. In gibbons, the pisiform has a proximodistal orientation which
374 increases the lever arm of the FCU for wrist flexion and ulnar deviation (Sarmiento, 1988). These wrist
375 movements are important during brachiation (Michilsens *et al.*, 2010).

376

377 The *m. palmaris longus* (PL) originates from the common flexor tendon at the medial epicondyle of the
378 humerus and its long and slender tendon extends into the palmar aponeurosis at the level of the wrist in
379 all macaques (7/7). This configuration is similar to that of modern humans, though the PL tendon of
380 macaques runs more ulnarly into the palmar aponeurosis. In gibbons, the origin of the PL is the same as
381 in macaques, with an additional origin from the fascia of the aponeurosis bicipitis of the Bb in two
382 specimens (2/8). At the insertion, the configuration in gibbons is distinct from that observed in
383 macaques, with a radially positioned PL tendon at the wrist (5/7), which is also seen in bonobos, or even
384 with an insertion onto the tendon of the FCR (2/7). The more radial insertion found in gibbons could be
385 important during brachiation as it can aid in radial deviation. However, more important is the fact that
386 the PL is always present in macaques and gibbons (and bonobos), while in modern humans the PL is
387 unilaterally absent in 16% of the population (Thompson, Mockford and Cran, 2001).

388

389 The *m. flexor digitorum superficialis* (FDS) originates from the common flexor tendon at the medial
390 epicondyle of the humerus in all macaques (7/7) and inserts most commonly with four separate tendons

391 onto the middle phalanx of digits 2 to 5 (6/7). In one specimen, the tendons to digits 2 and 3 are vestigial
392 and insert on the tendon sheaths of the FDP at the level of the lumbricals, while the tendons to digits 4
393 and 5 insert onto the proximal phalanx (1/7). The FDS has a rather complex architecture in macaques,
394 which is also commonly seen in bonobos, consisting of three partially fused muscle bellies that are
395 folded together; (1) a muscle running to digit 2 (FDS II), which shows a distinct belly-tendon-belly-
396 tendon configuration (cfr. bonobos (van Leeuwen *et al.*, 2018)), (2) a muscle belly with two tendons
397 inserting onto digit 3 and 4 (FDS III-IV), and (3) a muscle with one tendon inserting onto digit 5 (FDS
398 V) (**Fig. S2**). Moreover, in all macaque specimens, the FDS is connected with the *m. flexor digitorum*
399 *profundus* (FDP) with an additional muscle belly, at the level of the FDS for digit 2-3 (7/7). In gibbons,
400 the configuration of the FDS is even more variable than in macaques. In half of the specimens, the FDS
401 consists of one muscle belly (4/8), while two (2/8), three (1/8) or four muscles bellies (1/8) are also
402 observed. The distribution of tendons to the digits 2 to 5 differs from specimen to specimen. Moreover,
403 in gibbons the FDS originates not only from the medial epicondyle but also from the proximal ulna (4/8)
404 or from the proximal ulna and radius (1/8). In gibbons, the deep flexors of the toes, like the FDS, also
405 show considerable variation in the specific distribution of the tendons towards the digits (Langdon,
406 1990; Vereecke *et al.*, 2005), indicating that the tendon organization has no major influence on the
407 functionality of the FDS.

408

409 The *m. flexor digitorum profundus* (FDP) originates from the medial epicondyle of the humerus (situated
410 deep to the FDS), the shaft of the radius (in between the SUP and PQ), the interosseous membrane, and
411 the shaft of the ulna (from the oleocranon to the PQ) in all specimens (15/15). In bonobos, the FDP does
412 not originate from the medial epicondyle of the humerus, but from the interosseous membrane and the
413 shaft of the radius and ulna. In macaques and gibbons, the FDP has five tendons inserting respectively
414 onto the distal phalanges of each digit, with some exceptions (see **Table S1**). In gibbons, the FDP usually
415 consists of two muscle bellies that are partially fused, one for digit 1 (FDP I) and one for digits 2 to 5
416 (FDP II-V) (5/8) (**Fig. 4A**). The other specimens do not have a separate FDP I (3/8). In two specimens,
417 the FDP II-V sends a tendon to digit 1, which splits off from the tendon running to digit 2 (2/8). In
418 another gibbon specimen, two individual muscle bellies occur, one for digits 1 and 2 (FDP I-II) and one

419 muscle belly for digits 3 to 5 (FDP II-V). Here, the tendons to digit 2 and 3 partly originate from the
420 FDS (1/8) (**Fig. 4B**). In macaques, the configuration of the FDP is more variable, with the majority of
421 the specimens showing a configuration with three fused muscle bellies, one for digit 1 to 3 (FDP I-III),
422 one for digit 4 (FDP IV) and one for digit 5 (FDP V) (5/7) (**Fig. 4C**). One specimen shows a slightly
423 different configuration, with a division in FDP I-III-IV, FDP II and FDP V (1/7), while a second
424 macaque specimen displays an unusual FDP configuration with two muscle bellies – FDP I-II-III and
425 FDP IV-V. In addition, the tendons to digits 2 and 3 show a tendon-lumbrical-tendon configuration in
426 which the first two lumbricals form a single unit with the FDP tendons instead of originating from these
427 tendons (**Fig. 4D**). In macaques, the tendons of the FDP are clustered together at wrist level, and the
428 tendons to the digits split off more distally than seen in gibbons. In addition, the tendon to the thumb
429 originates from the middle of the tendon cluster, and not from FDP II as seen in gibbons. Also notable
430 is the connection between FDP and FDS in macaques, as described above. However, crucial is the
431 decoupling between the thumb (and index finger) and the lateral digits in gibbons, a configuration
432 common to humans, compared to the division between the medial and lateral digits in macaques (also
433 seen at the extensors, cfr. EDST and EDQQ).

434

435 Intrinsic hand musculature

436 The intrinsic hand musculature consists of the thenar muscles (APB, FPB, ADP, OPP), the hypothenar
437 muscles (ADM, FDM, ODM), the lumbricals (LUMB) and intermediate hand muscles (IM, FBP, IOP,
438 IOD, *mm. contrahentes*) (**Fig. 5, Table 2**). These intrinsic hand muscles of macaques and gibbons are
439 described in detail below.

440

441 The *m. abductor pollicis brevis* (APB) has a similar configuration in both macaques and gibbons. It
442 originates from the flexor retinaculum and inserts with a short tendon onto the radial sesamoid bone of
443 the first metacarpophalangeal joint (MCP1) in all specimens (11/11), similar to the configuration in
444 bonobos. In some macaques, the APB also originates from the palmar aponeurosis (4/7), while the
445 insertion can extend to the radial side of the proximal phalanx (3/7), which is common in humans (Gupta
446 and Michelsen-Jost, 2012). In one gibbon specimen, the APB is fused with the OPP (1/4), while some

447 macaque specimens show fusion between the APB and FPB (3/7). The APB functions as abductor of
448 the thumb both in gibbons and macaques, as well as a stabilizer for the TMC joint.

449

450 The *m. flexor pollicis brevis* (FPB), situated underneath the APB, originates from the flexor retinaculum
451 and it inserts with a short tendon onto the radial sesamoid bone of the MCP1 joint in all specimens
452 (13/13). A clear distinction between a superficial and deep head, as commonly observed in humans, may
453 occur in both gibbon (4/6) and macaques (2/7). In macaques, the FPB shows some fusion with the APB
454 at the origin (3/7), and with the oblique head of the ADP at insertion (3/7). In gibbons, the FPB can also
455 originate from both the flexor retinaculum and the volar side of MC1 (1/6), while its insertion can be
456 located at the ulnar side of the APB insertion (5/6) or at the base of the proximal phalanx of digit 1 (1/6).
457 In two gibbon specimens, the FPB shows some fusion with the OPP (2/6).

458

459 The *m. adductor pollicis* (ADP) always consists of a clearly separable transverse and oblique head in
460 macaques (7/7). The transverse head originates from the palmar base and shaft of MC3 (7/7) and inserts
461 onto the ulnar sesamoid bone of the MCP1 joint (7/7), in combination with the MCP joint (3/7) and/or
462 the proximal phalanx of digit 1 (4/7). In one specimen, muscle tissue extends towards the radial side of
463 MC2. The oblique head originates from the palmar base of MC1 (7/7), sometimes together with the
464 palmar base of MC2 (1/7) or MC3 (1/7). It also has its insertion onto the ulnar sesamoid bone of the
465 MCP1 joint (7/7), along with the ulnar (1/7) or radial (1/7) side of the proximal phalanx of digit 1 or the
466 MCP1 joint (1/7). In gibbons, both heads are usually clearly separable (4/6), however, occasionally they
467 are indistinguishable (2/6) in which case the ADP originates from the palmar base of MC1 and MC3
468 and inserts onto the ulnar sesamoid bone of the MCP 1 joint. The transverse head is similar to that of
469 macaques, with its origin on the palmar base and shaft of MC3 (4/4). It inserts onto the ulnar sesamoid
470 bone of the MCP1 joint (4/4) and may extend to the base of the proximal phalanx of digit 1 (1/4). The
471 oblique head either originates from the palmar base of MC1 (2/4), the base of MC2 (1/4), or the flexor
472 retinaculum (1/4). Like the transverse head, it inserts onto the ulnar sesamoid bone of the MCP1 joint
473 (4/4) with the occasional extension to the base of the proximal phalanx of digit 1 (2/4). The main function
474 of the ADP is adduction of the thumb.

475 The *m. opponens pollicis* (OPP) is a clearly separate muscle in macaques. It originates from the flexor
476 retinaculum, with some fibres originating from the APB and FPB (1/7) or the prepollex (2/7), and inserts
477 onto the radial side of the MC1 shaft. It has no contact with the sesamoid bones of the MCP1 joint. In
478 gibbons (and bonobos), the OPP is either completely fused with the FPB (1/5) or the APB (1/5), partially
479 fused with the FPB (1/5), or is present as a separate muscle (2/5). When separate, it originates from the
480 flexor retinaculum (2/2) in combination with the palmar base of MC1 (1/2), and it inserts onto the radial
481 side of the MC1 shaft (2/2). The OPP assists in opposition and adduction of the thumb.

482

483 The *m. palmaris brevis* (PB) is a well-developed muscle in macaques (7/7), while in gibbons (and
484 bonobos) no distinct PB can be identified (mostly fat tissue) in half of the specimens (2/4). The PB
485 originates from the flexor retinaculum and inserts onto the palmar aponeurosis in all primate specimens
486 (11/11). The PB of gibbons is similar in appearance to that of bonobos and humans, while the more
487 bulky PB in macaques is likely acting as a cushion to protect the ulnar artery and nerve during
488 quadrupedal walking.

489

490 The *m. abductor digiti minimi* (ADM) originates from the pisiform bone (7/7) in combination with the
491 flexor retinaculum and pisohamate ligament (4/7) in macaques (and bonobos). It inserts onto the ulnar
492 side of the MCP5 joint (7/7), in combination with the proximal phalanx (2/7) as seen in bonobos or
493 joining the FDM tendon (5/7). In two macaque specimens, the ADM is proximally fused with the FDM.
494 In gibbons, the ADM originates from either the pisiform bone (2/5) or the base of MC5 (3/5) and inserts
495 onto the ulnar side of the MCP5 joint (5/5). In one gibbon specimen, the ADM is partially fused with
496 the FDM. The ADM acts as abductor of digit 5.

497

498 The *m. flexor digiti minimi* (FDM) originates from the flexor retinaculum (7/7) and pisiform bone (2/7)
499 in macaques. It inserts onto the MCP5 joint (7/7), along with the ADM tendon (2/7) or the proximal
500 phalanx of digit 5 (4/7). In two macaque specimens, the FDM shows proximal fusion with the ADM. In
501 gibbons, the origin is more variable. The FDM can originate from the flexor retinaculum (3/5), the base
502 of MC5 (1/5), or the palmar aponeurosis (1/5). The FDM inserts onto the ulnar base of the proximal

503 phalanx of digit 5 in all gibbon specimens (5/5), and also bonobos. Proximal fusion with the ODM (1/5)
504 or distal fusion with the ADM (2/5) in gibbons is possible. The FDM acts as flexor of digit 5.

505

506 The *m. opponens digiti minimi* (ODM) originates from the flexor retinaculum and inserts onto the ulnar
507 side of the MC5 shaft in all macaque and gibbon specimens (11/11), similar to the bonobo configuration.
508 In one gibbon specimen, the ODM is completely fused with the FDM. In macaques, an additional origin
509 from the base of MC5 can be present (2/7). The function of the ODM is opposition of digit 5.

510

511 The *mm. lumbricales* (LUMB) of digit II-V each originate from the corresponding FDP tendon and
512 insert with a well-developed tendon onto the radial side of the extensor sheath at the proximal phalanx
513 of the corresponding digit in more than half of the specimens (9/15). However, some variation is possible
514 regarding the origin. In most macaque specimens, and also bonobos, LUMB III-V originate from two
515 FDP tendons (LUMB III from FDP II and III (5/6), LUMB IV from FDP III and IV (7/7), and LUMB
516 V from FDP IV and V (6/7)), which might aid force transmission. One macaque specimen shows a
517 particular configuration in which the lumbrical muscle was positioned in series with the FDP tendon
518 (see FDP description). In gibbons, LUMB II (1/8) and LUMB III (3/8) can originate from the FDP II
519 and III tendons, LUMB IV from FDP III and IV (2/8), and LUMB V from FDP IV and V (2/8) or solely
520 from FDP IV (1/8). In one gibbon specimen, proximal fusion of LUMB II-IV occurs near the origin on
521 the FDP tendons. The LUMB act as flexors of the MCP joints and extensors of the IP joints.

522

523 The primitive mammalian condition for the intermediate hand muscles is the presence of four *mm.*
524 *intermetacarpales* (IM) and ten *mm. flexores breves profundi* (FBP) (Diogo *et al.*, 2009; Diogo and
525 Tanaka, 2012; Diogo and Molnar, 2014; Lemelin and Diogo, 2016). In primates, two FBP have
526 differentiated: FBP I forms the FPB and OPP, FBP X forms the FDM and ODM. In humans, the IM (I-
527 IV) are fused with FBP (III, V, VI, VIII) to form the *mm. interossei dorsales* (IOD I-IV) (Diogo *et al.*,
528 2009). In all macaque specimens, both the IM and FBP are fused to form the IOD (7/7). In gibbons,
529 however, some individuals display an intermediate configuration where only one, two or three IOD are
530 present while the other IM and FBP remain present as separate muscles (5/8). This configuration is also

531 seen in bonobos (van Leeuwen *et al.*, 2018). In macaques, the presence of IOD might be important for
532 specific hand movements during quadrupedal walking, such as abduction of fingers to accommodate to
533 uneven terrain. A detailed visualisation of individual specimen's intermediate hand muscle
534 configurations is reported in the Supplementary material (**Fig. S3**). In addition to the IOD and IOP, a *m.*
535 *contrahens* (C5) is present in all but one macaque specimens (7/8). The C5 originates from the palmar
536 base of MC3 (partially fused with IOD II and III) and inserts on the radial side of the MCP5 joint, joining
537 the extensor mechanism (**Fig. 6A**). No other *contrahens* muscles are observed in the macaque sample.
538 In contrast, the gibbons sample shows *contrahens* muscles associated with digit 2, 3 and 4 are present in
539 some specimens. Four specimens have a C2 inserting onto the ulnar side of the MCP2 joint (4/8) (**Fig.**
540 **6B**), and three specimens have a C4 and C5 inserting onto the ulnar side of, respectively, the MCP3 and
541 MCP4 joints (3/8). In the literature, however, the insertion of C4 and C5 has been described onto the
542 radial side of the MCP3 and MCP4 joint in gibbons (one *Hylobates lar* (Yamamoto, Murakami and
543 Ohtsuka, 1988)), macaques (two macaques (Yamamoto, Murakami and Ohtsuka, 1988)) and three
544 Japanese monkeys (Homma and Sakai, 1994). In one gibbon specimen, an additional muscle distinct
545 from the *contrahens* muscles described above is present. It originates from the IOD I and inserts onto the
546 radial side of the proximal phalanx of digit 1. This muscle is similar to the *m. contrahens digitorum*
547 (CD) of modern humans, as described by Tubbs *et al.* (Tubbs, Salter and Oakes, 2005).

548 **Discussion**

549 In this study, the configuration of the forearm and hand muscles of arboreal gibbons is compared with
550 that of terrestrial macaques. In addition, anatomical data from previous dissections on knuckle-walking
551 bonobos and bipedal humans are included to allow us to evaluate if the forearm and hand musculature
552 shows functional adaptations to locomotor behaviour (van Leeuwen et al., 2018).

553

554 Upper arm musculature

555 The most notable trait in the gibbon upper limb is the configuration of the short head of the *m. biceps*
556 *brachii* (Bb), which originates from the lesser tubercle of the humerus as such losing its function at the
557 glenohumeral joint, which is most likely a derived condition. In gibbons, the short head therefore
558 primarily acts as elbow flexor and forearm supinator (Michilsens *et al.*, 2009), while in macaques,
559 bonobos, and humans the short head of the Bb functions as shoulder flexor as it crosses the shoulder
560 joint and originates from the coracoid process of the scapula. According to Jungers and Stern (1980), in
561 gibbons the short head of the Bb forms a ventral muscle chain between the *m. pectoralis major* (PM)
562 and *m. flexor digitorum superficialis* (FDS) (Jungers and Stern, 1980), although this specific action
563 remains debated.

564

565 Other remarkable muscles are the *m. dorso-epitrochlearis* (DET) and *m. epitrochleoanconeus* (ETA).
566 The DET is present in both macaques and gibbons but has a slightly different configuration. In most
567 gibbons the DET inserts onto the medial epicondyle as opposed to the lateral side of the elbow in
568 macaques (Sonntag, 1922; Jungers and Stern, 1980; Michilsens *et al.*, 2009). In great apes, the DET also
569 inserts onto the medial epicondyle of the humerus (Diogo *et al.*, 2010, 2013; Diogo, Potau and Pastor,
570 2013), while in other primate taxa (*Alouatta*, *Saimiri*, *Callithrix*), the DET inserts onto the oleocranon
571 as seen in macaques (R. Diogo and Wood, 2012). Although Aversi-Ferreira et al. suggest that the DET
572 favors arboreal locomotion when it inserts onto the oleocranon and quadrupedal locomotion when it
573 inserts onto the epicondyle of the humerus (Aversi-Ferreira *et al.*, 2016), this contradicts our results.
574 The insertion onto the oleocranon in macaques might be important to help stabilize the elbow during
575 terrestrial quadrupedalism, while through its insertion onto the medial epicondyle of the humerus in

576 gibbons and bonobos, the DET could produce elbow and digital flexion (i.e. dorsal muscle chain) which
577 could be an advantage during brachiation in gibbons and climbing/clambering in bonobos (Jungers and
578 Stern, 1980), although this function is still debated as is the case for the ventral muscle chain (see above).
579 The ETA is a prominent muscle in macaques, but is not observed in gibbons (and humans). It may serve
580 to protect the ulnar nerve, running superficially through the cubital tunnel, and it potentially helps to
581 extend the forearm and/or stabilize the elbow joint during quadrupedal walking. However, there is still
582 some discussion about the presence or absence of this muscle across different primate taxa which
583 requires anatomical data from a larger nonhuman primate sample (Uscetin *et al.*, 2014; de Ruiter and
584 van Duinen, 2017; Diogo, Molnar and Wood, 2017).

585

586 Forearm rotators

587 The forearm rotators (BR, SUP, PT, PQ) have a very similar configuration in macaques and gibbons
588 (and bonobos), with a low variability in muscle architecture. This conserved morphology might indicate
589 that these muscles are under strong selective pressure and that their specific configuration is tightly
590 linked to forearm functionality. A two-headed configuration of the PT, as in modern human, was never
591 observed in neither the macaque nor the gibbon sample. In the PQ, on the other hand, a two-headed
592 configuration similar to humans was observed in two gibbon specimens. Due to the oblique orientation
593 of the muscle fibres, the primary function of the PQ is likely stabilization of the distal radioulnar joint
594 in macaques, gibbons and bonobos (Johnson and Shrewsbury, 1976). This implies that the PT is the
595 most important forearm pronator in these primates.

596

597 Extrinsic hand musculature

598 The dorsal compartment of the forearm shows a different configuration in macaques and gibbons. In
599 macaques, the fingers are controlled in pairs by the EDST and EDQQ. A similar organization is found
600 in the finger flexors of macaques, where the fingers are also controlled in pairs. We suggest that this
601 specific organization might aid in efficient positioning of the hand and fingers during palmi- or
602 digitigrade quadrupedal locomotion on uneven substrates. In gibbons, the little finger is controlled by a
603 separate EDM, and extension of digits 2-4 is coupled. This might indicate that simultaneous extension

604 of digits 2-4 in gibbons is important when reaching for and grasping an overhead support during
605 brachiation. Humans and bonobos have a separate EDM and EI, resulting in a functional dissociation
606 between the extension of the index finger and little finger. In humans, this is likely linked to the high
607 manual dexterity.

608 The ventral compartment shows an extraordinary variability within the FDS and FDS, both in gibbons
609 and macaques. This variability is also seen in bonobos. This high inter-individual variation might
610 indicate that these muscles are under mild selective pressure, and that the differences in configuration
611 of these muscles has no major influence on the functionality of the hand/fingers.

612

613 Intrinsic hand musculature

614 The thenar (APB, FPB, OPP, ADP) and hypothenar (ADM, FDM, ODM) muscles have a very similar
615 configuration in gibbons and macaques (and bonobos), with a varying degree of fusion between the
616 different muscles. The intermediate hand musculature is much more variable and a different
617 configuration is seen in macaques compared to gibbons. The intermediate hand muscles are organized
618 in palmar and dorsal interossei in macaques, similar to the human configuration, while gibbons display
619 a highly variable configuration with at least some unfused FBP and IM, a configuration also seen in
620 bonobos. In gibbons, various contrahens muscles can be present, while in macaques only a C5 is
621 observed. The intermediate hand muscles of gibbons show a higher degree of variation compared to
622 those of macaques, which might suggest that there are no major implications for the functionality of the
623 hand.

624

625 *Critical considerations*

626 Our findings are based on a detailed dissection of eight gibbon and seven macaque specimens. Although
627 this is a limited sample size compared to human studies, it forms a unique and valuable sample of
628 nonhuman primates that was studied using a consistent protocol. Inherent to working with primate
629 cadavers is the lack of an equal distribution across species, sexes or ages, and most importantly,
630 sampling from captivity. However, given a healthy gene pool, we do not expect an impact of captivity
631 on muscle configuration. Given the genetic distance between macaques and gibbons, we cannot be

632 certain that the differences in muscle configuration are due to variation in locomotor behaviour and not
633 genetics. This is challenging to test, although it should not go unremarked as only two taxa are being
634 compared in detail, and there is no relative context of variation across other arboreal or terrestrial primate
635 taxa. We have tried to mitigate this issue by adding information on the forelimb and hand musculature
636 of two additional taxa, the bonobo and human, with different locomotor behaviours. However, the
637 gibbon group contains different genera and species in contrast to the homologous sampling of rhesus
638 macaques. This could explain the difference in variation of the FDS, FDP, and intermediate hand
639 muscles between gibbons and macaques, although we also observe a high variation in bonobos. The
640 contrasting results on the DET also stress the importance of broad phylogenetic sampling.

641 Despite these limitations, not only is this research important to obtain a detailed insight in the anatomy
642 of the gibbon and macaque forelimb and hand, but in combination with in vivo research and behavioural
643 studies it can be translated to complete form-function relationships of the primate hand which will aid
644 functional interpretation of fossil remains of nonhuman primates and hominins.

645

646 **Conclusion**

647 The overall configuration of the forelimb and hand musculature is highly comparable between the
648 different primate groups and follows the general primate condition. Most of the identified differences in
649 muscle configuration between arboreal gibbons, terrestrial macaques, knuckle-walking bonobos, and
650 bipedal humans seem to be related to the specific locomotor behaviour of each group though sampling
651 in a wider range of primate taxa is needed to further substantiate these functional adaptations.

652 **Acknowledgements**

653 The authors thank the different zoos and institutes which provided additional primate specimens: Georg
654 Hantke (National Museum of Scotland, Edinburgh), Pieter Cornillie (Ghent University, campus
655 Merelbeke), Koen Nelissen (KU Leuven, campus Gasthuisberg), François Druelle (Zoological and
656 Botanical Park of Mulhouse, France), Robby Van der Velden (Pakawi Park, Belgium). Furthermore, we
657 thank Olivier Vanovermeire and Henk Lacaeyse from the Medical Imaging Department, AZ Groeninge
658 (Kortrijk, Belgium) for CT-scanning of the specimens. Finally, we would like to thank one the students
659 who assisted during the dissections and Tracy Kivell for constructive comments on the manuscript.
660 Funding for this project was obtained from KU Leuven (project C14/16/082).

661

662 **Author contributions**

663 EEV conceived the study; EEV, MJMV and TvL designed the study; MJMV and TvL performed the
664 dissections; MJMV and EEV analysed the data and wrote the manuscript; all authors reviewed and
665 approved the manuscript.

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851

852 **Figure legends**

853 **Fig. 1** – The well-developed *m. epitrochleoanconeus* (ETA) of macaques. It originates from the medial
854 epicondyle of the humerus and inserts onto the medial border of the oleocranon. As it crosses the cubital
855 tunnel, the ETA protects the ulnar nerve. Activation of the ETA potentially facilitates forearm extension
856 and/or stabilization of the elbow joint during quadrupedal walking.

857 **Fig. 2** – A) *m. extensor digiti secundi et tertii proprius* (EDST) and *m. extensor digiti quarti et quinti*
858 *proprius* (EDQQ) of macaques; B) *m. extensor digitorum brevis* (EDB) and *m. extensor digiti minimi*
859 (EDM) of gibbons. Note that in macaques the fingers are controlled in pairs, which might aid in efficient
860 positioning of the hand and fingers on uneven terrain during quadrupedal walking. In contrast, extension
861 of the little finger in gibbons is separate from the extension of digits 2-4, suggesting that simultaneous
862 extension of digits 2-4 in gibbons might be important when reaching or grasping a support during
863 brachiation.

864 **Fig. 3** – Illustration of the *m. abductor pollicis longus* (APL): A) in macaques, the APL consists of one
865 muscle belly with a tendon that splits at the level of the trapezium, inserting with one slip onto the base
866 of MC1 and with the other onto the prepollex; B) in gibbons, the APL consists of two muscle bellies
867 each with its own tendon, APL I (insertion on the base of MC1) and APL II (insertion on the trapezium).

868 **Fig. 4** – The *m. flexor digitorum profundus* (FDP) in macaques (A, B) and gibbons (C, D): A) common
869 FDP configuration with three fused muscle bellies, one for digit 1 to 3 (FDP I-III), one for digit 4 (FDP
870 IV) and one for digit 5 (FDP V), the FDP is connected to the FDS with an additional muscle belly (*);
871 B) unusual FDP configuration with two muscle bellies (FDP I-III and FDP IV-V), the tendons to digits
872 2 and 3 show a tendon-lumbrical-tendon configuration in which the first two lumbricals form a single
873 unit with the FDP tendons instead of originating from these tendons; C) common FDP configuration
874 with two partially fused muscle bellies, one for digit 1 (FDP I) and one for digits 2 to 5 (FDP II-V); D)
875 unusual FDP configuration with two muscle bellies (FDP I-II and FDP III-V), the tendons to digits 2
876 and 3 partly originate from the FDS (*).

877 **Fig. 5** – Overview of the general organization of the thenar musculature in A) macaques and B) gibbons.
878 In gibbons, there is a clear distinction between the superficial and deep head of the FPB.

879 APB (*m. abductor pollicis brevis*), FPB (*m. flexor pollicis brevis*), FPBs (*m. flexor pollicis brevis*,
880 superficial head), FBPd (*m. flexor pollicis brevis*, deep head), OPP (*m. opponens pollicis*), ADPo (*m.*
881 *adductor pollicis*, oblique head), ADPt (*m. adductor pollicis*, transverse head).

882 **Fig. 6** – Two examples of a contrahens muscle: A) C5 of macaques, which originates from the palmar
883 base of MC3 (partially fused with IOD II and III) and inserts on the radial side of the MCP5 joint (joining
884 the extensor mechanism); B) C2 of gibbons, which has a varying origin and inserts onto the ulnar side
885 of the MCP2 joint.

886 **Supplementary material**

887 **Fig. S1** – Configuration of the *m. extensor digitorum communis* (EDC) in gibbons. The tendon to digit
888 2 splits off proximally to the wrist, the tendon to digit 5 splits off at the level of the wrist, and the tendons
889 to digits 3 and 4 split off at the dorsum of the hand and commonly interconnect with the tendons of
890 digits 2 and 5 (juncturae tendineum).

891 **Fig. S2** – The architecture of the *m. flexor digitorum superficialis* (FDS) in macaques consists of three
892 partially fused muscle bellies that are folded together; (1) a muscle running to digit 2 (FDS II), which
893 shows a distinct belly-tendon-belly-tendon configuration (cfr. bonobos), (2) a muscle belly with two
894 tendons inserting onto digit 3 and 4 (FDS III-IV), and (3) a muscle with one tendon inserting onto digit
895 5 (FDS V). In this example, the order of the tendons is II – V – IV – III when the FDS is folded open.

896 **Fig. S3** – Configuration of the *mm. intermetacarpales* (IM), *mm. flexores breves profundi* (FBP), *mm.*
897 *interossei palmares* (IOP), and *mm. interossei dorsales* (IOD). In macaques, the IM and FBP are fused
898 to form the IOD (similar to modern humans). In gibbons, some individuals display an intermediate
899 configuration where only one, two or three IOD are present while the other IM and FBP remain present
900 as separate muscles.